

Positive expansiveness versus network dimension in symbolic dynamical systems

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(1/21)

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We will generalize Shereshevsky's result to a much broader class of *symbolic dynamical systems*. These are systems like a CA, but having an 'irregular' network topology.

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In fact, we shall now see that *any* symbolic dynamical system can be seen as an automaton network.

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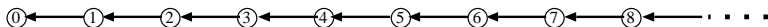
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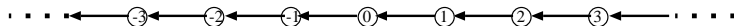
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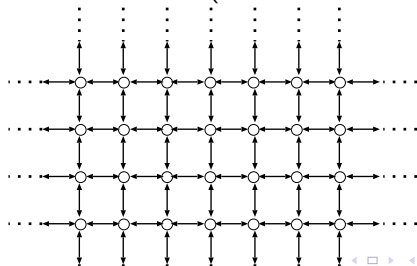
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Example. The network of CA on \mathbb{Z}^2 (von Neumann neighbourhood)



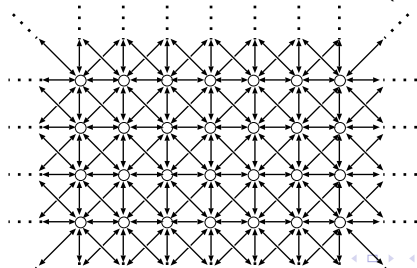
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Example. The network of cellular automaton on \mathbb{Z}^2 (Moore neighbourhood)



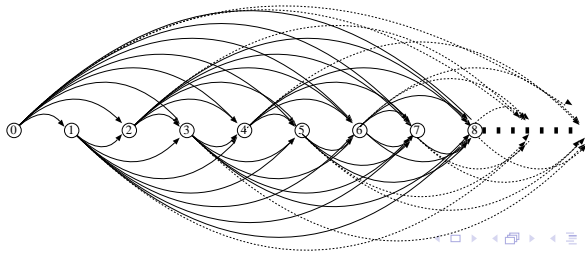
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Example. The network of an odometer.



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If $v \in V$, then $\mathbb{B}(v, r)$ is the set of all $w \in V$ such that there exists a directed path $w = v_1 \bullet \rightarrow v_2 \bullet \rightarrow \cdots \bullet \rightarrow v_s = v$ with $s \leq r$.

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Example. If $\Phi : \mathcal{A}^{\mathbb{Z}^D} \rightarrow \mathcal{A}^{\mathbb{Z}^D}$ is a CA, then $\dim(\mathbb{Z}^D, \bullet \rightarrow) = D$.

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Example. If $\Phi : \mathcal{A}^{\mathbb{Z}^D} \rightarrow \mathcal{A}^{\mathbb{Z}^D}$ is a CA, then $\dim(\mathbb{Z}^D, \bullet \rightarrow) = D$.

More generally, if \mathbb{G} is a group, and $\Phi : \mathcal{A}^{\mathbb{G}} \rightarrow \mathcal{A}^{\mathbb{G}}$ is a CA, then $\dim(\mathbb{G}, \bullet \rightarrow) =$ the dimension of the group \mathbb{G} .

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(b) Suppose $\mathbb{V} = \mathbb{Z}^D$ (with Cayley digraph), and $\mathcal{X} \subseteq \mathcal{A}^{\mathbb{Z}^D}$ is a D -dimensional subshift. Then $h(\mathcal{X})$ is the (D -dimensional) topological entropy of \mathcal{X} .

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Let $(\mathbb{V}, \bullet \rightarrow)$ be a digraph, and let $\mathcal{X} \subseteq \mathcal{A}^{\mathbb{V}}$ be a closed subset. Say that \mathcal{X} is *weakly independent* if there is some constant $\epsilon > 0$ such that, for any disjoint balls $\mathbb{B}_1, \dots, \mathbb{B}_N \subset \mathbb{V}$,

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A *subisometry* of $(\mathbb{V}, \bullet \rightarrow)$ is an injection $\tau : \mathbb{V} \rightarrow \mathbb{V}$ such that, for all $v, w \in \mathbb{V}$, we have $(v \bullet \rightarrow w) \iff (\tau(v) \bullet \rightarrow \tau(w))$.

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Example. For all $v \in \mathcal{A}$, let $\mathcal{A}_v \subseteq \mathcal{A}$ with $|\mathcal{A}_v| \geq 2$. Let $\mathcal{X} := \prod_{v \in \mathbb{V}} \mathcal{A}_v \subseteq \mathcal{A}^{\mathbb{V}}$; then $\underline{h}(\mathcal{X}) \geq 1$, and \mathcal{X} is weakly independent. In particular, the space $\mathcal{X} = \mathcal{A}^{\mathbb{V}}$ itself is weakly independent.

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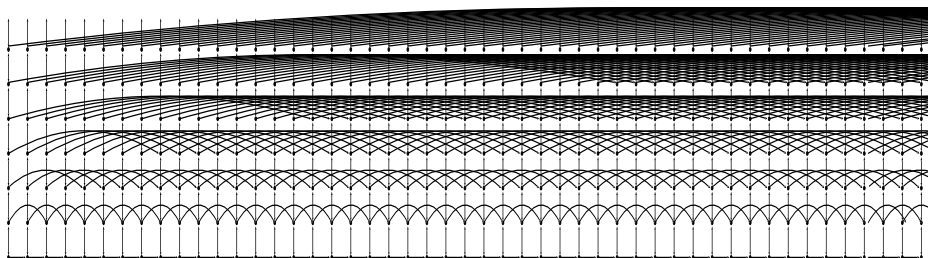
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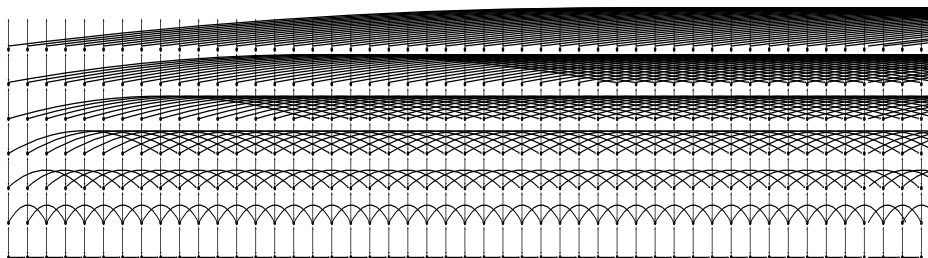
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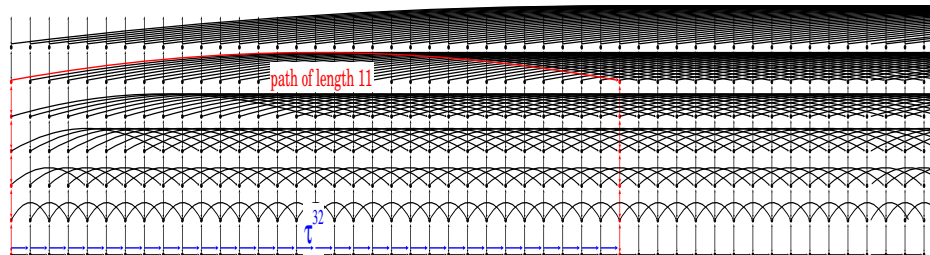


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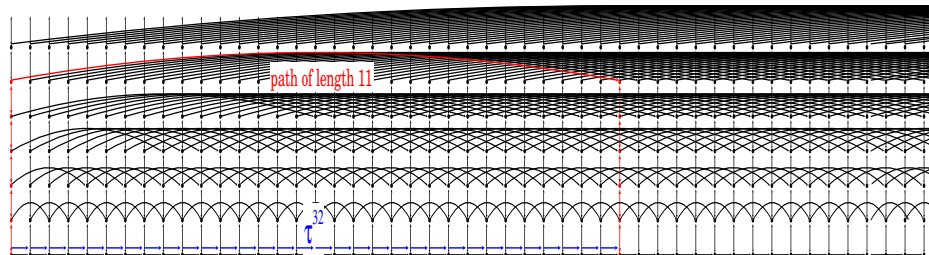


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Theorem 1. *Let $\Phi : \mathcal{A}^{\mathbb{V}} \rightarrow \mathcal{A}^{\mathbb{V}}$ be a continuous self-map with a **moving subsymmetry**.*

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In fact, Theorems 1 and 2 are both special cases of a more general result.

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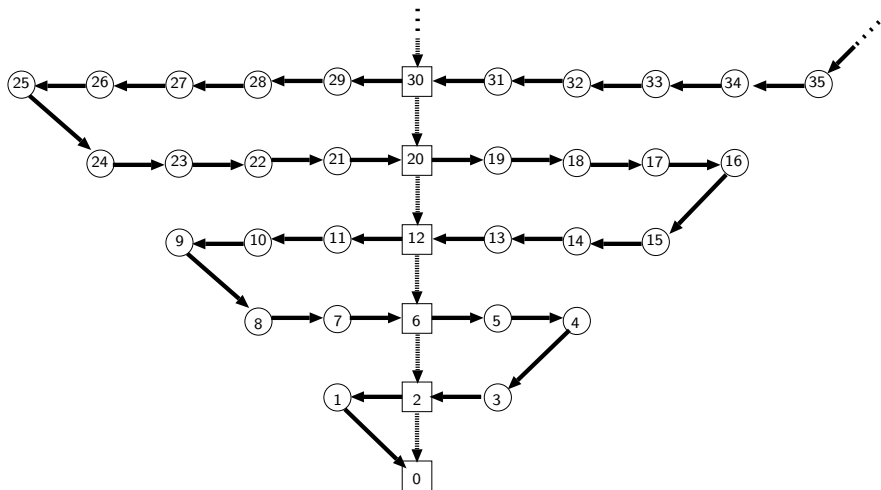
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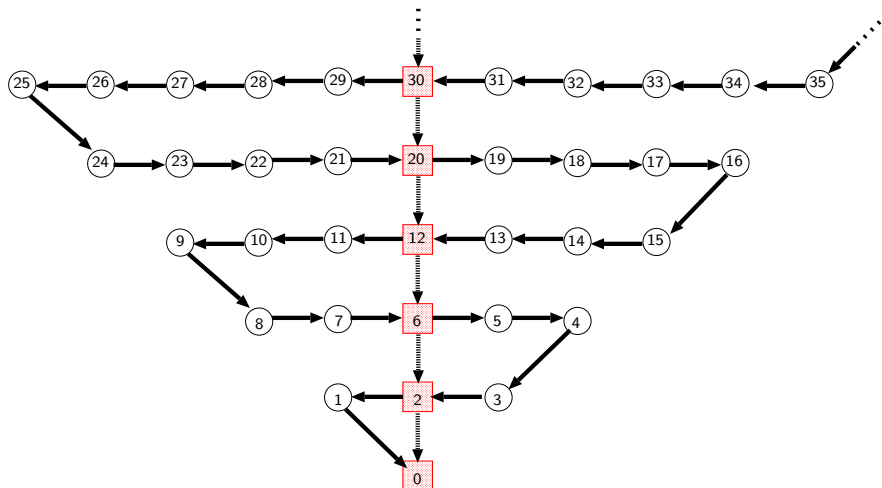
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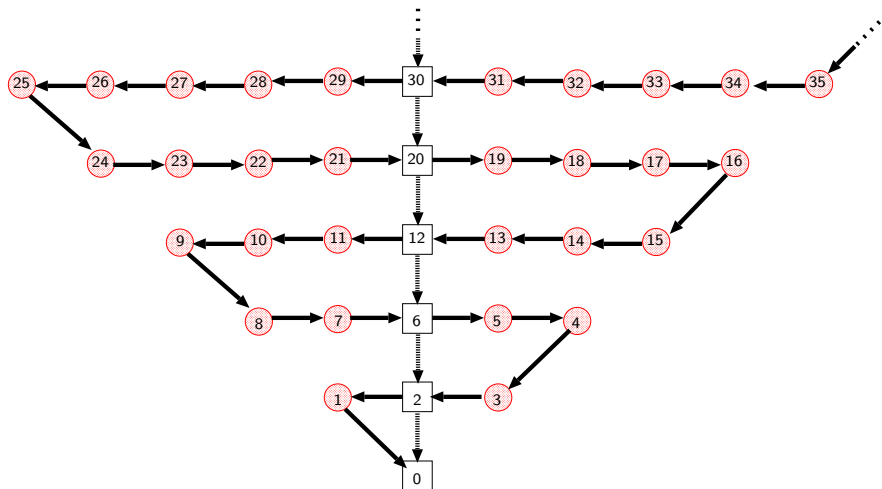
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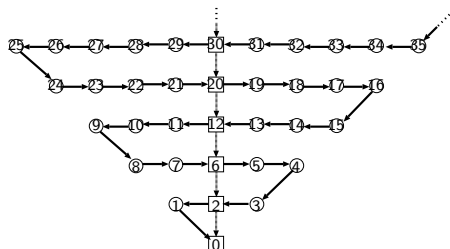
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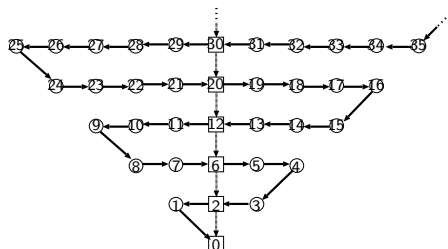
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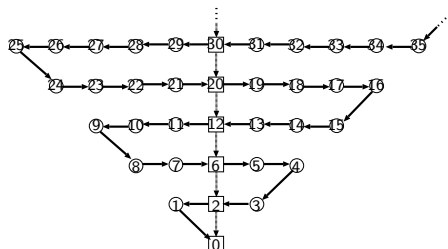


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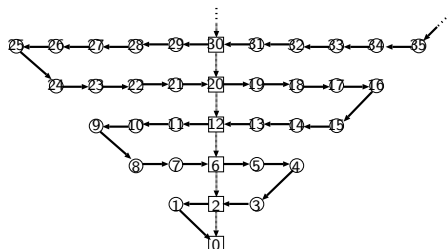
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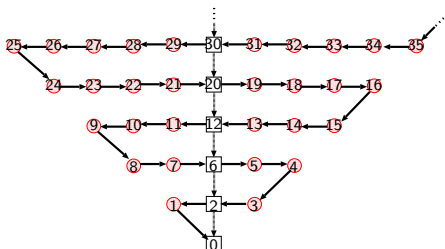
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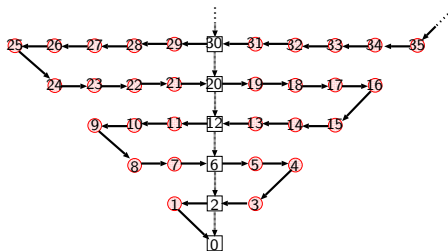
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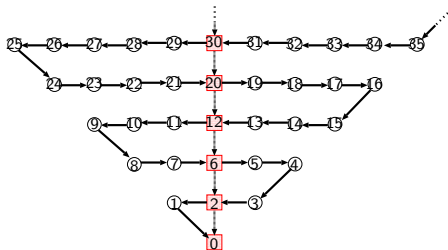
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For any $n \in \mathbb{V}_{\circ}$, define $\phi_n : \mathcal{X}_{n+1} \rightarrow \mathcal{X}_n$ by $\phi_n \begin{pmatrix} a_{n+1} \\ b_{n+1} \end{pmatrix} = \begin{pmatrix} a_{n+1} \\ 0 \end{pmatrix}$ (i.e. ϕ_n just copies the first coordinate of vertex $n+1$ into vertex n).



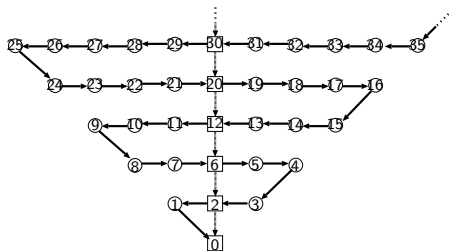
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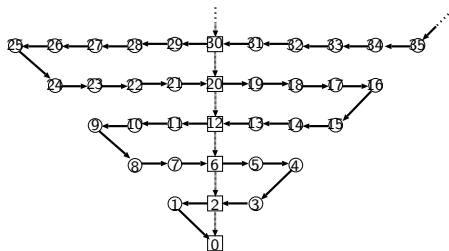


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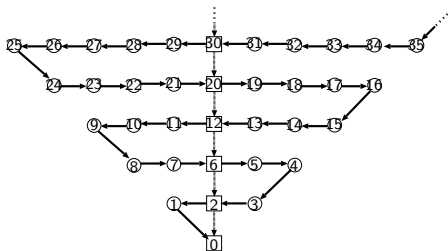


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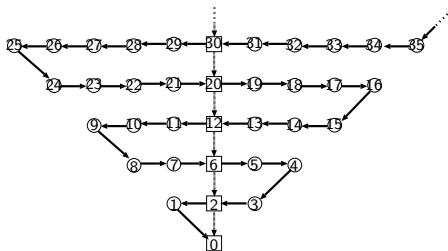


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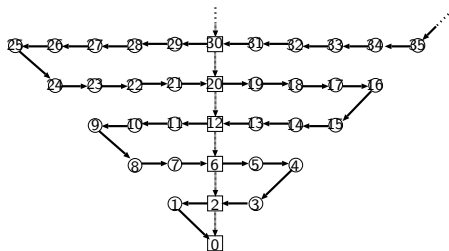
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Theorem. (a) $\underline{h}(\mathcal{X}) \geq 1$, and \mathcal{X} is weakly independent; and

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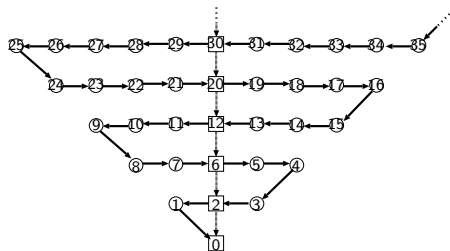
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Proof sketch.



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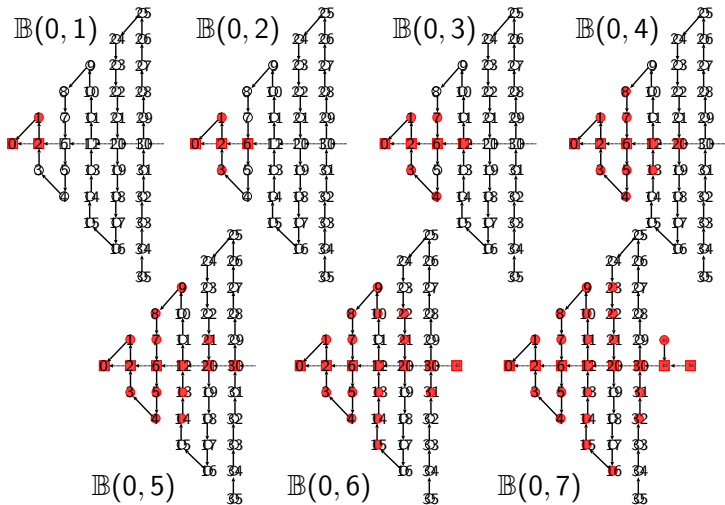
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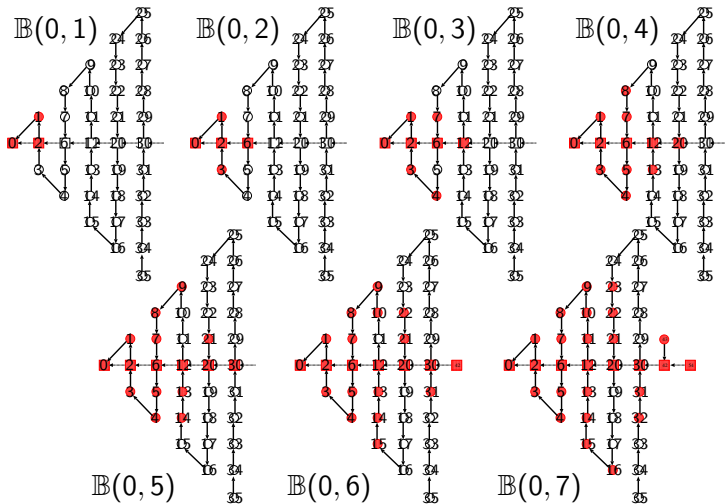
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Proof sketch. (a) is obvious from the definition of \mathcal{X} .



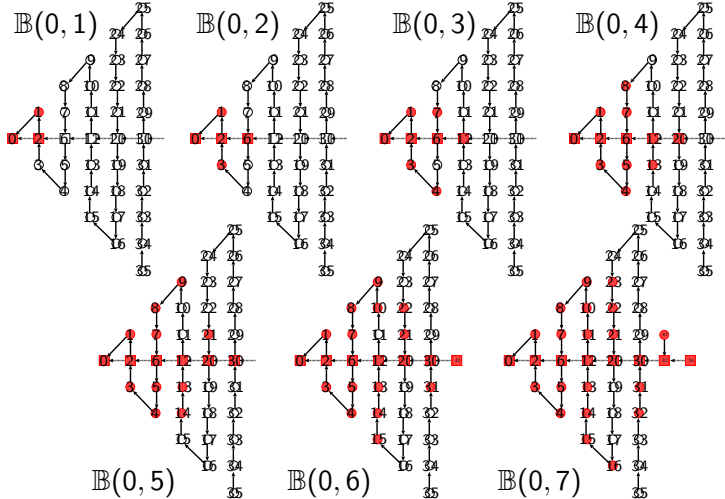
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Proof sketch. (b) (Case $v = 0$) The figure shows $\mathbb{B}(0, r)$ for $r = 1, 2, \dots, 7$.



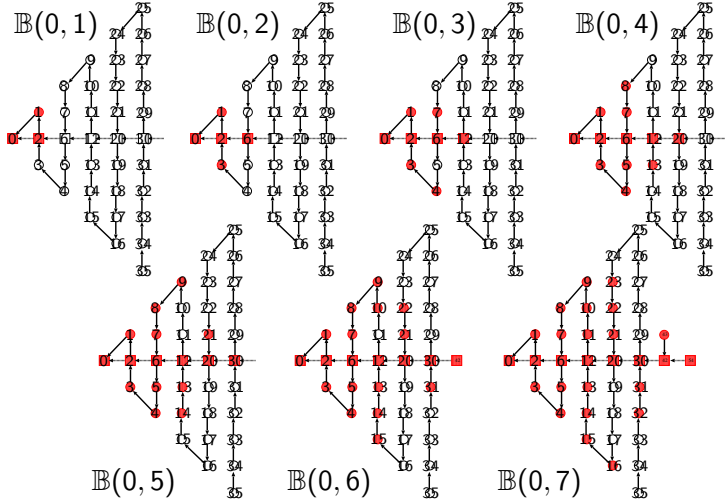
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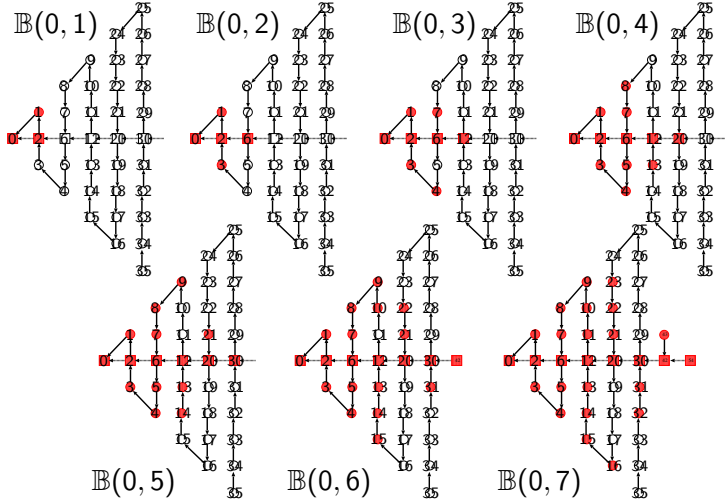
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Proof sketch. (c) Straightforward computation shows that the data $\mathbf{x}_0, \Phi(\mathbf{x})_0, \Phi^2(\mathbf{x})_0, \Phi^3(\mathbf{x})_0, \dots, \Phi^t(\mathbf{x})_0, \dots$ is sufficient to reconstruct \mathbf{x} , for any $\mathbf{x} \in \mathcal{X}$.

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Let (\mathcal{X}', d') be another metric space, and let $\Gamma : \mathcal{X} \rightarrow \mathcal{X}'$ be a continuous function. Say Γ is **Hölder** if there are constants $\eta, \lambda \in (0, \infty)$ such that, for all $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{X}$, we have $d'(\Gamma(\mathbf{x}_1), \Gamma(\mathbf{x}_2)) \leq \lambda \cdot d(\mathbf{x}_1, \mathbf{x}_2)^\eta$.

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Thank you.

These presentation slides are available at

<http://euclid.trentu.ca/pivato/Research/network.pdf>

For more information, see

Positive expansiveness versus network dimension in symbolic dynamical systems, to appear in *Theoretical Computer Science* (2011).

<http://arxiv.org/abs/0907.2935>

Introduction: Shereshevsky's result

Symbolic dynamical systems

- Definition & examples

- The network of a symbolic dynamical system

- Network Dimension

- Entropy

- Local independence and subisometries

- Subisometries and subsymmetries

- Moving subsymmetries

Main results

- Theorems 1 and 2

- Theorem 0

- Remarks

An expansive system of dimension two

- Construction

- Theorem statement

- Proof sketch

Conjugacy invariance

- Dimension is not a conjugacy invariant...

...but it is a Hölder conjugacy invariant

Conclusion