

# Crystallographic Defects in Cellular Automata

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## Cellular Automata

CA are the ‘discrete analog’ of partial differential equations. They are *spatially distributed* dynamical systems whose dynamics are driven by *local interactions* governed by *translationally equivariant* rules.

- **Space** is a lattice  $\mathbb{Z}^D$  (for  $D \geq 1$ ).
- The **local state** at each point in the lattice is an element of a finite alphabet, e.g.  $\mathcal{A} := \{0, 1\}$ .
- The **global state** is a  $\mathbb{Z}^D$ -indexed *configuration*  $\mathbf{a} : \mathbb{Z}^D \longrightarrow \mathcal{A}$ .  
The space of such configurations is denoted  $\mathcal{A}^{\mathbb{Z}^D}$ .  
A generic element of  $\mathcal{A}^{\mathbb{Z}^D}$  will be denoted by  $\mathbf{a} := [a_z]_{z \in \mathbb{Z}^D}$ .
- The evolution is governed by a map  $\Phi : \mathcal{A}^{\mathbb{Z}^D} \longrightarrow \mathcal{A}^{\mathbb{Z}^D}$ , computed by applying a ‘**local rule**’  $\phi$  at every point in space.

**Neighbourhood:**

$\mathbb{K} \subset \mathbb{Z}^D$  (finite set)

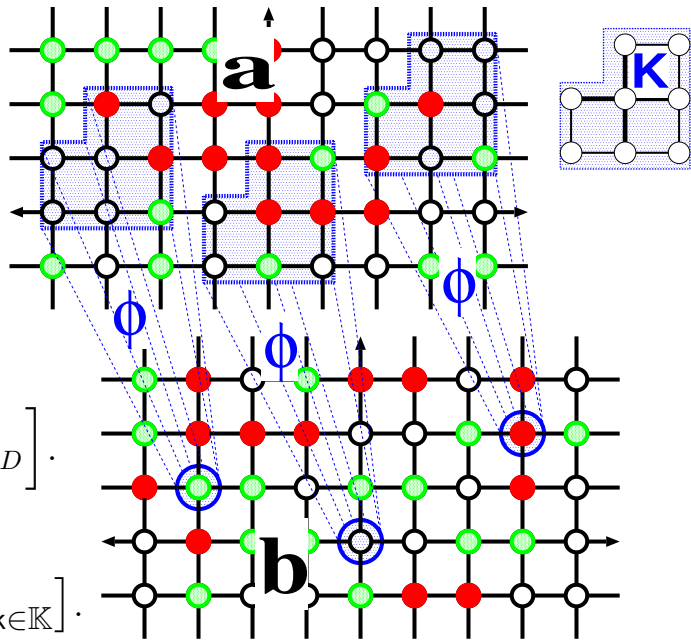
**Local rule:**  $\phi : \mathcal{A}^{\mathbb{K}} \longrightarrow \mathcal{A}$

Let  $\mathbf{a} \in \mathcal{A}^{\mathbb{Z}^D}$ ,  $\mathbf{a} := [a_z]_{z \in \mathbb{Z}^D}$ .

$\forall z \in \mathbb{Z}^D$ , let  $b_z := \phi[a_{(k+z)}]_{k \in \mathbb{K}}$ .

This defines new configuration  $\mathbf{b} := [b_z]_{z \in \mathbb{Z}^D}$ .

The CA **induced by**  $\phi$  is function  $\Phi : \mathcal{A}^{\mathbb{Z}^D} \rightrightarrows \mathcal{A}^{\mathbb{Z}^D}$  defined:  $\Phi(\mathbf{a}) := \mathbf{b}$ .

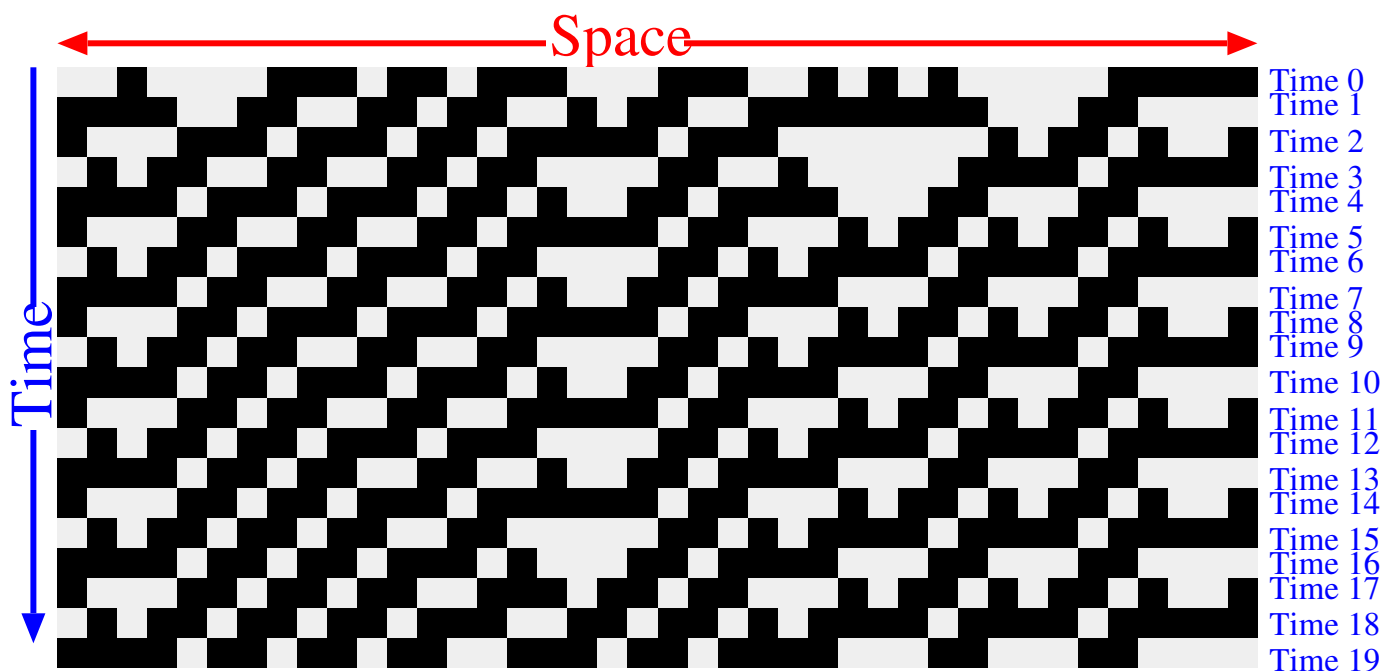


\_\_\_\_\_ **Example: Elementary Cellular Automaton #62** \_\_\_\_\_

Let  $D := 1$ ,  $\mathbb{K} := \{-1, 0, 1\}$ , and  $\mathcal{A} := \{0, 1\}$ .

Define  $\phi_{62} : \{0, 1\}^{\{-1,0,1\}} \longrightarrow \{0, 1\}$  by:

$$\begin{aligned} \phi_{62}(0, 0, 1) &= 1; & \phi_{62}(0, 0, 0) &= 0; \\ \phi_{62}(0, 1, 0) &= 1; & \phi_{62}(1, 1, 0) &= 0; \\ \phi_{62}(0, 1, 1) &= 1; & \phi_{62}(1, 1, 1) &= 0; \\ \phi_{62}(1, 0, 0) &= 1; \\ \phi_{62}(1, 0, 1) &= 1. \end{aligned}$$



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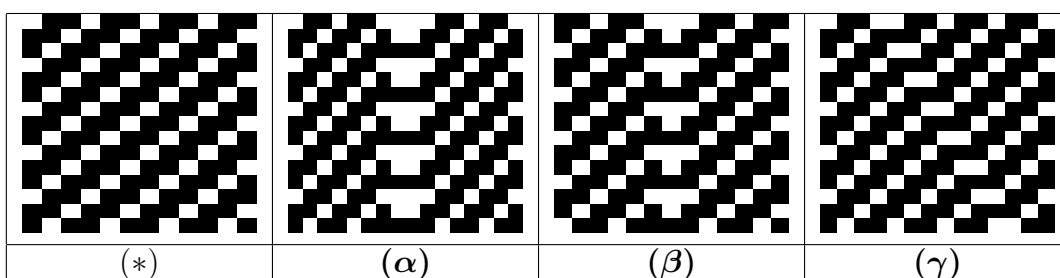
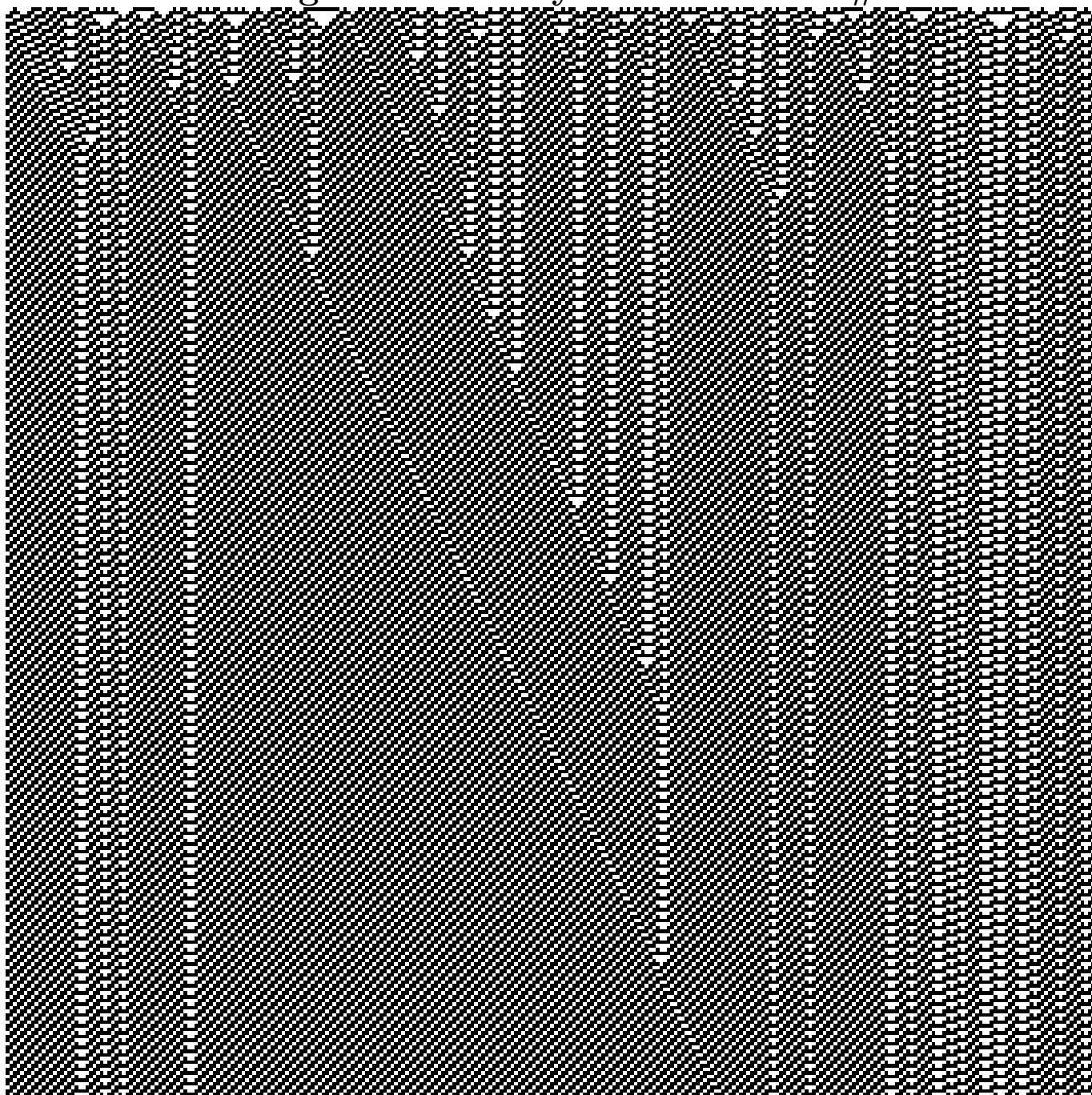
Such a nearest-neighbour CA on  $\{0, 1\}^{\mathbb{Z}}$  is called an **Elementary Cellular Automaton**. Each ECA is described by an 8-bit binary number (i.e. a number between 0 and 255) as follows:

If  $N = n_0 + 2n_1 + 2^2n_2 + 2^3n_3 + 2^4n_4 + 2^5n_5 + 2^6n_6 + 2^7n_7 \in [0..255]$

then  $\phi_N(a_0, a_1, a_2) := n_k$ , where  $k := a_0 + 2a_1 + 4a_2 \in [0..7]$ .

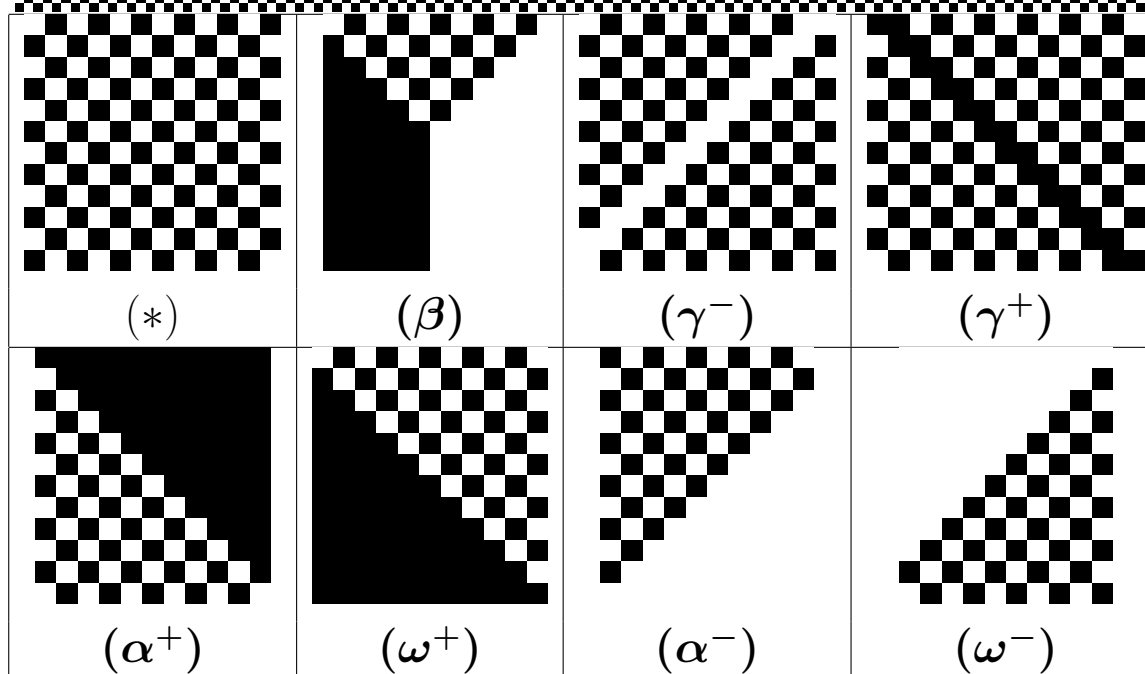
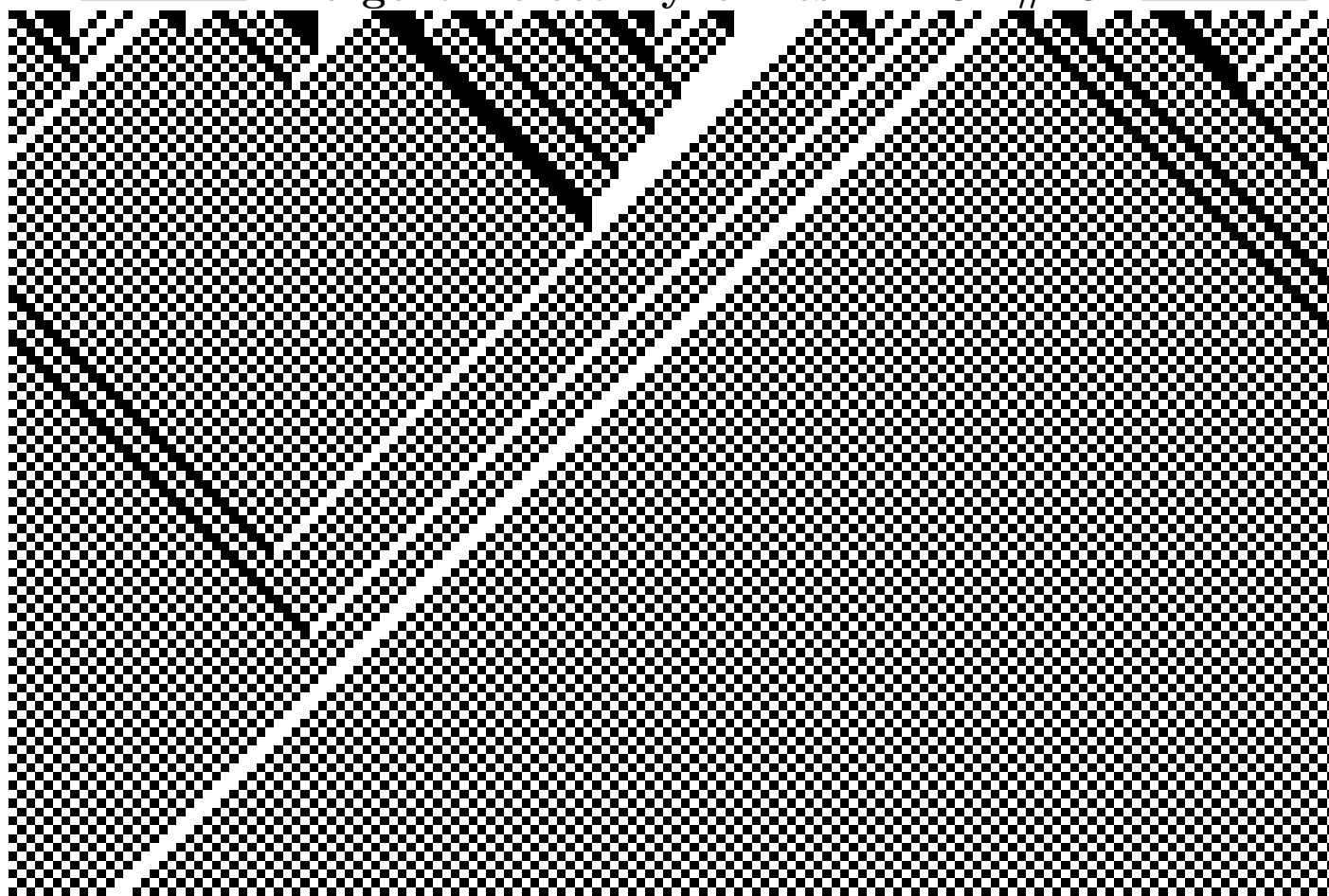
For example, the CA here is ECA#62, because  $2^1 + 2^2 + 2^3 + 2^4 + 2^5 = 62$ .

## Emergent Defect Dynamics in ECA#62



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# Emergent Defect Dynamics in ECA#184

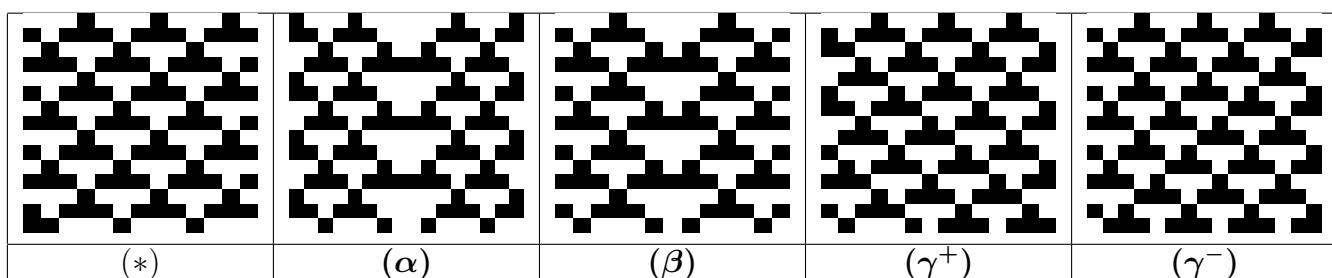
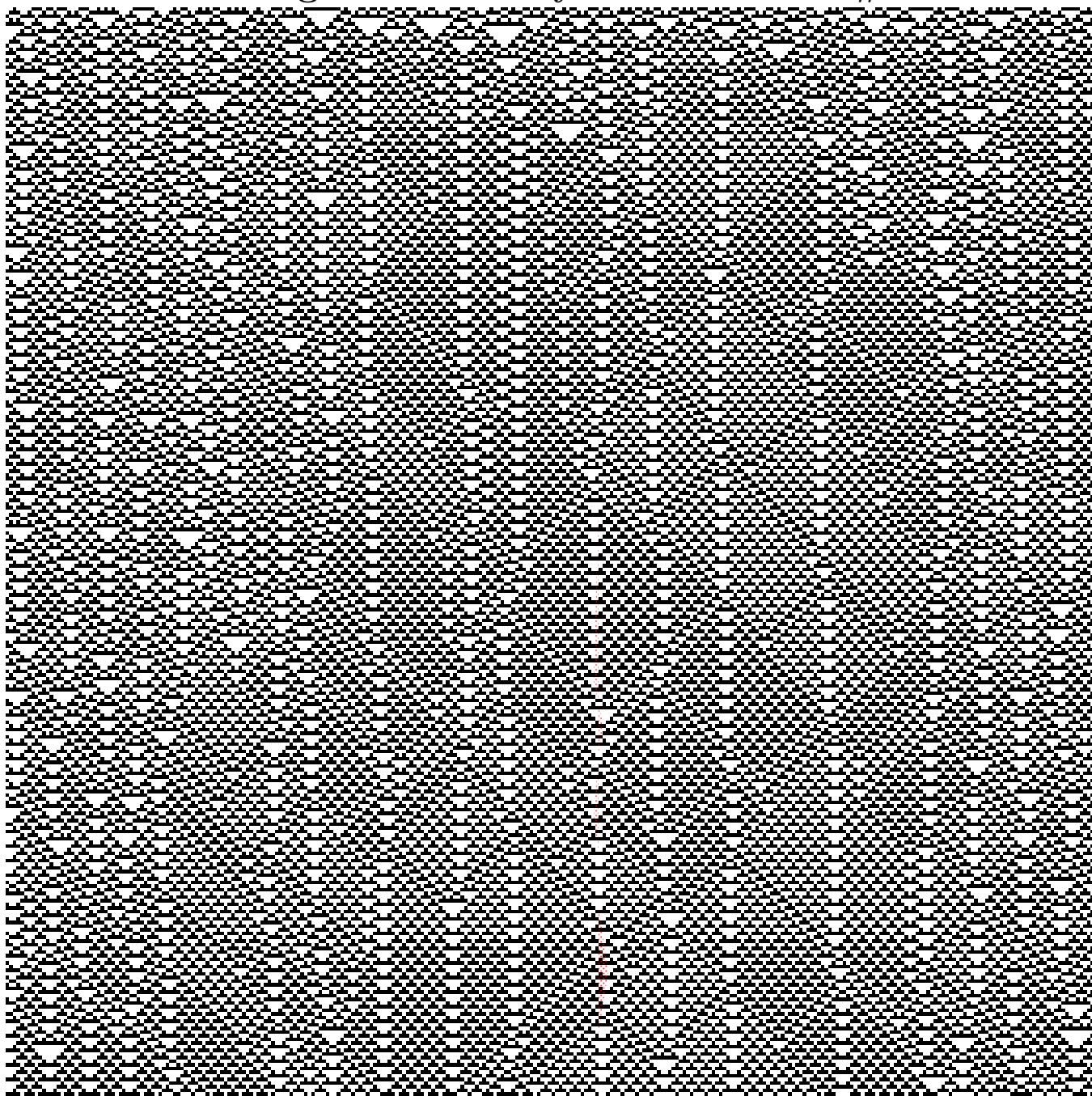


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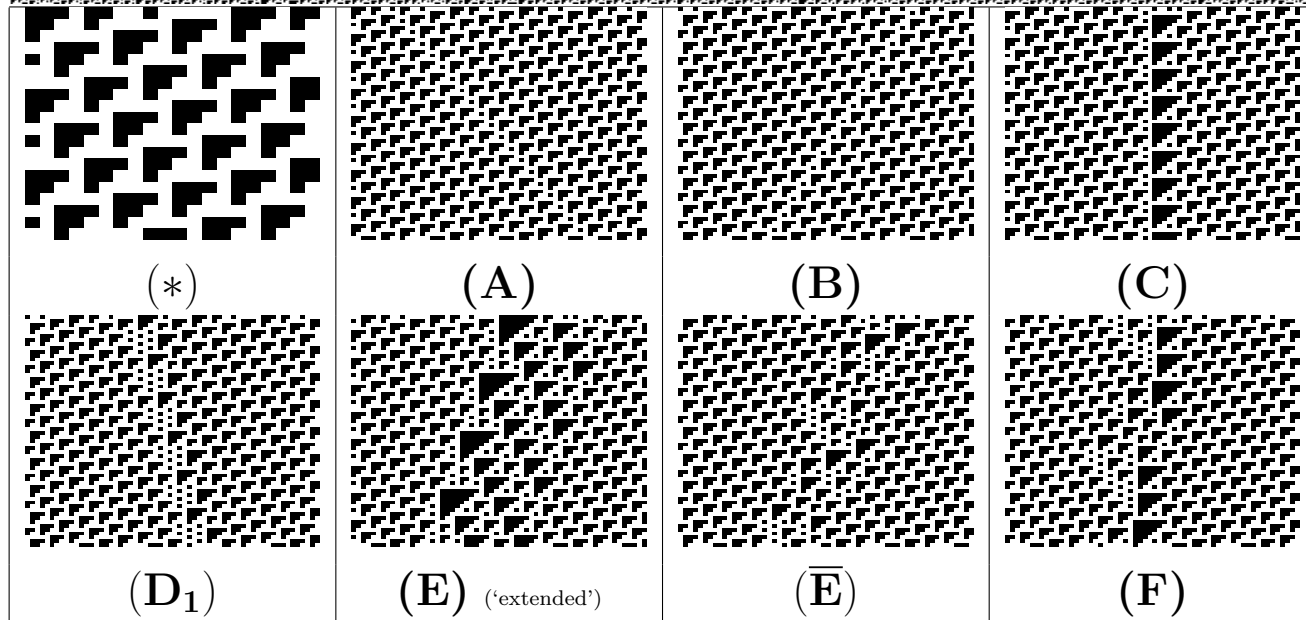
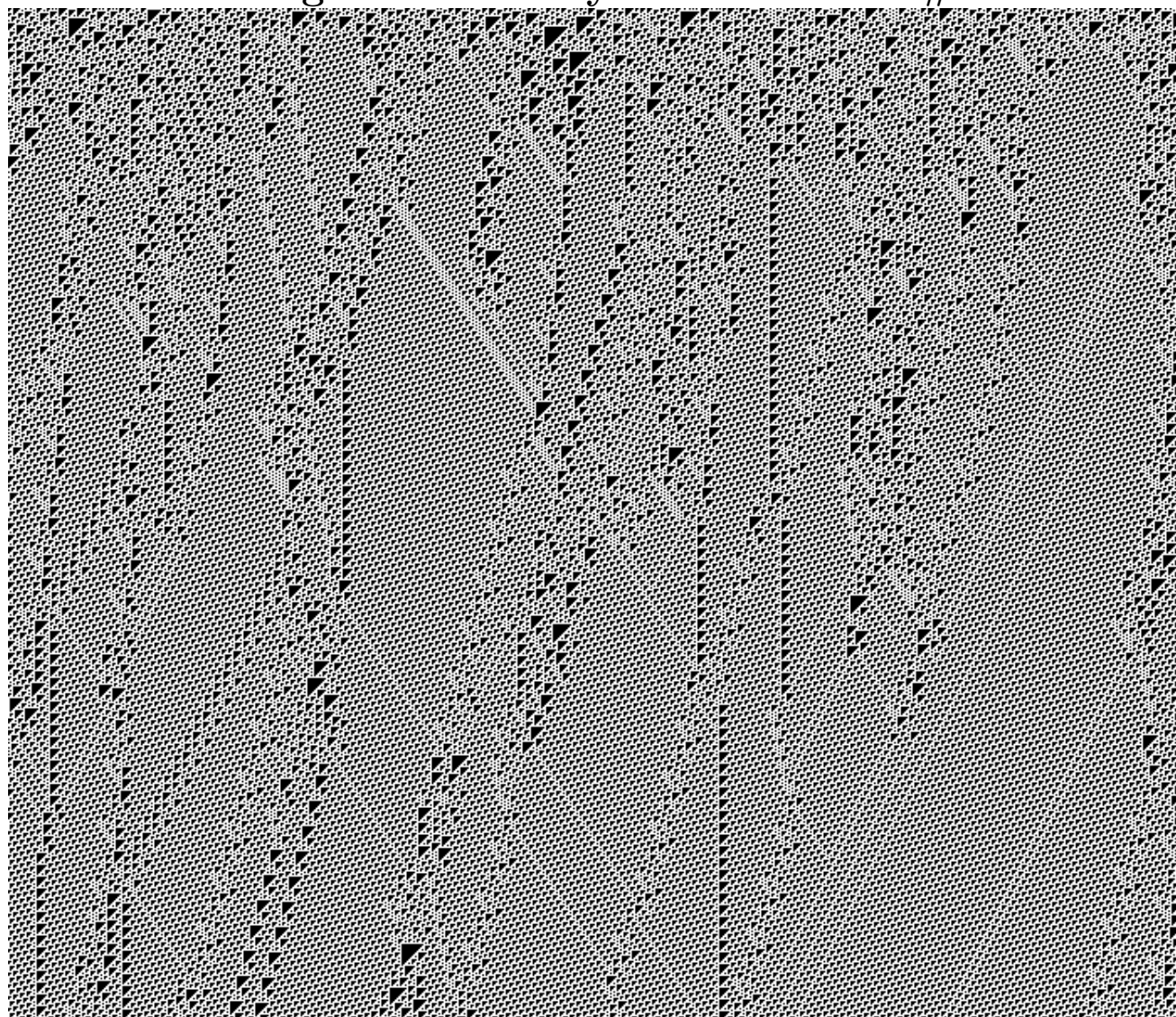
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## Emergent Defect Dynamics in ECA#54

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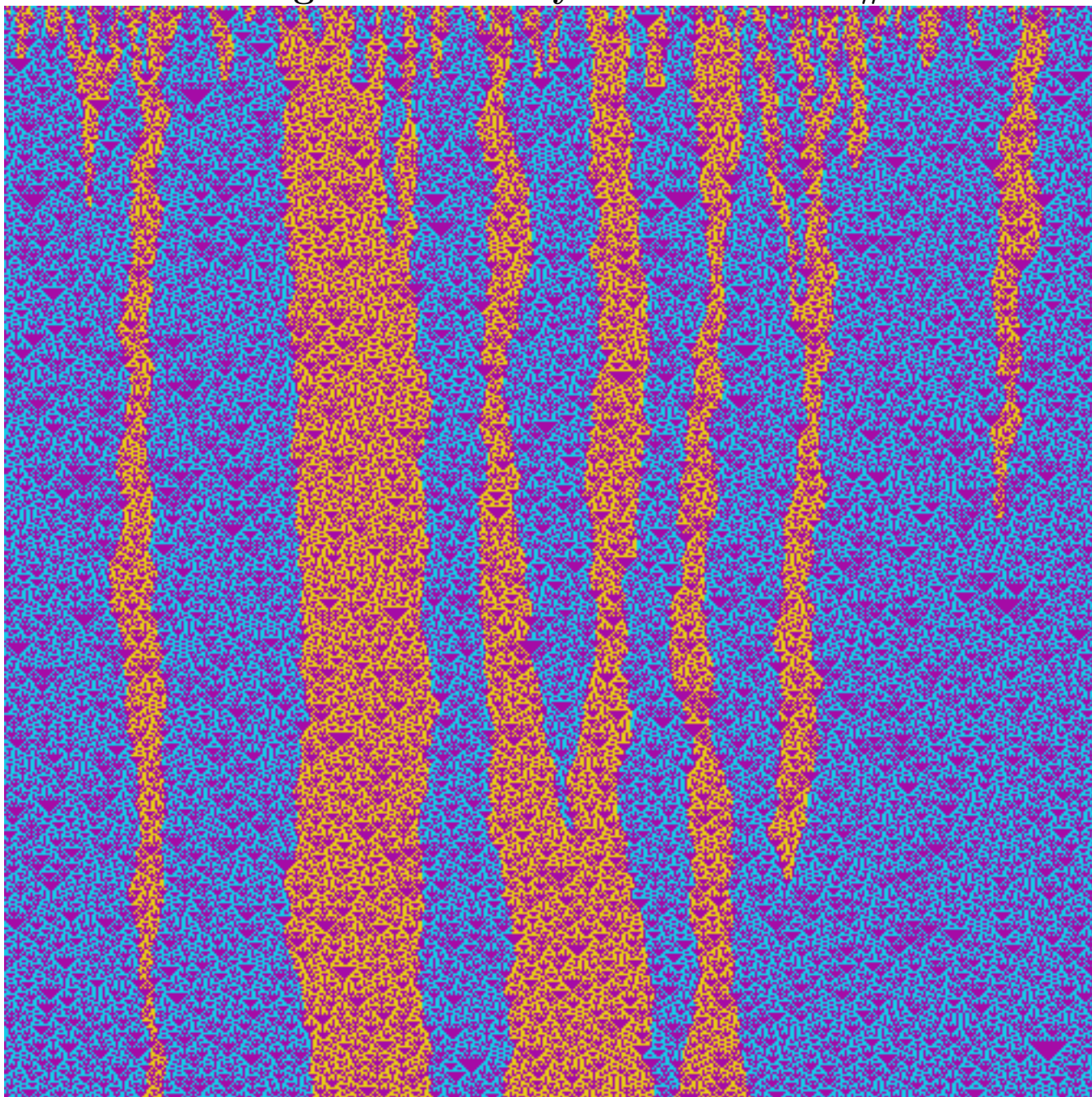


# Emergent Defect Dynamics in ECA#110



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## Emergent Defect Dynamics in ECA#18



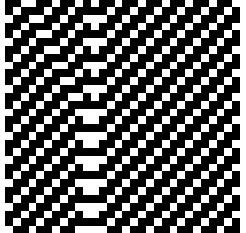
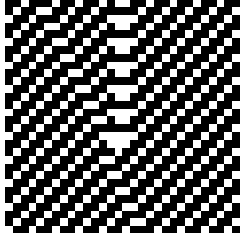
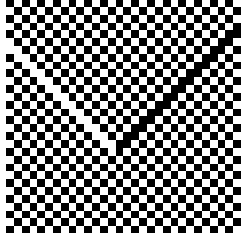
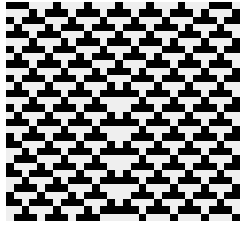
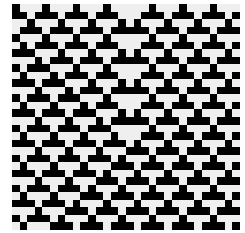
Invariant sofic subshift:  $\textcircled{1} \iff \textcircled{0} \iff \textcircled{0}$  (the *Odd Shift*).

Defects are ‘phase slips’:

[...  $\underbrace{00\ 01\ 00\ 01\ 01}_{\text{orange}}$   $\underbrace{00\ 00\ 00\ 00\ 00\ 00\ 00\ 00\ 00}_{\text{even \# of zeroes}}$   $\underbrace{10\ 00\ 10\ 00\ 00\ 10}_{\text{blue}}$  ...].



## Defect Particle ‘Chemistry’

ECA #62		ECA #184	ECA #54	
				
$\gamma + \beta \rightarrow \alpha$	$\gamma + \alpha \rightarrow \gamma$	$\gamma^+ + \gamma^- \rightarrow \emptyset$	$\gamma^+ + \gamma^- \rightarrow \beta$	$\gamma^+ + \beta \rightarrow \gamma^-$

**Empirical Work:** • P. Grassberger [1983, 1984].

- Steven Wolfram [1983-2005]. (Mainly ECA #110).
- S. Wolfram and Doug Lind [1986]. (Classified defects of ECA #110).
- N. Boccara, J. Naser, M. Rogers [1991]. (ECAs 18, 54, 62, 184).
- James Crutchfield and James Hanson’s ‘Computational Mechanics’ [1992-2001]. (Also Cosma Shalizi, Wim Hordijk, Melanie Mitchell).
- Harold V. McIntosh [1999, 2000].

**Theoretical Work:** • Doug Lind [1984] conjectured:

(i) *Defects in ECA#18 perform random walks.*

(ii) *Defect density decays to zero through annihilations. Thus, ECA#18 converges ‘in measure’ to the ‘odd’ sofic shift  $\textcircled{1} \rightleftharpoons \textcircled{0} \rightleftharpoons \textcircled{0}$ .*

- Kari Eloranta [1993-1995] proved Lind’s conjecture (i); studied quasirandom defect motion in ‘partially permutive’ CA.

- Petr Kůrka and Alejandro Maass [2000, 2002] studied CA convergence to limit sets through ‘defect annihilation’. Kůrka [2003] proved Lind’s conjecture (ii).

- S. Wolfram and Matthew Cook [2002, 2004]: ECA #110 *is computationally universal* (used ‘defect physics’ to engineer universal computer).

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## Questions:

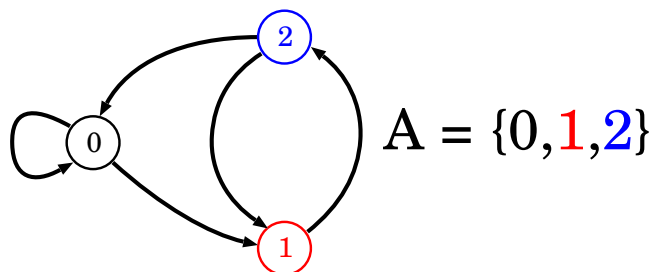
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- What is a ‘defect’? What is a ‘regular background pattern’?
- Is there an ‘algebraic structure’ governing defect ‘chemistry’?
- Why do defects ‘persist’ over time instead of disappearing? Is this related to aforementioned ‘algebraic structure’?
- What is the ‘kinematics’ by which defects propagate through space?

A **subshift** is a subset  $\mathfrak{A} \subseteq \mathcal{A}^{\mathbb{Z}^D}$  of configurations, defined by stipulating which ‘local patterns’ may or may not occur around each point in  $\mathbb{Z}^D$ .

### Topological Markov Shifts:

Let  $D = 1$ . Let  $\mathcal{A} :=$  the vertices of a directed graph. A sequence  $\mathbf{a} \in \mathcal{A}^{\mathbb{Z}}$  is admissible iff it describes an infinite directed path through the graph.



$$\mathbf{A} = \{0, 1, 2\}$$

$$\mathbf{a} = [\dots 0, 1, 2, 1, 2, 0, 0, 0, 0, 1, 2, 0, 0, 1, 2, 1, 2, 1, 2, 0, 0, \dots]$$

**Sofic Shift:** Let  $D = 1$ . Like a topological Markov shift, but now several vertices might be labelled with the same letter in  $\mathcal{A}$ .

**Example:**  $\textcircled{1} \iff \textcircled{0} \iff \textcircled{0}$  (the *Odd Shift* from ECA#18).

$[\dots 00\ 01\ 00\ 01\ 01\ 00\ 00\ 00\ 00\ 01\ 00\ 00\ 00\ 01\ 0100\ 01\ 00\ 00\ 01\dots]$ .

Let  $\mathfrak{A}_{(r)} :=$  set of  $\mathfrak{A}$ -admissible ‘local patterns’ seen in  $\mathbb{B}(r) := [-r\dots r]^D$

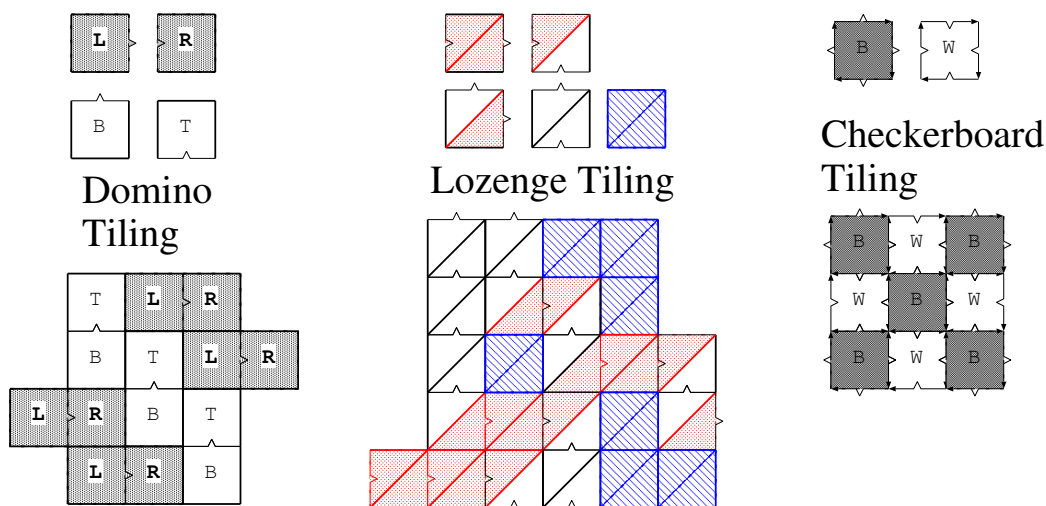
A configuration  $\mathbf{a} \in \mathcal{A}^{\mathbb{Z}^D}$  is **defective** if there are points in  $\mathbb{Z}^D$  where the local pattern in  $\mathbf{a}$  is *inadmissible* —i.e. *not* in  $\mathfrak{A}_{(r)}$ . These points are called **defects**. Let  $\mathbb{D}(\mathbf{a}) \subset \mathbb{Z}^D$  be the set of these ‘defect points’ in  $\mathbf{a}$ .

Let  $\Phi : \mathcal{A}^{\mathbb{Z}^D} \longrightarrow \mathcal{A}^{\mathbb{Z}^D}$  be a CA. We say  $\mathfrak{A}$  is  **$\Phi$ -invariant** if  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ . Empirically, if  $\mathbf{a} \in \mathcal{A}^{\mathbb{Z}^D}$  has defects, then so does  $\Phi(\mathbf{a})$ .

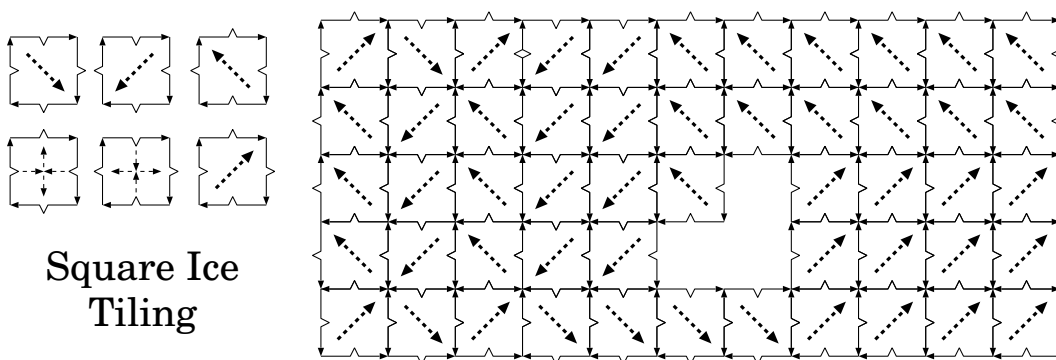
Let  $\tilde{\mathfrak{A}} := \{\text{configurations with ‘finite’ defects}\}$ . Then  $\Phi(\tilde{\mathfrak{A}}) \subseteq \tilde{\mathfrak{A}}$ .

## Wang tilings

Let  $D = 2$ . Let  $\mathcal{A} :=$  set of square tiles, with notches on their edges which dictate how the tiles can be assembled. These **edge-matching constraints** determine a subshift  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}^2}$ , called a **Wang tiling**.



A defect corresponds to a ‘hole’ in the tiling:



**Remark:** Wang tilings and topological Markov shifts are **subshifts of finite type (SFTs)**, meaning they are determined entirely by ‘local constraints’. Sofic shifts are a broader class, which may have ‘nonlocal’ constraints. (Defect theory more complicated, but still possible.)

**Generalization to  $\mathbb{Z}^D$ :** Idea:  $\mathcal{A} =$  set of ‘atoms’, with certain admissible ‘chemical bonds’ between them. Thus, an admissible configuration corresponds to a ‘crystalline solid’. Defects are ‘flaws’ in crystal structure.

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**Questions:**

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- *Is there an ‘algebraic structure’ governing defect ‘chemistry’?*
- *Why do defects ‘persist’ over time instead of disappearing? Is this related to aforementioned ‘algebraic structure’?*
- *What is the ‘kinematics’ by which defects propagate through space?*

**Formalism:** Fix  $D \in \mathbb{N}$ . For any  $r > 0$ , let  $\mathbb{B}(r) := [-r\dots r]^D \subset \mathbb{Z}^D$ . Fix  $r > 0$ . Let  $\mathfrak{A}_{(r)} \subset \mathcal{A}^{\mathbb{B}(r)}$  be a set of **admissible  $r$ -blocks**.

The **subshift of finite type (SFT)** determined by  $\mathfrak{A}_{(r)}$  is the set

$$\mathfrak{A} := \left\{ \mathbf{a} \in \mathcal{A}^{\mathbb{Z}^D} ; \mathbf{a}_{\mathbf{z}+\mathbb{B}(r)} \in \mathfrak{A}_{(r)}, \forall \mathbf{z} \in \mathbb{Z}^D \right\}$$

For any  $R > 0$ , let  $\mathfrak{A}_{(R)}$  be the projection of  $\mathfrak{A}$  to  $\mathcal{A}^{\mathbb{B}(R)}$ .

If  $\mathbf{a} \in \mathcal{A}^{\mathbb{Z}^D}$  and  $\mathbf{z} \in \mathbb{Z}^D$ , then  $\mathbf{a}$  is **defective** at  $\mathbf{z}$  if  $\mathbf{a}_{\mathbf{z}+\mathbb{B}(r)} \notin \mathfrak{A}_{(r)}$ . The **defect set** of  $\mathbf{a}$  is the set  $\mathbb{D}(\mathbf{a})$  of all such  $\mathbf{z}$ .

Let  $\Phi : \mathcal{A}^{\mathbb{Z}^D} \longrightarrow \mathcal{A}^{\mathbb{Z}^D}$  be a CA. We say  $\mathfrak{A}$  is  **$\Phi$ -invariant** if  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ .

Empirically, if  $\mathbf{a} \in \mathcal{A}^{\mathbb{Z}^D}$  has defects, then so does  $\Phi(\mathbf{a})$ .

We say  $\mathbf{a}$  is **finitely defective** if,  $\forall R > 0$ ,  $\exists \mathbf{z} \in \mathbb{Z}^D$  with  $\mathbf{a}_{\mathbb{B}(\mathbf{z}, R)} \in \mathfrak{A}_{(R)}$ .

**Idea:**  $\mathbf{a}$  may have infinitely large defects, but  $\mathbf{a}$  also has infinitely large ‘nondefective’ regions. Let  $\tilde{\mathfrak{A}} := \{\text{finitely defective } \mathbf{a} \in \mathcal{A}^{\mathbb{Z}^D}\}$ . ( $\mathfrak{A} \subset \tilde{\mathfrak{A}}$ )

**Lemma:** *If  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ , then  $\Phi(\tilde{\mathfrak{A}}) \subseteq \tilde{\mathfrak{A}}$ .*

*Also, if  $\mathbf{a} \in \tilde{\mathfrak{A}}$  and  $\mathbf{a}' = \Phi(\mathbf{a})$ , then the any defects in  $\mathbf{a}'$  are ‘close’ to corresponding defects in  $\mathbf{a}$ .* □

**The Fine Print:** To extend the definition of ‘defect’ to other subshifts (not of finite type), it is necessary to introduce a ‘detection range’  $R > 0$ . We must then talk about ‘defects of range  $R$ ’.

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## Domain Boundaries

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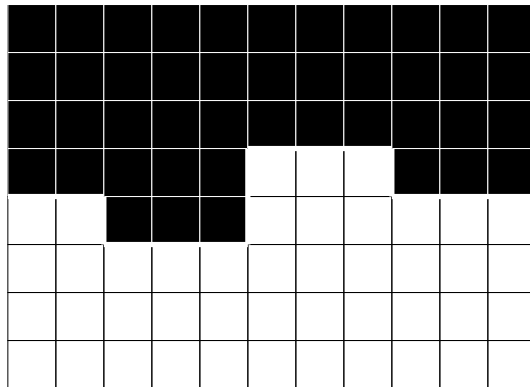
Let  $\mathbb{G}(\mathbf{a}) := \{\mathbf{z} \in \mathbb{Z}^D ; \mathbf{a} \text{ is not defective at } \mathbf{z}\}$ . Let  $\mathbf{G}(\mathbf{a}) \subset \mathbb{R}^D$  be the union of all unit cubes whose corner vertices are all in  $\mathbb{G}(\mathbf{a})$ .

The defect in  $\mathbf{a}$  is a **domain boundary**\* if  $\mathbf{G}(\mathbf{a})$  is disconnected.

**Examples:** (a) If  $D = 1$ , then all defects are domain boundaries.

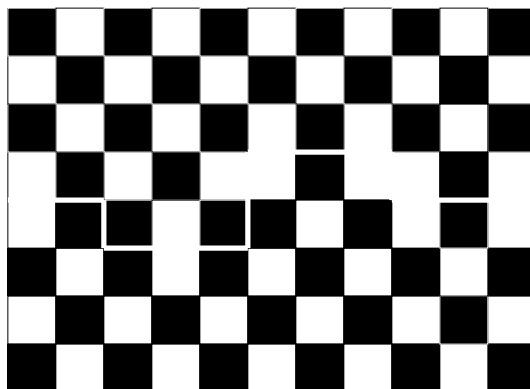
(b) (*Monochromatic*) Let  $\mathcal{A} := \{\blacksquare, \square\}$ . Let  $\mathfrak{M}_\circ \subset \mathcal{A}^{\mathbb{Z}^2}$  be SFT such that no  $\blacksquare$  can be adjacent to a  $\square$ .

The following configuration has a domain boundary defect:



(c) (*Checkerboard*) Let  $\mathcal{A} := \{\blacksquare, \square\}$ . Let  $\mathfrak{C}_\mathfrak{h} \subset \mathcal{A}^{\mathbb{Z}^2}$  be SFT where no  $\blacksquare$  can be adjacent to a  $\blacksquare$ , and no  $\square$  can be adjacent to a  $\square$ .

The following configuration has a domain boundary defect:



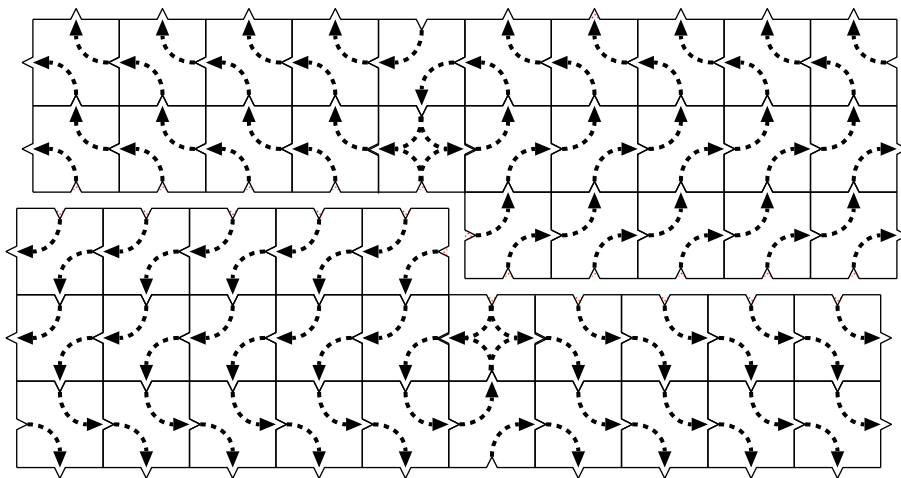
(\*) If we considering a defect of range  $R > 0$ , then technically this is a *domain boundary of range*  $R$ .

Domain Boundaries

(d) (*Square ice*) Let  $\mathcal{I} := \left\{ \begin{array}{c} \text{[Square with 3 arrows on one edge]} \\ \text{[Square with 3 arrows on another edge]} \\ \text{[Square with 3 arrows on a third edge]} \\ \text{[Square with 3 arrows on a fourth edge]} \\ \text{[Square with 4 arrows]} \\ \text{[Square with 4 arrows]} \end{array} \right\}$ .

Let  $\mathfrak{I}_{ce} \subset \mathcal{I}^{\mathbb{Z}^2}$  be the SFT defined by obvious edge-matching conditions.

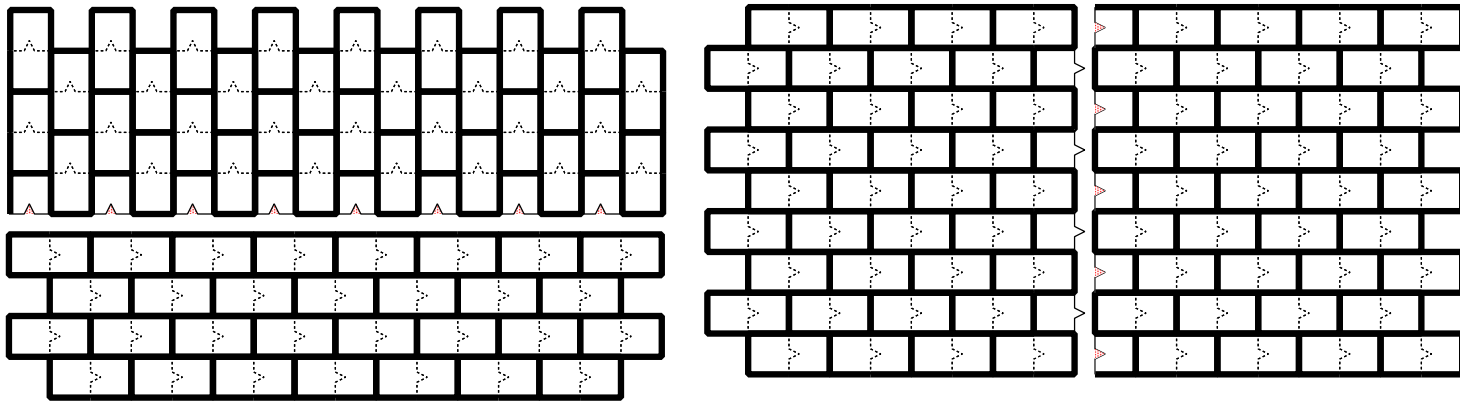
The following configuration has a domain boundary defect:



(e) (*Domino Tiling*) Let  $\mathcal{D} := \left\{ \begin{array}{c} \text{[Square with protrusion on right]} \\ \text{[Square with indentation on left]} \\ \text{[Square with protrusion on top]} \\ \text{[Square with indentation on bottom]} \end{array} \right\}$ .

Let  $\mathfrak{D}_{om} \subset \mathcal{D}^{\mathbb{Z}^2}$  be the SFT defined by obvious edge-matching conditions.

The following configurations have domain boundary defects:

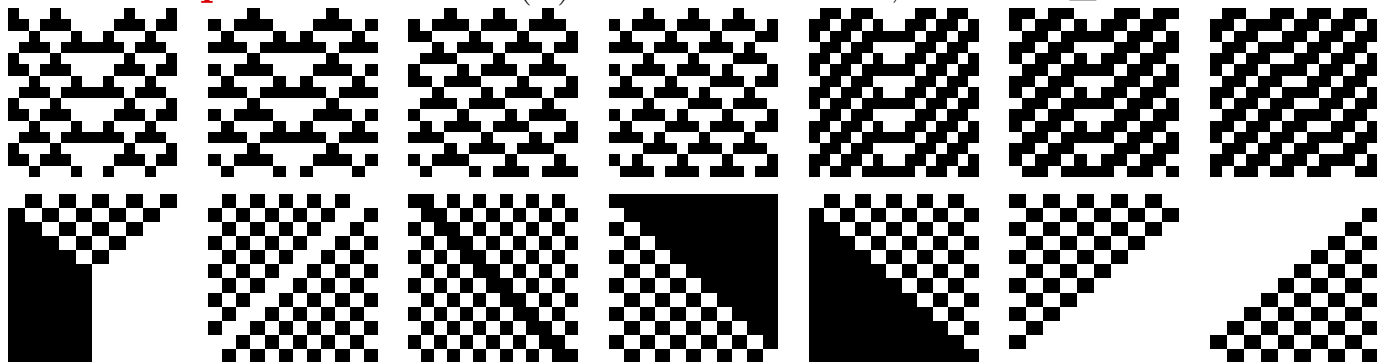


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## Persistent Defects

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Let  $\Phi : \mathcal{A}^{\mathbb{Z}^D} \longrightarrow \mathcal{A}^{\mathbb{Z}^D}$  be a CA, with  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ . Let  $\mathbf{a} \in \tilde{\mathfrak{A}}$ . The defect in  $\mathbf{a}$  is  **$\Phi$ -persistent** if  $\Phi^t(\mathbf{a})$  also has a defect, for all  $t \geq 0$ .



**Question:** These defects seem to be persistent. Are they? Why?

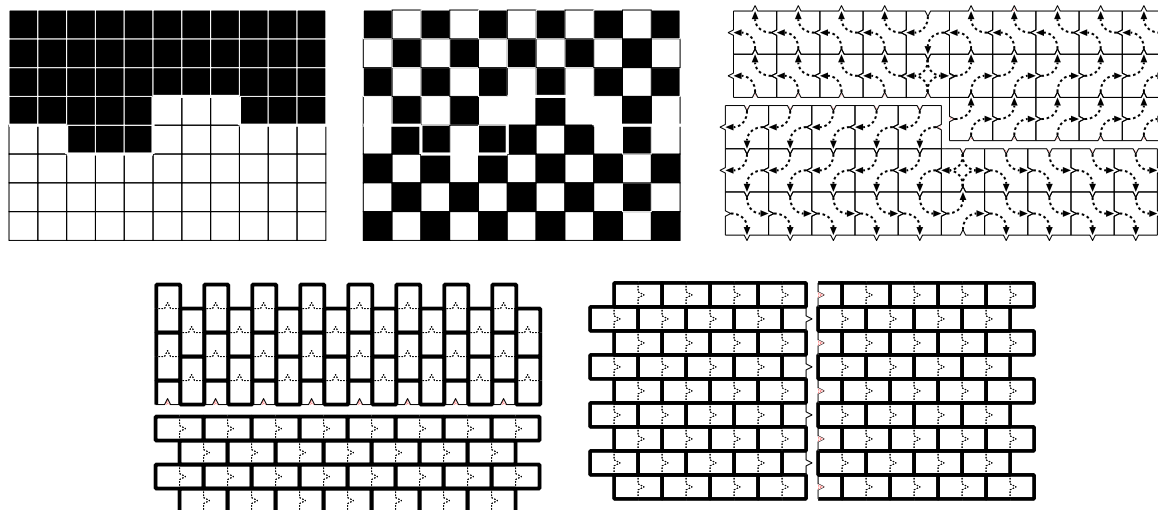
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## Essential Defects

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A defect is **essential** if it can't be removed through a local change. That is,  $\forall R > 0$ , if  $\mathbf{a}' \in \mathcal{A}^{\mathbb{Z}^D}$  is obtained by modifying  $\mathbf{a}$  in an  $R$ -neighbourhood of defect, then  $\mathbf{a}'$  is also defective.

**Proposition:** *If  $\Phi : \mathfrak{A} \longrightarrow \mathfrak{A}$  is bijective (e.g. if  $\mathfrak{A} \subseteq \text{Fix}[\Phi]$  or  $\mathfrak{A} \subseteq \text{Fix}[\Phi^p]$  or  $\mathfrak{A} \subseteq \text{Fix}[\Phi^p \circ \sigma^q]$ ), then any essential defect is  $\Phi$ -persistent.  $\square$*



**Question:** These defects seem essential. Are they? Why?

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**Interfaces** (intuitive version)
 

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Suppose  $\mathfrak{A}_{(r)}$  breaks into two (or more) disjoint subsets  $\mathfrak{A}_{(r)} = \mathfrak{B}_{(r)} \sqcup \mathfrak{C}_{(r)}$  (called  $(F, \sigma)$ -transitive components), such that, for each  $\mathbf{a} \in \mathfrak{A}$ ,

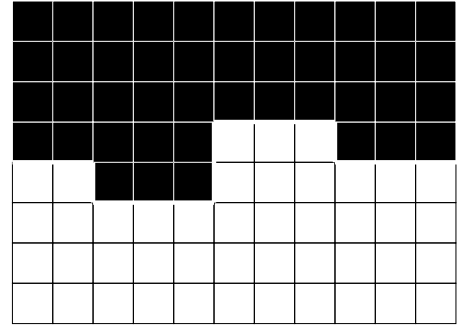
*either*  $\mathbf{a}$  is totally covered by  $\mathfrak{B}_{(r)}$ -blocks,

*or*  $\mathbf{a}$  is totally covered by  $\mathfrak{C}_{(r)}$ -blocks,

*but*  $\mathbf{a}$  cannot have a mixture of  $\mathfrak{B}_{(r)}$ -blocks and  $\mathfrak{C}_{(r)}$ -blocks.

An **interface** is a domain boundary between a  $\mathfrak{B}_{(r)}$ -covered region and a  $\mathfrak{C}_{(r)}$ -covered region. Such a boundary is necessarily an essential defect.

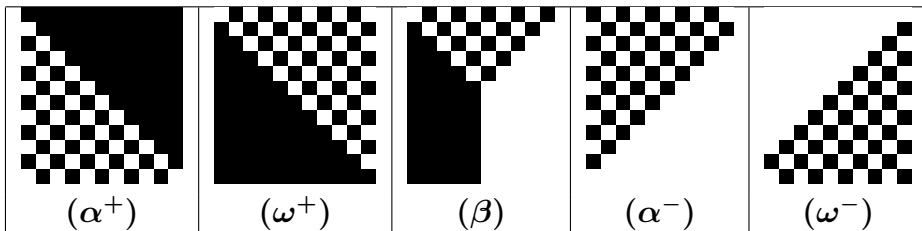
**Example:** Let  $\mathfrak{M}$  be the *monochromatic* shift. Then  $\mathfrak{M}_{(1)} := \mathfrak{B}_{(1)} \sqcup \mathfrak{W}_{(1)}$ , where  $\mathfrak{B}_{(1)} := \left\{ \begin{array}{c} \blacksquare \blacksquare \\ \blacksquare \blacksquare \end{array} \right\}$  and  $\mathfrak{W}_{(1)} := \left\{ \begin{array}{c} \square \square \\ \square \square \\ \square \square \end{array} \right\}$ .  
The defect at right is an interface.



**Example:** (ECA #184) Let  $\mathcal{A} = \{\square, \blacksquare\}$ . Let  $\mathfrak{G}_{(1)} := \mathfrak{B}_{(1)} \sqcup \mathfrak{W}_{(1)} \sqcup \mathfrak{C}_{(1)}$ , where  $\mathfrak{B}_{(1)} := \{\blacksquare \blacksquare \blacksquare\}$ ,  $\mathfrak{W}_{(1)} := \{\square \square \square\}$ , and  $\mathfrak{C}_{(1)} := \{\blacksquare \square \blacksquare, \square \blacksquare \square\}$ . This yields 6 possible interfaces:

$$\begin{array}{ll}
 \alpha^+ : \mathfrak{C}_{(1)} \left[ \dots \blacksquare \square \square \square \square \right] \left[ \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \dots \right] \mathfrak{B}_{(1)} & \alpha^- : \mathfrak{C}_{(1)} \left[ \dots \blacksquare \square \square \square \square \right] \left[ \square \square \square \square \square \dots \right] \mathfrak{W}_{(1)} \\
 \omega^+ : \mathfrak{B}_{(1)} \left[ \dots \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \right] \left[ \blacksquare \square \square \square \square \dots \right] \mathfrak{C}_{(1)} & \omega^- : \mathfrak{W}_{(1)} \left[ \dots \square \square \square \square \square \right] \left[ \blacksquare \square \square \blacksquare \square \dots \right] \mathfrak{C}_{(1)} \\
 \beta : \mathfrak{B}_{(1)} \left[ \dots \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \right] \left[ \square \square \square \square \square \dots \right] \mathfrak{W}_{(1)} & \epsilon : \mathfrak{B}_{(1)} \left[ \dots \square \square \square \square \square \right] \left[ \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \dots \right] \mathfrak{W}_{(1)}
 \end{array}$$

$\Phi_{184}(\mathfrak{G}) \subseteq \mathfrak{G}$ , and the  $\Phi_{184}$ -propagation of these interfaces is as follows:



**Theorem:** If  $\Phi : \mathfrak{A} \rightarrow \mathfrak{A}$  is surjective, then all interfaces are  $\Phi$ -persistent defects.  $\square$



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**Interfaces** (formal version)
 

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$\mathfrak{A}$  is  **$(\Phi, \sigma)$ -transitive** if  $\bigcup_{t \in \mathbb{N}} \bigcup_{z \in \mathbb{Z}^D} \Phi^{-t} \sigma^{-z}(\mathfrak{D})$  is dense in  $\mathfrak{A}$ , for any nonempty open  $\mathfrak{D} \subset \mathfrak{A}$ . (Equivalent: most  $(\Phi, \sigma)$ -orbits are dense in  $\mathfrak{A}$ ).

Suppose  $\mathfrak{A}$  is not transitive, but  $\mathfrak{A} = \mathfrak{A}_1 \sqcup \dots \sqcup \mathfrak{A}_K$ , where  $\mathfrak{A}_1, \dots, \mathfrak{A}_K$  are clopen  $(\Phi, \sigma)$ -transitive components.

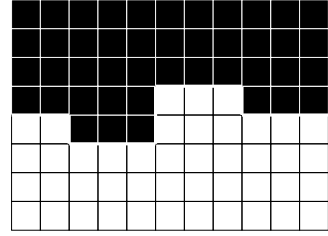
$(\mathfrak{A}_1, \dots, \mathfrak{A}_K \text{ are clopen}) \Rightarrow (\text{indicator functions are } \mathbf{locally\ determined})$   
 i.e.  $\exists r > 0$ , and function  $\kappa : \mathfrak{A}_{(r)} \rightarrow [1 \dots K]$  such that,  $\forall \mathbf{a} \in \mathfrak{A}$ ,

$$(\mathbf{a} \in \mathfrak{A}_k) \iff (\kappa(\mathbf{a}_{\mathbb{B}(r)}) = k).$$

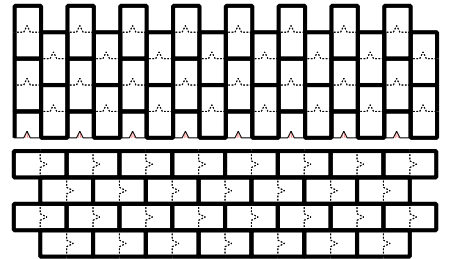
$\forall \mathbf{z} \in \mathbb{Z}^D$ , let  $\kappa_{\mathbf{z}}(\mathbf{a}) := \kappa(\mathbf{a}_{\mathbb{B}(\mathbf{z}, r)})$ . Then  $\kappa_{\mathbf{z}}(\mathbf{a})$  is also well-defined for any  $\mathbf{a} \in \tilde{\mathfrak{A}}$  such that  $\mathbf{a}_{\mathbb{B}(\mathbf{z}, r)}$  is  $\mathfrak{A}$ -admissible.

If  $\mathbf{y}, \mathbf{z} \in \mathbb{Z}^D$ , then  $\mathbf{a}$  has an **interface**<sup>†</sup> between  $\mathbf{y}$  and  $\mathbf{z}$  if  $\kappa_{\mathbf{y}}(\mathbf{a}) \neq \kappa_{\mathbf{z}}(\mathbf{a})$ .

**Example:**  $\mathfrak{M}_0$  has two  $\sigma$ -transitive components:  $\mathfrak{M}_0 := \text{all-black}$ , and  $\mathfrak{M}_1 := \text{all-white}$ . This defect is an interface.



**Nonexample:** This is *not* an interface, because  $\mathfrak{D}_{\text{om}}$  is  $\sigma$ -transitive [Einsiedler, 2001]. Instead this is a ‘gap’ defect.



Interfaces always form domain boundaries. Let  $\mathbb{Y}_1, \dots, \mathbb{Y}_N$  be the connected components of  $\mathbb{G}(\mathbf{a})$ . There is a function  $\mathcal{K} : [1 \dots N] \rightarrow [1 \dots K]$  such that for any  $n \in [1 \dots N]$  and any  $\mathbf{y} \in \mathbb{Y}_n$ ,  $\kappa_{\mathbf{y}}(\mathbf{a}) = \mathcal{K}(n)$ .

(†) Technically, this is an interface of range  $r$ , and this concept only makes sense for domain boundaries of range  $R \geq r$ .

## Persistence of Interfaces

A connected component  $\mathbb{Y}_n$  of  $\mathbb{G}$  is **projective** if, for all  $R > 0$ ,  $\exists \mathbf{y} \in \mathbb{Y}_n$  with  $\mathbf{a}_{\mathbb{B}(\mathbf{y}, R)} \in \mathfrak{A}_{(R)}$ . (i.e.  $\mathbb{Y}_n$  contains arbitrarily large  $\mathfrak{A}$ -admissible patches.)

**Lemma:** *The interface in  $\mathbf{a}$  is essential if there are two projective components  $\mathbb{Y}_n$  and  $\mathbb{Y}_m$  with  $\mathcal{K}(n) \neq \mathcal{K}(m)$ .*  $\square$

**Signature** of the interface := restriction of  $\mathcal{K}$  to projective components.

**Example:** Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}}$ . Suppose  $\mathbf{a} \in \tilde{\mathfrak{A}}$  has defects  $\mathbf{d}_1, \dots, \mathbf{d}_N$  with  $\mathbb{Y}_0, \dots, \mathbb{Y}_N$  being the  $\mathfrak{A}$ -admissible intervals between these defects:

$$\cdots \leftarrow \mathbb{Y}_0 \longrightarrow \mathbf{d}_1 \longleftarrow \mathbb{Y}_1 \longrightarrow \mathbf{d}_2 \longleftarrow \mathbb{Y}_2 \longrightarrow \cdots \longleftarrow \mathbb{Y}_{N-1} \longrightarrow \mathbf{d}_N \longleftarrow \mathbb{Y}_N \longrightarrow \cdots$$

Projective components:  $\mathbb{Y}_0$  &  $\mathbb{Y}_N$ .  $\therefore$  Interface is essential if  $\mathcal{K}(0) \neq \mathcal{K}(N)$ .

**Theorem:** *If  $\Phi : \mathfrak{A} \rightarrow \mathfrak{A}$  is surjective, then all essential interfaces are  $\Phi$ -persistent. If  $\mathbf{a} \in \tilde{\mathfrak{A}}$  has an essential interface, then  $\Phi(\mathbf{a})$  also has an essential interface, with the same signature as  $\mathbf{a}$ .*  $\square$

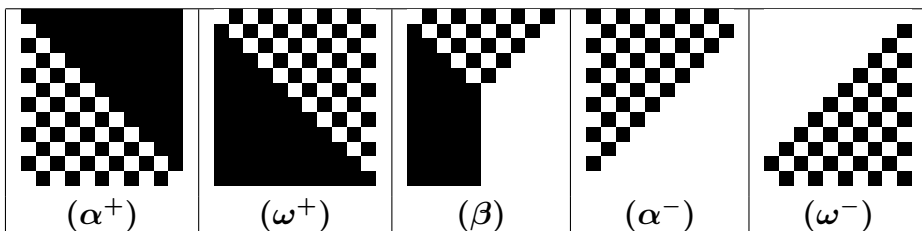
**Example:** (ECA #184) Let  $\mathcal{A} = \{\square, \blacksquare\}$ . Let  $\mathfrak{G} := \mathfrak{G}_0 \sqcup \mathfrak{G}_1 \sqcup \mathfrak{G}_*$ , where  $\mathfrak{G}_0 := \{\blacksquare\}$ ,  $\mathfrak{G}_1 := \{\square\}$ , and  $\mathfrak{G}_* := \{\blacksquare\square, \square\square\}$ . (Here,  $\blacksquare := [\dots \blacksquare \blacksquare \blacksquare \blacksquare \dots]$  and  $\square\square := [\dots \blacksquare \square \square \square \dots]$ , etc.)

Then  $\mathfrak{G}_0 \cup \mathfrak{G}_1 \subset \text{Fix}[\Phi_{184}]$ , while  $\Phi_{184}|_{\mathfrak{G}_*} = \sigma$ .

$\mathfrak{G}$  has three  $(\Phi_{184}, \sigma)$ -transitive components, so  $\exists$  6 possible interfaces:

$$\begin{array}{ll} \alpha^+ : \mathfrak{G}_* \left[ \dots \blacksquare \square \square \square \square \right] \left[ \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \dots \right] \mathfrak{G}_0 & \alpha^- : \mathfrak{G}_* \left[ \dots \blacksquare \blacksquare \blacksquare \blacksquare \square \right] \left[ \square \square \square \square \square \dots \right] \mathfrak{G}_1 \\ \omega^+ : \mathfrak{G}_0 \left[ \dots \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \right] \left[ \blacksquare \square \square \square \square \dots \right] \mathfrak{G}_* & \omega^- : \mathfrak{G}_1 \left[ \dots \square \square \square \square \square \right] \left[ \blacksquare \blacksquare \blacksquare \blacksquare \dots \right] \mathfrak{G}_* \\ \beta : \mathfrak{G}_0 \left[ \dots \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \right] \left[ \square \square \square \square \square \dots \right] \mathfrak{G}_1 & \epsilon : \mathfrak{G}_0 \left[ \dots \square \square \square \square \square \right] \left[ \blacksquare \blacksquare \blacksquare \blacksquare \dots \right] \mathfrak{G}_1 \end{array}$$

The  $\Phi_{184}$ -propagation of these defects is as follows:

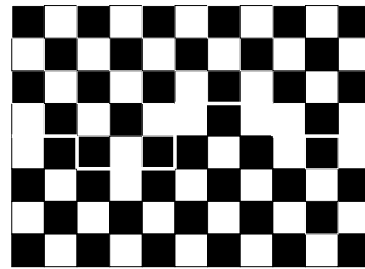


**Dislocations** (intuitive version)

Suppose  $\mathfrak{A}$  has a *spatiotemporally periodic* structure. In any  $\mathfrak{A}$ -admissible configuration, certain patterns must recur periodically in space and time.

A **dislocation** is a domain boundary between two regions which are ‘out of phase’ with respect to this periodic structure. Such a domain boundary is necessarily an essential defect.

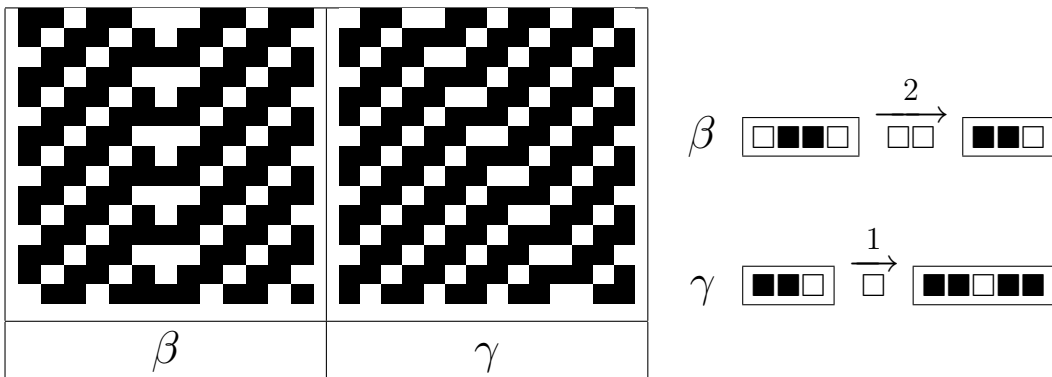
**Example:** The checkerboard shift  $\mathfrak{C}_h$  is both vertically and horizontally 2-periodic in space. The domain boundary at right is a dislocation.



The spatiotemporally periodic structure of  $\mathfrak{A}$  is described by a subgroup  $\mathbb{K} \subset \mathbb{Z}^{D+1}$ . Each dislocation is characterized by a **displacement**  $\delta \in \Delta$ , where  $\Delta := \mathbb{Z}^{D+1}/\mathbb{K}$  is the quotient group.

**Example:** (ECA#62) Let  $\mathfrak{D} = \text{orbit of } [\dots \blacksquare\blacksquare\blacksquare \blacksquare\blacksquare\blacksquare \blacksquare\blacksquare\blacksquare \dots]$ . Then  $\Phi_{62}|_{\mathfrak{D}} = \sigma$ , so  $(\mathfrak{D}, \Phi_{62})$  is 3-periodic in both space and time, and  $\Delta \cong \mathbb{Z}/3$ .

Here are two dislocations in  $\mathfrak{D}$  and their displacements:



**Theorem:** If  $\Phi : \mathfrak{A} \rightarrow \mathfrak{A}$  is surjective, then any nontrivial dislocation is a  $\Phi$ -persistent defect. Furthermore the displacement of each dislocation is constant over time. □

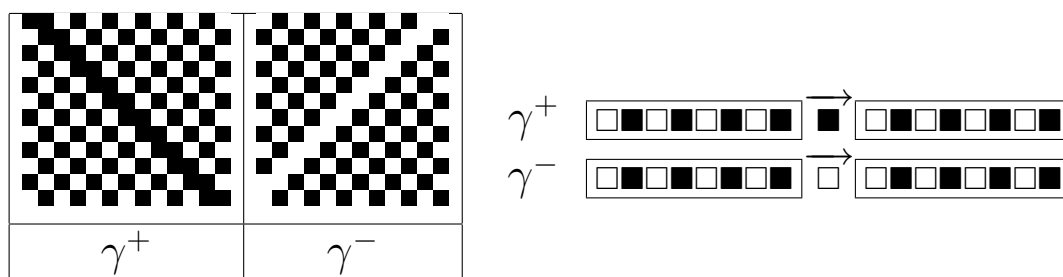
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### Dislocations in ECA#184 (intuitive version)

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Let  $\mathfrak{G}_*$  = orbit of  $[\dots \blacksquare \blacksquare \blacksquare \blacksquare \dots]$ . Then  $\Phi_{184}|_{\mathfrak{G}_*} = \sigma$ , so  $(\mathfrak{G}_*, \Phi_{184})$  is 2-periodic in both space and time, and  $\Delta \cong \mathbb{Z}_2$ .

Here are two dislocations, both with displacement  $1 \in \mathbb{Z}_2$ :

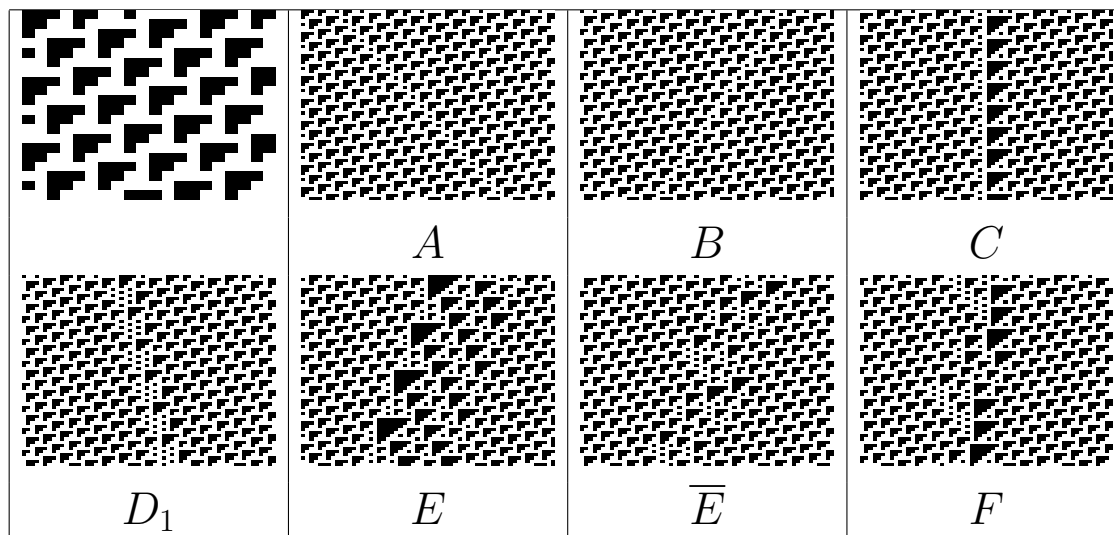
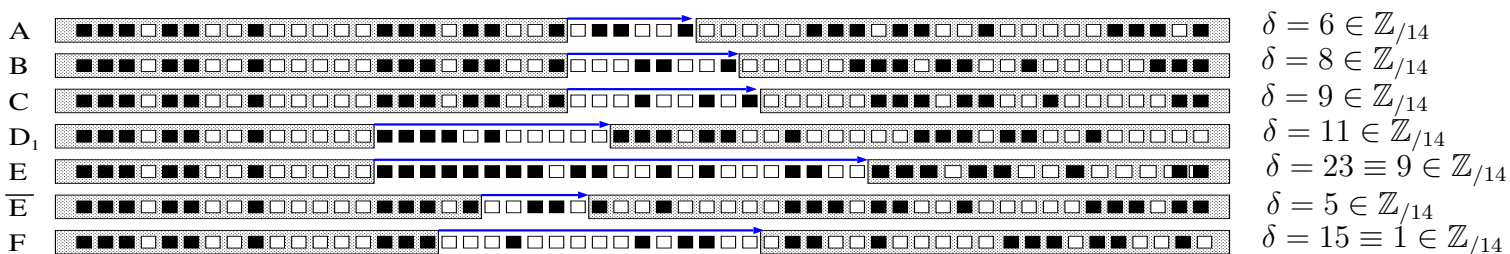



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### Dislocations in ECA#110

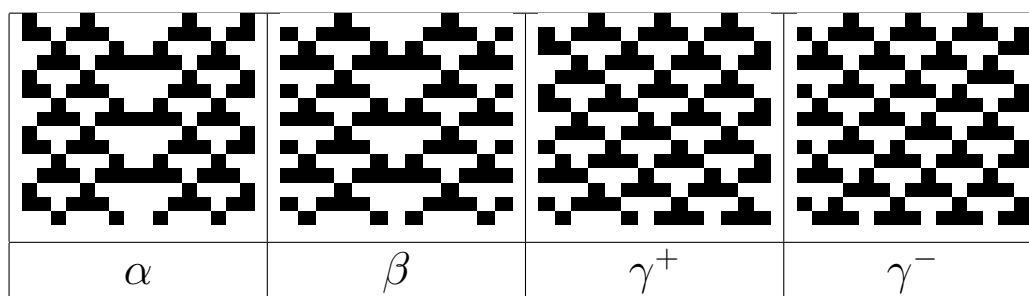
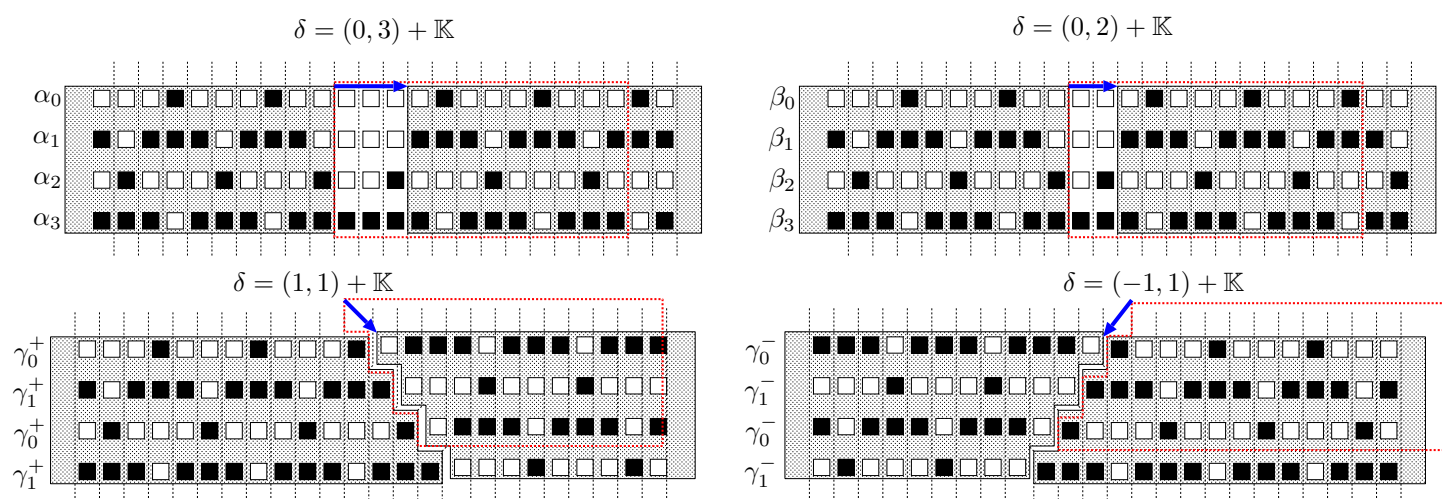
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Let  $\mathfrak{E} = \text{orbit of } [\dots \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \dots]$ . Then  $\Phi_{110}|_{\mathfrak{E}} = \sigma^4$ , so  $(\mathfrak{E}, \Phi_{110})$  is spatiotemporally periodic, and  $\Delta \cong \mathbb{Z}_{14}$ . Here are seven dislocations in  $\mathfrak{E}$ :



**Dislocations in ECA#54 (intuitive version)**

Let  $\mathfrak{B} := \mathfrak{B}_0 \sqcup \mathfrak{B}_1$ , where  $\mathfrak{B}_0$  is the  $\sigma$ -orbit of  $[\dots \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \dots]$  and  $\mathfrak{B}_1$  is the  $\sigma$ -orbit of  $[\dots \square \square \square \blacksquare \square \square \square \blacksquare \square \square \square \dots]$ . Then  $\Phi_{54}(\mathfrak{B}_0) = \mathfrak{B}_1$ ,  $\Phi_{54}(\mathfrak{B}_1) = \mathfrak{B}_0$ , and  $\Phi_{54}^2|_{\mathfrak{B}} = \sigma^2$ . Thus,  $(\mathfrak{B}, \Phi_{54})$  is spatiotemporally periodic, and  $\Delta = \mathbb{Z}^2/\mathbb{K}$ , where  $\mathbb{K} := \mathbb{Z}(2, 2) \oplus \mathbb{Z}(0, 4)$ . Here are four dislocations in ECA#54 and their displacements:



**Displacement Algebra and Defect Chemistry**

When two displacement defects collide, the outcome can be partially predicted by the algebra of the displacement group  $\Delta$ .

<i>ECA#62</i>		<i>ECA#184</i>	<i>ECA#54</i>	
$\gamma + \beta \rightarrow \alpha$	$\gamma + \alpha \rightarrow \gamma$	$\gamma^+ + \gamma^- \rightarrow \emptyset$	$\gamma^+ + \gamma^- \rightarrow \beta$	$\gamma^+ + \beta \rightarrow \gamma^-$
$2 + 1 \equiv 0$	$2 + 0 \equiv 2$	$1 + 1 \equiv 0$	$(1, 1) + (-1, 1) = (0, 2)$	$(1, 1) + (0, 2) \equiv (-1, 1)$

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## Dislocations (fomal version)

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Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}^D}$  be a  $\Phi$ -invariant subshift. Let  $\boldsymbol{\lambda} := (\lambda_0; \lambda_1, \dots, \lambda_D)$  be a  $(D + 1)$ -tuple of complex roots of unity. A **rational eigenfunction** of  $\mathfrak{A}$  with **eigenvalue**  $\boldsymbol{\lambda}$  is a function  $F : \mathfrak{A} \rightarrow \mathbb{C}$  such that:

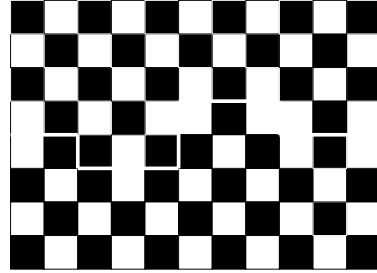
$$F \circ \Phi = \lambda_0 F, \quad \text{and} \quad F \circ \sigma^{\mathbf{z}} = \boldsymbol{\lambda}^{\mathbf{z}} F, \quad \forall \mathbf{z} \in \mathbb{Z}^D.$$

Here, if  $\mathbf{z} = (z_1, \dots, z_D)$ , then we define  $\boldsymbol{\lambda}^{\mathbf{z}} := \lambda_1^{z_1} \cdots \lambda_D^{z_D}$ .

Any rational eigenfunction is **locally determined** i.e.  $\exists r > 0$ , and function  $f : \mathfrak{A}_{(r)} \rightarrow \mathbb{C}$  such that,  $\forall \mathbf{a} \in \mathfrak{A}$ ,  $F(\mathbf{a}) = f(\mathbf{a}_{\mathbb{B}(r)})$ .

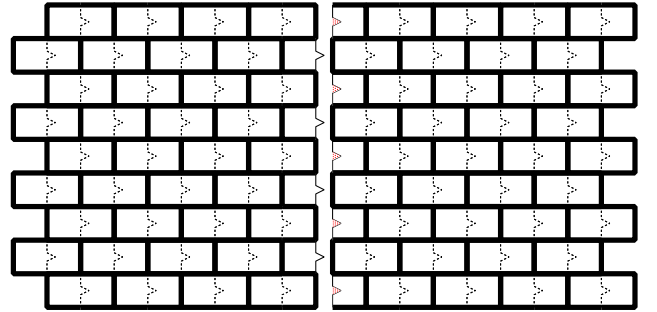
$\forall \mathbf{z} \in \mathbb{Z}^D$ , let  $f_{\mathbf{z}}(\mathbf{a}) := f(\mathbf{a}_{\mathbb{B}(\mathbf{z}, r)})$ . Then  $f_{\mathbf{z}}(\mathbf{a})$  is also well-defined for any  $\mathbf{a} \in \tilde{\mathfrak{A}}$  such that  $\mathbf{a}_{\mathbb{B}(\mathbf{z}, r)}$  is  $\mathfrak{A}$ -admissible. If  $\mathbf{x}, \mathbf{y} \in \mathbb{Z}^D$ , then  $\mathbf{a}$  has an  **$(\mathfrak{A}, \Phi)$ -dislocation**<sup>‡</sup> between  $\mathbf{x}$  and  $\mathbf{y}$  if  $f_{\mathbf{x}}(\mathbf{a})/f_{\mathbf{y}}(\mathbf{a}) \neq \boldsymbol{\lambda}^{\mathbf{x}-\mathbf{y}}$ .

**Example:** Define  $F : \mathfrak{C}_b \rightarrow \{\pm 1\}$  by local rule  $f : \{\blacksquare, \square\} \rightarrow \{\pm 1\}$  where  $f(\blacksquare) = 1$  and  $f(\square) = -1$ . Then  $F$  is  $\sigma$ -eigenfunction with eigenvalue  $(-1, -1)$ .



**Nonexample:** This is *not* a dislocation, because  $\mathfrak{D}_{\text{om}}$  is  $\sigma$ -mixing [Einsiedler, 2001], and thus, has no nontrivial eigenfunctions [Keynes & Robertson, 1969].

Instead this is a ‘gap’ defect.



Dislocations always form domain boundaries. Let  $\mathbb{K} := \{\mathbf{k} \in \mathbb{Z}^D ; \boldsymbol{\lambda}^{\mathbf{k}} = 1\}$ . For any connected components  $\mathbb{X}, \mathbb{Y}$  of  $\mathbb{G}(\mathbf{a})$ ,  $\exists$  unique **displacement**  $\boldsymbol{\delta} \in \mathbb{Z}^{D+1}/\mathbb{K}$  such that, for any  $\mathbf{x} \in \mathbb{X}$  and  $\mathbf{y} \in \mathbb{Y}$ ,  $\frac{f_{\mathbf{x}}(\mathbf{a})}{\boldsymbol{\lambda}^{\mathbf{x}-\mathbf{y}} f_{\mathbf{y}}(\mathbf{a})} = \boldsymbol{\lambda}^{\boldsymbol{\delta}}$ .

(‡) Technically, this is a dislocation of range  $r$ , and this concept only makes sense for domain boundaries of range  $R \geq r$ .

Persistence of Dislocations

**Lemma:** *The dislocation in  $\mathbf{a}$  is essential if  $\exists$  two projective components  $\mathbb{X}$  and  $\mathbb{Y}$  with a nontrivial displacement between them.  $\square$*

If  $\mathbf{a}$  has  $N$  projective components, then the **displacement matrix** is the antisymmetric  $N \times N$  matrix of  $(\mathbb{Z}^{D+1}/\mathbb{K})$ -valued displacements between them. Essential dislocations are persistent:

**Theorem:** *If  $\Phi : \mathfrak{A} \rightarrow \mathfrak{A}$  is surjective, then all essential dislocations are  $\Phi$ -persistent. If  $\mathbf{a} \in \tilde{\mathfrak{A}}$  has essential dislocation, then  $\Phi(\mathbf{a})$  also has essential dislocation, with the same displacement matrix as  $\mathbf{a}$ .  $\square$*

**Example:** (ECA#62) Let  $\mathcal{A} = \{\blacksquare, \square\}$ . Let  $\mathfrak{D}$  be the three-periodic  $\sigma$ -orbit of  $\overline{\blacksquare\blacksquare\blacksquare}$ . Then  $\Phi_{62}|_{\mathfrak{D}} = \sigma$ .

Let  $\lambda := e^{2\pi i/3}$ . Define  $F : \mathfrak{D} \rightarrow \mathbb{C}$  by  $F(\overline{\blacksquare\blacksquare\blacksquare}) = \square$ ,  $F(\overline{\blacksquare\square\blacksquare}) = \lambda$ , and  $F(\overline{\square\blacksquare\blacksquare}) = \lambda^2$ . Then  $F \circ \sigma = \lambda F = F \circ \Phi_{62}$ , so  $F$  is eigenfunction with eigenvalue  $(\lambda, \lambda)$ .

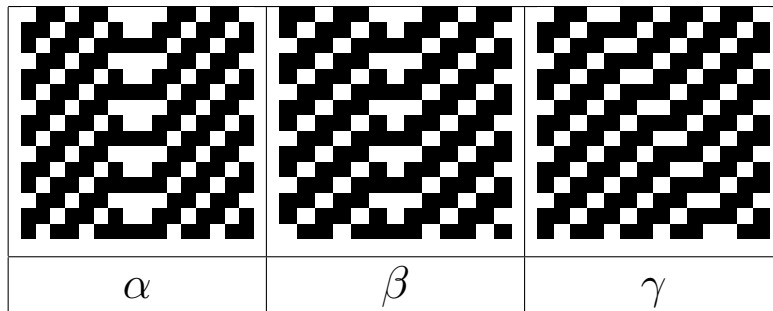
$\mathbb{K} = \mathbb{Z}(3, 0) \oplus \mathbb{Z}(1, 2)$ , so displacements are elements of  $\Delta \cong \mathbb{Z}/3$ .

Below are three rational dislocations in  $\mathfrak{D}$  and their displacements.

$$\begin{array}{ll}
 \alpha \quad \overline{\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare} \xrightarrow{\overline{\square\square\square}} \overline{\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare} & \delta = 3 \equiv 0 \in \mathbb{Z}/3 \\
 \beta \quad \overline{\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare} \xrightarrow{\overline{\square\square}} \overline{\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare} & \delta = 2 \in \mathbb{Z}/3 \\
 \gamma \quad \overline{\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare} \xrightarrow{\overline{\square}} \overline{\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare} & \delta = 1 \in \mathbb{Z}/3
 \end{array}$$

The  $\beta$  and  $\gamma$  defects are essential, hence persistent by the theorem.

The  $\alpha$  defect is *not* essential, but is still persistent (not because of the theorem).



Persistence of Dislocations in ECA #54

Let  $\mathfrak{B} := \mathfrak{B}_0 \sqcup \mathfrak{B}_1$ , where  $\mathfrak{B}_0$  is the 4-periodic  $\sigma$ -orbit of  $\overline{\blacksquare\blacksquare\blacksquare\blacksquare}$  and  $\mathfrak{B}_1$  is the 4-periodic  $\sigma$ -orbit of  $\overline{\square\square\blacksquare\square}$ .

Then  $\Phi_{54}(\mathfrak{B}_0) = \mathfrak{B}_1$ ,  $\Phi_{54}(\mathfrak{B}_1) = \mathfrak{B}_0$ , and  $\Phi_{54}^2|_{\mathfrak{B}} = \sigma^2$ .

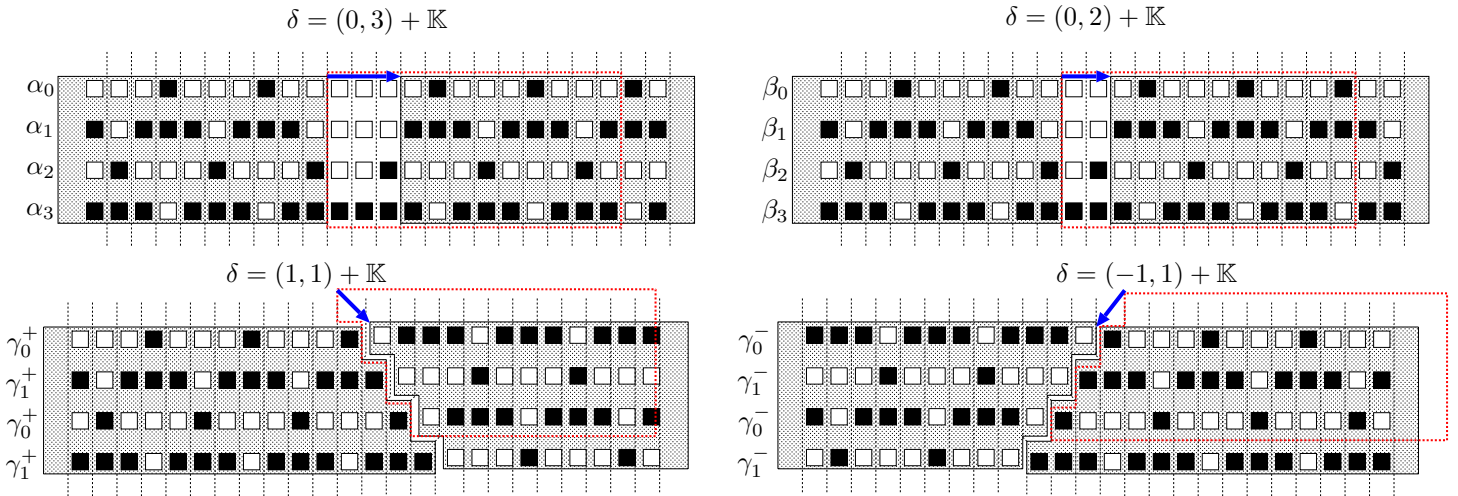
Define  $F : \mathfrak{B} \rightarrow \{\pm 1, \pm \mathbf{i}\}$  by

$$\begin{aligned} F(\overline{\blacksquare\blacksquare\blacksquare\blacksquare}) &= F(\overline{\square\blacksquare\square\square}) &= 1; \\ F(\overline{\blacksquare\square\blacksquare\blacksquare}) &= F(\overline{\blacksquare\square\square\square}) &= \mathbf{i}; \\ F(\overline{\square\blacksquare\blacksquare\blacksquare}) &= F(\overline{\square\square\square\blacksquare}) &= -1; \\ F(\overline{\blacksquare\blacksquare\blacksquare\square}) &= F(\overline{\square\square\blacksquare\square}) &= -\mathbf{i}. \end{aligned}$$

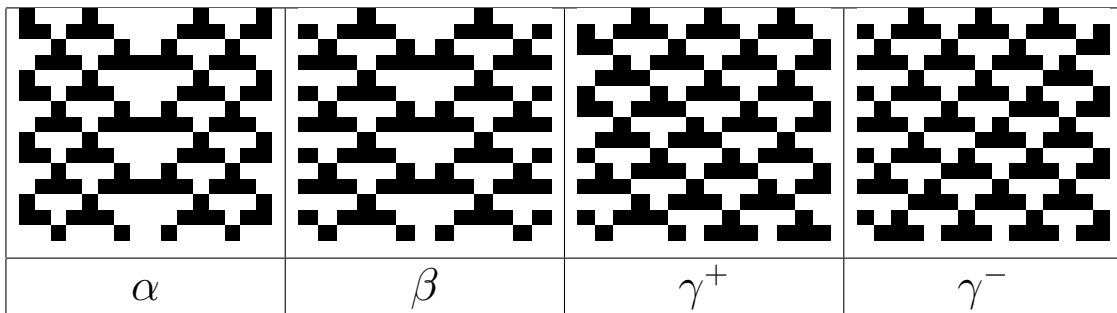
Then  $F \circ \sigma = \mathbf{i}F = F \circ \Phi_{54}$ , so  $F$  is eigenfunction with eigenvalue  $(\mathbf{i}, \mathbf{i})$ .

$\mathbb{K} := \mathbb{Z}(2, 2) \oplus \mathbb{Z}(0, 4)$ , so displacements are elements of  $\mathbb{Z}^2/\mathbb{K}$ .

Here are four rational dislocations in ECA#54 and their displacements:



All four have nontrivial displacement, so they are essential,  $\therefore \Phi_{54}$ -persistent.





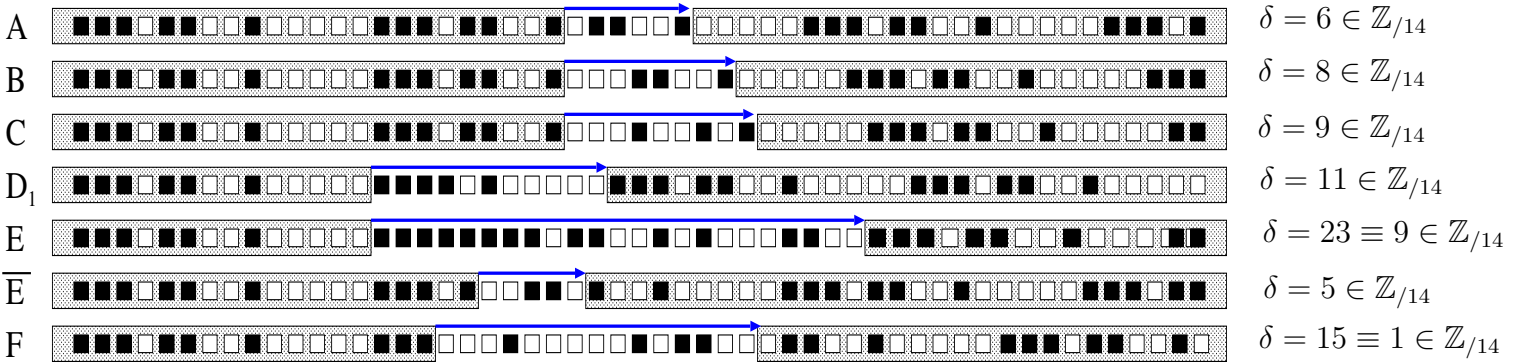
Persistence of Dislocations in ECA #110

Let  $\mathfrak{E} \subset \mathcal{A}^{\mathbb{Z}}$  be the 14-periodic  $\sigma$ -orbit of  $\overline{\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare}$ . Then  $\Phi_{110}|_{\mathfrak{E}} = \sigma^4$ .

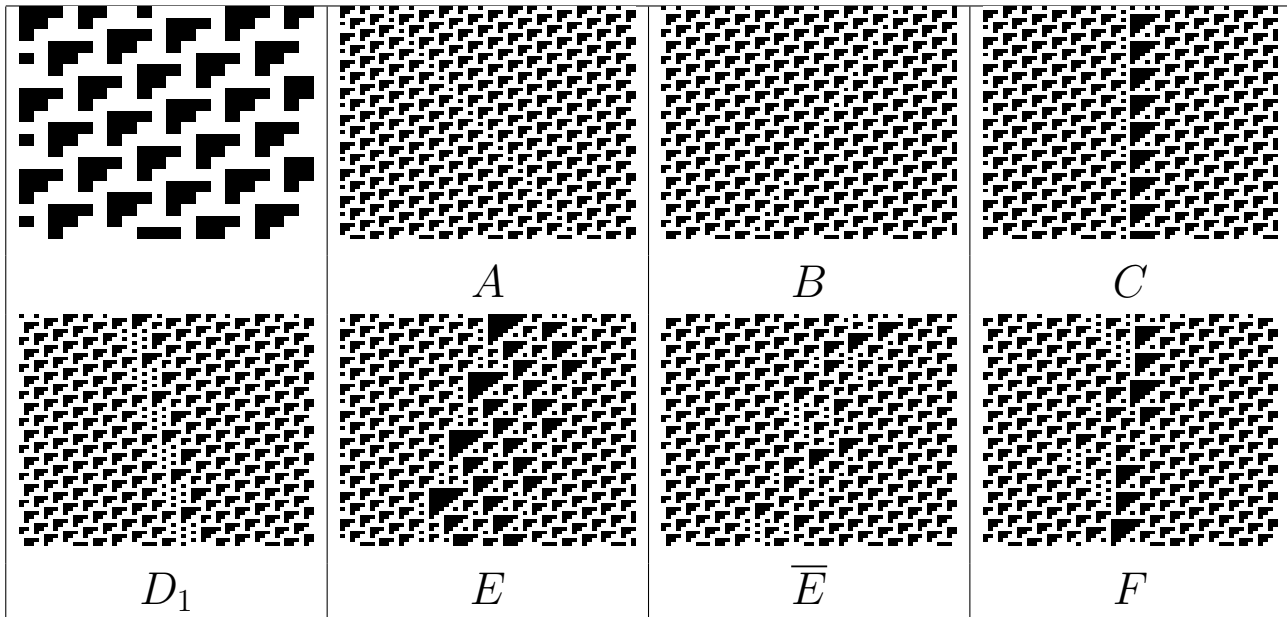
Let  $\lambda := e^{\pi i/7}$ . Let  $F : \mathfrak{E} \rightarrow \{\lambda^k\}_{k=0}^{13}$  be a  $\sigma$ -eigenfunction with  $F \circ \sigma = \lambda F$ . Then  $F \circ \Phi_{110} = \lambda^4 F$ , so  $F$  is a  $(\Phi_{184}, \sigma)$ -eigenfunction with eigenvalue  $(\lambda^4; \lambda)$ .

$\mathbb{K} = \mathbb{Z}(0, 14) \oplus \mathbb{Z}(1, 10)$ , so displacements are elements of  $\mathbb{Z}^2/\mathbb{K} \cong \mathbb{Z}_{/14}$ .

Here are seven rational dislocations in  $\mathfrak{E}$ :



All have nontrivial displacement, so they are essential and  $\Phi_{110}$ -persistent.



Persistence of Dislocations in ECA #184

Let  $\mathfrak{G}_* = \{\overline{\square\square}, \overline{\blacksquare\square}\}$ . Then  $\Phi_{184}|_{\mathfrak{G}_*} = \sigma$ .

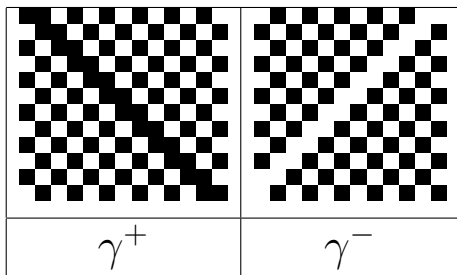
Define  $F : \mathfrak{G}_* \rightarrow \{\pm 1\}$  by  $F(\overline{\square\square}) = 1$  and  $F(\overline{\blacksquare\square}) = -1$ . Then

$F \circ \sigma = -F = F \circ \Phi_{184}$ , so  $F$  is eigenfunction with eigenvalue  $(-1, -1)$ .

$\mathbb{K} = \mathbb{Z}(2, 0) \oplus \mathbb{Z}(1, 1)$ , so displacements are elements of  $\mathbb{Z}^2/\mathbb{K} \cong \mathbb{Z}/2$ .

Here are two dislocations and their displacements:

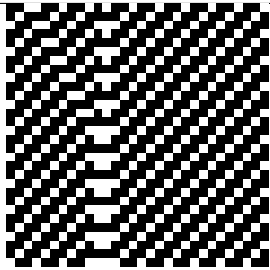
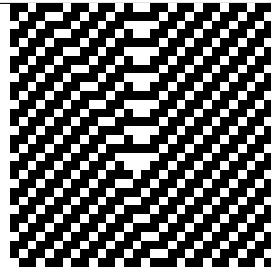
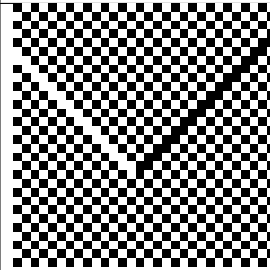
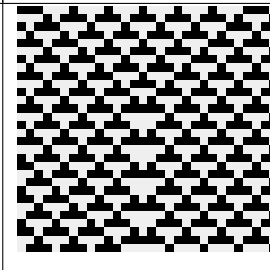
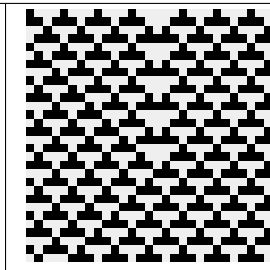
$$\begin{aligned} \gamma^+ & \quad \overline{\square\square\square\square\square\square\square\square} \xrightarrow{\blacksquare} \overline{\square\square\square\square\square\square\square\square} & \delta = 1 \in \mathbb{Z}/2 \\ \gamma^- & \quad \overline{\square\square\square\square\square\square\square\square} \xrightarrow{\square} \overline{\square\square\square\square\square\square\square\square} & \delta = 1 \in \mathbb{Z}/2 \end{aligned}$$



Both have nontrivial displacement, so they are essential and  $\Phi_{184}$ -persistent.

Displacement Algebra and Defect Chemistry

When two displacement defects collide, the outcome can be partially predicted by the algebra of the displacement group  $\mathbb{Z}^{D+1}/\mathbb{K}$ .

<i>ECA#62</i>		<i>ECA#184</i>	<i>ECA#54</i>	
				
$\gamma + \beta \rightarrow \alpha$ $2 + 1 \equiv 0$ (mod 3)	$\gamma + \alpha \rightarrow \gamma$ $2 + 0 \equiv 2$ (mod 3)	$\gamma^+ + \gamma^- \rightarrow \emptyset$ $1 + 1 \equiv 0$ (mod 2)	$\gamma^+ + \gamma^- \rightarrow \beta$ $(1, 1) + (-1, 1)$ $= (0, 2)$ $\in \mathbb{Z}^2/\mathbb{K}$	$\gamma^+ + \beta \rightarrow \gamma^-$ $(1, 1) + (0, 2) =$ $(1, 3) \equiv (-1, 1)$ $\in \mathbb{Z}^2/\mathbb{K}$

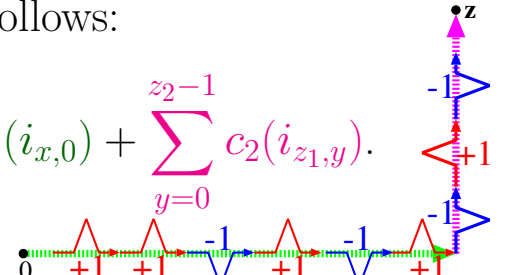
**The Fine Print:** Our definition of ‘displacement’ here is somewhat oversimplified. The ‘real’ definition is that a displacement is a *character* on the spectral group of  $(\mathfrak{A}, \Phi, \sigma)$ . This is necessary to extend the theory of dislocations to *irrational* eigenvalues (e.g. in Sturmian shifts or multidimensional SFTS) or *discontinuous* eigenfunctions (e.g. on sofic shifts, as in ECA#18).

## Cocycles

Let  $\mathfrak{A} \subseteq \mathcal{A}^{\mathbb{Z}^D}$  be a subshift. Let  $(\mathcal{G}, \cdot)$  be a (discrete) group. A  $\mathcal{G}$ -valued **cocycle** is continuous function  $C : \mathbb{Z}^D \times \mathfrak{A} \rightarrow \mathcal{G}$  satisfying **cocycle equation**:

$$C(\mathbf{y} + \mathbf{z}, \mathbf{a}) = C(\mathbf{y}, \sigma^{\mathbf{z}}(\mathbf{a})) \cdot C(\mathbf{z}, \mathbf{a}), \quad \forall \mathbf{a} \in \mathcal{A}^{\mathbb{Z}^D} \text{ and } \forall \mathbf{y}, \mathbf{z} \in \mathbb{Z}^D.$$

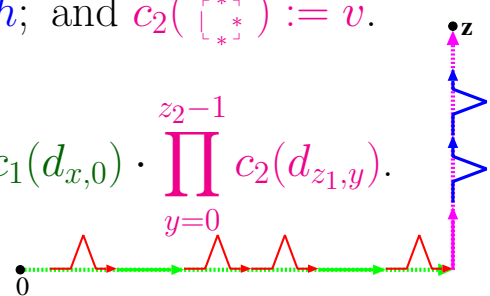
**Examples:** (a) Let  $\mathfrak{I}_{ce} \subset \mathcal{I}^{\mathbb{Z}^2}$  be square ice. Define  $c_1, c_2 : \mathcal{I} \rightarrow \{\pm 1\}$  by  $c_1(\begin{smallmatrix} * & * \\ \wedge & * \end{smallmatrix}) := +1 =: c_2(\begin{smallmatrix} * \\ \swarrow & * \end{smallmatrix})$  and  $c_1(\begin{smallmatrix} * & * \\ \vee & * \end{smallmatrix}) := -1 =: c_2(\begin{smallmatrix} * \\ \searrow & * \end{smallmatrix})$  ('\*' means 'anything'). Define cocycle  $C : \mathbb{Z}^2 \times \mathfrak{I}_{ce} \rightarrow \mathbb{Z}$  as follows:

$$\forall \mathbf{i} \in \mathfrak{I}_{ce}, \quad \forall \mathbf{z} = (z_1, z_2) \in \mathbb{Z}^2, \quad C(\mathbf{z}, \mathbf{i}) := \sum_{x=0}^{z_1-1} c_1(i_{x,0}) + \sum_{y=0}^{z_2-1} c_2(i_{z_1,y}).$$


This is a **height function** (a  $\mathbb{Z}$ -valued cocycle). These arise in tilings [e.g. K. Eloranta 1999-2005, H.Cohn & J.Propp] and statistical mechanics [R.Baxter 1989].

(b) Let  $\mathfrak{D}_{om} \subset \mathcal{D}^{\mathbb{Z}^2}$  be dominoes. Let  $\mathcal{G} := \mathbb{Z}/2 * \mathbb{Z}/2$  be group of finite products  $vhv hv \cdots v hv$ , where  $v$  and  $h$  are noncommuting generators with  $v^2 = e = h^2$ . Define  $c_1, c_2 : \mathcal{I} \rightarrow \mathcal{G}$  by

$$c_1(\begin{smallmatrix} \square \\ \wedge \end{smallmatrix}) := v h v; \quad c_1(\begin{smallmatrix} * & * \\ * & * \end{smallmatrix}) := h; \quad c_2(\begin{smallmatrix} * \\ \swarrow \end{smallmatrix}) := h v h; \quad \text{and} \quad c_2(\begin{smallmatrix} * \\ * \end{smallmatrix}) := v.$$

$$\forall \mathbf{d} \in \mathfrak{D}_{om}, \quad \forall \mathbf{z} = (z_1, z_2) \in \mathbb{Z}^2, \quad C(\mathbf{z}, \mathbf{d}) := \prod_{x=0}^{z_1-1} c_1(d_{x,0}) \cdot \prod_{y=0}^{z_2-1} c_2(d_{z_1,y}).$$


(c) If  $b : \mathfrak{A} \rightarrow \mathcal{G}$  is continuous, then function  $C(\mathbf{z}, \mathbf{a}) := b(\sigma^{\mathbf{z}}(\mathbf{a})) \cdot b(\mathbf{a})^{-1}$  is a cocycle, called a **coboundary**.

(d) Let  $\mathbf{X}$  = topological space. Let  $\mathcal{H} = \text{homeo}(\mathbf{X})$ . Then  $\mathcal{H}$ -valued cocycles are the fibre-wise maps of a skew product extension of the  $\sigma$ -action on  $\mathfrak{A}$  to a  $\mathbb{Z}^D$ -action on  $\mathfrak{A} \times \mathbf{X}$ . [R.Zimmer 1976-80, J.Kammeyer 1990-93]

## Cohomology

Two cocycles  $C$  and  $C'$  are **cohomologous** ( $C \approx C'$ ) if  $\exists$  continuous **transfer function**  $b : \mathfrak{A} \rightarrow \mathcal{G}$  such that

$$C'(\mathbf{z}, \mathbf{a}) = b(\sigma^{\mathbf{z}}(\mathbf{a})) \cdot C(\mathbf{z}, \mathbf{a}) \cdot b(\mathbf{a})^{-1}, \quad \forall \mathbf{z} \in \mathbb{Z}^D, \text{ and } \mathbf{a} \in \mathfrak{A}.$$

Let  $\underline{C} :=$  cohomology equivalence class of the cocycle  $C$ .

$$\mathcal{Z}^1(\mathfrak{A}, \mathcal{G}) := \{\mathcal{G}\text{-valued cocycles}\}.$$

$$\mathcal{H}^1(\mathfrak{A}, \mathcal{G}) := \{\text{cohomology equivalence classes in } \mathcal{Z}^1(\mathfrak{A}, \mathcal{G})\}.$$

If  $(\mathcal{G}, \cdot)$  is abelian, then  $\mathcal{Z}^1(\mathfrak{A}, \mathcal{G})$  is a group (under pointwise multiplication), and  $\mathcal{H}^1(\mathfrak{A}, \mathcal{G})$  is a quotient group, called the **1st cohomology group** of  $\mathfrak{A}$  (with coefficients in  $\mathcal{G}$ ). [see e.g. K.Schmidt (1995, 1998) for discussion]

## Trails and locally determined cocycles

Let  $\mathbb{E} := \{\mathbf{z} \in \mathbb{Z}^D ; \mathbf{z} = (0, \dots, 0, \pm 1, 0, \dots, 0)\}$ . A **trail** is a sequence  $\zeta = (\mathbf{z}_0, \mathbf{z}_1, \dots, \mathbf{z}_N) \subset \mathbb{Z}^D$ , where,  $\forall n \in [1 \dots N]$ ,  $\mathbf{z}'_n := (\mathbf{z}_n - \mathbf{z}_{n-1}) \in \mathbb{E}$ .

Let  $r > 0$ . Let  $c : \mathbb{E} \times \mathfrak{A}_{(r)} \rightarrow \mathcal{G}$  be such that,  $\forall \mathbf{e}, \mathbf{e}' \in \mathbb{E}, \quad \forall \mathbf{a} \in \mathfrak{A}$ ,

$$\begin{aligned} \text{(a)} \quad & c(\mathbf{e}', \mathbf{a}_{\mathbb{B}(\mathbf{e}, r)}) \cdot c(\mathbf{e}, \mathbf{a}_{\mathbb{B}(r)}) = c(\mathbf{e}, \mathbf{a}_{\mathbb{B}(\mathbf{e}', r)}) \cdot c(\mathbf{e}', \mathbf{a}_{\mathbb{B}(r)}). \quad \text{i.e. } c(\uparrow \rightarrow) = c(\leftarrow \downarrow) \\ \text{(b)} \quad & c(-\mathbf{e}, \mathbf{a}_{\mathbb{B}(\mathbf{e}, r)}) = c(\mathbf{e}, \mathbf{a}_{\mathbb{B}(r)})^{-1}. \quad \text{i.e. } c(\downarrow) = c(\uparrow)^{-1} \end{aligned}$$

Then  $c(\zeta, \mathbf{a}) := \prod_{n=1}^N c(\mathbf{z}'_n, \mathbf{a}_{\mathbb{B}(\mathbf{z}_{n-1}, r)})$  depends only on  $\mathbf{z}_0$  and  $\mathbf{z}_N$ , not  $\zeta$ .

**Example:** If  $\zeta$  is **closed** (i.e.  $\mathbf{z}_N = \mathbf{z}_0$ ) then  $c(\zeta, \mathbf{a}) = e_{\mathcal{G}}$ .

Define cocycle  $C : \mathbb{Z}^D \times \mathfrak{A} \rightarrow \mathcal{G}$  as follows:  $\forall \mathbf{a} \in \mathfrak{A}, \mathbf{z} \in \mathbb{Z}^D$ ,  $C(\mathbf{z}, \mathbf{a}) := c(\zeta, \mathbf{a})$ , (where  $\zeta$  is *any* trail from 0 to  $\mathbf{z}$ ). We say  $C$  is **locally determined** with **local rule**  $c$  of **radius**  $r$ .

If  $\mathcal{G}$  is discrete, then  $\forall$  continuous  $\mathcal{G}$ -valued cocycles are locally determined. For any  $r > 0$ , let  $\mathcal{Z}_r^1(\mathfrak{A}, \mathcal{G}) :=$  radius- $r$  cocycles on  $\mathfrak{A}$ .

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**Cocycles and Cellular Automata**

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**Proposition:** *Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}^D}$  be a subshift. Let  $\Phi : \mathcal{A}^{\mathbb{Z}^D} \longrightarrow \mathcal{A}^{\mathbb{Z}^D}$  be a cellular automaton with  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ . Let  $\mathcal{G}$  be a group.*

- (a) *Let  $C \in \mathcal{Z}^1(\mathfrak{A}, \mathcal{G})$  be cocycle. Define  $\Phi_* C : \mathbb{Z}^D \times \mathfrak{A} \longrightarrow \mathcal{G}$  by  $\Phi_* C(\mathbf{z}, \mathbf{a}) = C(\mathbf{z}, \Phi(\mathbf{a}))$ . Then  $\Phi_* C$  is also a cocycle on  $\mathfrak{A}$ .*
- (b) *If  $\Phi$  has radius  $R$ , and  $C$  is locally determined with radius  $r$ , then  $\Phi_* C$  is locally determined with radius  $r + R$ .*
- (c) *Let  $C, C' \in \mathcal{Z}^1(\mathfrak{A}, \mathcal{G})$ . If  $C \approx C'$ , then  $\Phi_* C \approx \Phi_* C'$ . Thus,  $\Phi$  induces a function  $\Phi_* : \mathcal{H}^1(\mathfrak{A}, \mathcal{G}) \longrightarrow \mathcal{H}^1(\mathfrak{A}, \mathcal{G})$ .*
- (d) *If  $(\mathcal{G}, \cdot)$  is abelian, then  $\Phi_*$  is a group endomorphism. □*

We will see that the  $\Phi$ -persistence of certain kinds of defects depends critically on the surjectivity of the endomorphism  $\Phi_*$ .

**Question:** *When is  $\Phi_*$  surjective?*

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## Gap Defects: Definition

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Some domain boundaries exhibit divergence in cocycle asymptotics.

Let  $C \in \mathcal{Z}_r^1(\mathfrak{A}, \mathbb{Z})$  be a range- $r$  cocycle (i.e. ‘height function’).

Let  $\mathbf{a} \in \tilde{\mathfrak{A}}$ . Let  $\mathbb{X}$  be an infinite, simply-connected component of  $\mathbb{G}_r(\mathbf{a})$ . Fix  $\mathbf{x}^* \in \mathbb{X}$ . For any  $\mathbf{x} \in \mathbb{X}$ , we define the **height difference**:

$$\mathbf{C}_{\mathbf{a}}(\mathbf{x}^*, \mathbf{x}) \quad := \quad c(\zeta, \mathbf{a}),$$

where  $c : \mathfrak{A}_{(r)} \rightarrow \mathbb{Z}$  is ‘local rule’, and  $\zeta$  is any trail in  $\mathbb{X}$  from  $\mathbf{x}^*$  to  $\mathbf{x}$ .

(Well-defined independent of  $\zeta$  because  $\mathbb{X}$  is a simply-connected.) Note:

$$|\mathbf{C}_{\mathbf{a}}(\mathbf{x}^*, \mathbf{x})| \quad \leq \quad K \cdot d_{\mathbb{X}}(\mathbf{x}^*, \mathbf{x}),$$

where  $K := \max_{\mathbf{a} \in \mathfrak{A}_{(r)}} |c(\mathbf{a})|$ , and  $d_{\mathbb{X}}(\mathbf{x}^*, \mathbf{x}) := \min \text{length}(\mathbb{X}\text{-trail from } \mathbf{x}^* \text{ to } \mathbf{x})$ .

Let  $\mathbb{Y}$  be another infinite connected component of  $\mathbb{G}_r(\mathbf{a})$ . Fix  $\mathbf{y}^* \in \mathbb{Y}$ . For any  $\mathbf{y} \in \mathbb{Y}$ , define  $C_{\mathbf{a}}(\mathbf{y}, \mathbf{y}^*)$  in the same way as  $C_{\mathbf{a}}(\mathbf{x}^*, \mathbf{x})$  above. We then define

$$\mathbf{C}(\mathbf{y}, \mathbf{x}) \quad := \quad C(\mathbf{y}, \mathbf{y}^*) + C(\mathbf{x}^*, \mathbf{x}).$$

If  $\mathbb{X}$  and  $\mathbb{Y}$  were the same connected component (or if we could remove the defect in  $\mathbf{a}$  so that they were), then we expect

$$C(\mathbf{y}, \mathbf{x}) \quad \leq \quad K \cdot d_{\mathbb{X}}(\mathbf{y}, \mathbf{x}) + \text{const.} \quad \approx \quad K|\mathbf{y} - \mathbf{x}| + \text{const.}$$

We say there is a **C-gap** between  $\mathbb{X}$  and  $\mathbb{Y}$  if  $\sup_{\mathbf{y} \in \mathbb{Y}, \mathbf{x} \in \mathbb{X}} \frac{|C(\mathbf{y}, \mathbf{x})|}{|\mathbf{y} - \mathbf{x}|} = \infty$ .

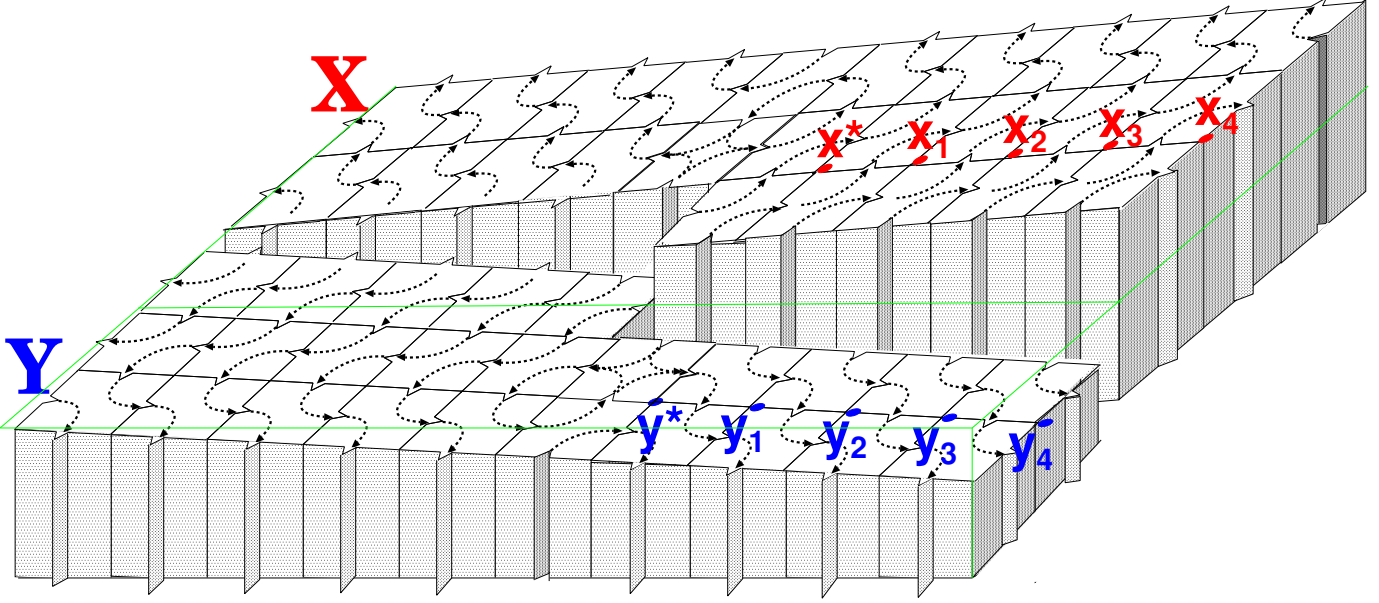
(This suggests that the defect separating  $\mathbb{X}$  and  $\mathbb{Y}$  is essential.)

**Fine print:** If  $\mathcal{G} \neq \mathbb{Z}$ , we can also define gaps for  $\mathcal{G}$ -valued cocycles, by first defining an appropriate *pseudonorm*  $\|\bullet\| : \mathcal{G} \rightarrow \mathbb{R}$  which satisfies the triangle inequality and is invariant under conjugation.

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## Gaps in the Ice

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**Example:** Consider the defective configuration in  $\tilde{\mathcal{I}}_{\text{ce}}$  shown above, and let  $\{\mathbf{x}^*, \mathbf{x}_1, \mathbf{x}_2, \dots\} \subset \mathbb{X}$  and  $\{\mathbf{y}^*, \mathbf{y}_1, \mathbf{y}_2, \dots\} \subset \mathbb{Y}$  be as shown. Let  $C \in \mathcal{Z}^1(\tilde{\mathcal{I}}_{\text{ce}}, \mathbb{Z})$  be the cocycle with local rule

$$c_1\left(\begin{array}{c} * \\ \wedge \\ * \end{array}\right) := +1 =: c_2\left(\begin{array}{c} * \\ \leftarrow \\ * \end{array}\right) \text{ and } c_1\left(\begin{array}{c} * \\ \vee \\ * \end{array}\right) := -1 =: c_2\left(\begin{array}{c} * \\ \rightarrow \\ * \end{array}\right).$$

Then  $C(\mathbf{x}^*, \mathbf{x}_n) = n$  and  $C(\mathbf{y}^*, \mathbf{y}_n) = -n$ , so  $C(\mathbf{x}_n, \mathbf{y}_n) = 2n$ ,  $\forall n \in \mathbb{N}$ .

But  $|\mathbf{x}_n - \mathbf{y}_n| = 2$ ,  $\forall n \in \mathbb{N}$ , so  $\lim_{n \rightarrow \infty} \frac{|C(\mathbf{x}_n, \mathbf{y}_n)|}{|\mathbf{x} - \mathbf{y}|} = \lim_{n \rightarrow \infty} \frac{2n}{2} = \infty$ ;  
hence there is a gap between  $\mathbb{X}$  and  $\mathbb{Y}$ .

**Example:** Let  $C : \mathbb{Z}^2 \times \mathcal{D}_{\text{om}} \rightarrow \mathcal{G} := \mathbb{Z}/2 * \mathbb{Z}/2$  have local rule:

$$c_1\left(\begin{array}{c} \leftarrow \\ \wedge \\ \leftarrow \end{array}\right) := hvv; \quad c_1\left(\begin{array}{c} * \\ \leftarrow \\ * \end{array}\right) := h; \quad c_2\left(\begin{array}{c} \rightarrow \\ \vee \\ \rightarrow \end{array}\right) := hvh; \text{ and } c_2\left(\begin{array}{c} * \\ \rightarrow \\ * \end{array}\right) := v.$$

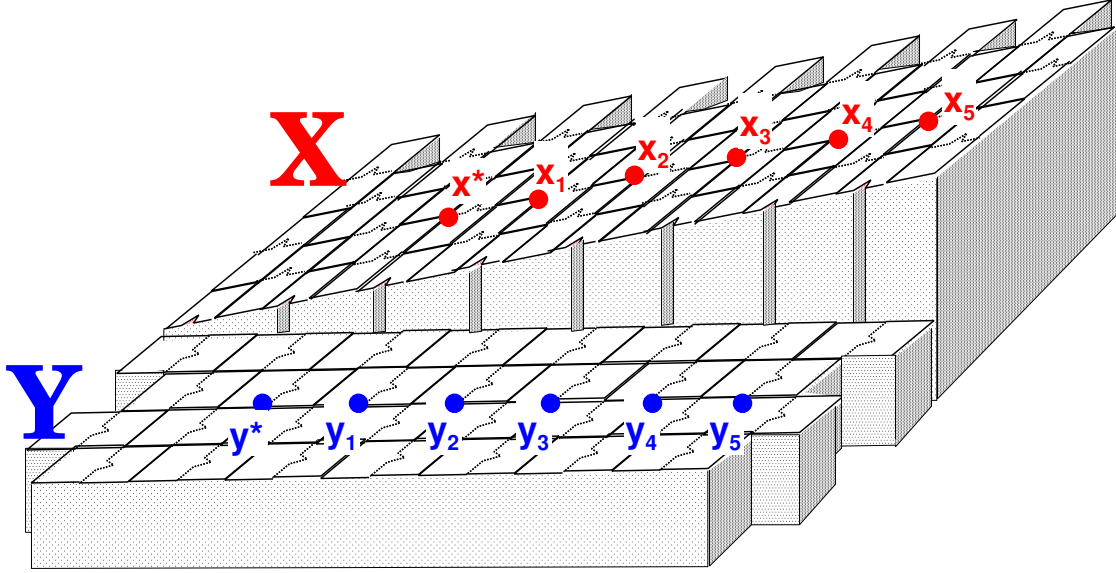
Let  $\mathcal{Z} := \{\text{cyclic subgroup generated by } hv\} \subset \mathcal{G}$ . Then  $(\mathcal{Z}, \cdot) \cong (\mathbb{Z}, +)$ , and for all  $\mathbf{d} \in \mathcal{D}_{\text{om}}$  and  $2\mathbf{z} \in 2\mathbb{Z}^2$ ,  $C(2\mathbf{z}, \mathbf{d}) \in \mathcal{Z}$ .

Let  $\mathcal{D}_2 \subset \mathcal{D}^{2 \times 2}$  be the alphabet of  $\mathcal{D}_{\text{om}}$ -admissible  $2 \times 2$  blocks. Let  $\mathcal{D}_2 \subset \mathcal{D}_2^{\mathbb{Z}^2}$  be ‘recoding’ of  $\mathcal{D}_{\text{om}}$  in this alphabet. Then  $2\mathbb{Z}^2$  acts on  $\mathcal{D}_2$  in the obvious way, and  $C$  yields a cocycle  $C' : 2\mathbb{Z}^2 \times \mathcal{D}_2 \rightarrow \mathcal{Z} \cong \mathbb{Z}$ .

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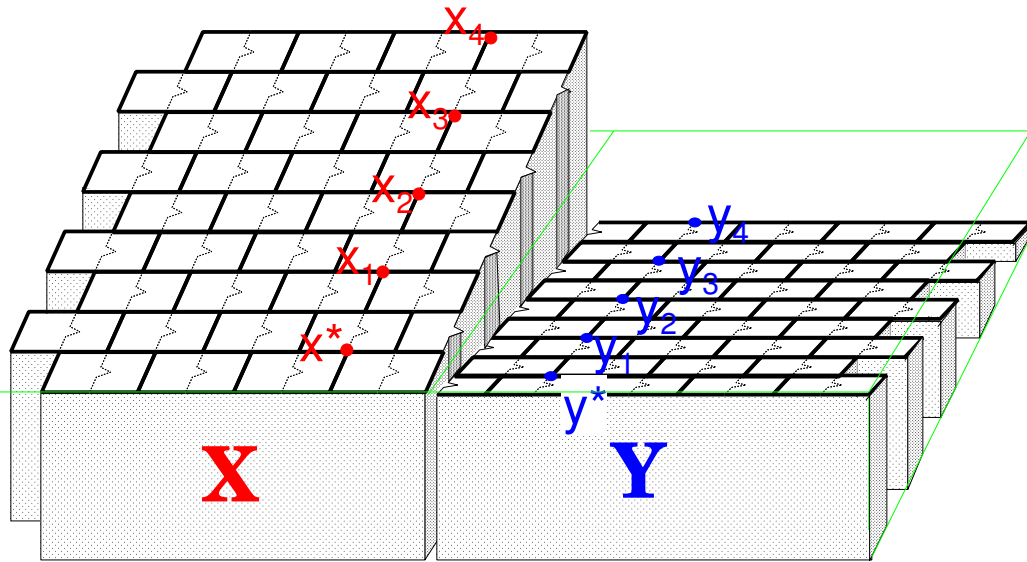
## Gaps in Dominoes

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In the  $\widetilde{\mathcal{D}}_{\text{om}}$ -configuration shown above,  $C'(x^*, x_n) = (vhvh)^n \cong 2n$ , while  $C'(y^*, y_n) = h^{2n} \cong 0$ , so  $C'(y_n, x_n) = n$ , for all  $n \in \mathbb{N}$ .

But  $|x_n - y_n| = 4, \forall n \in \mathbb{N}$ , so  $\lim_{n \rightarrow \infty} \frac{|C'(x_n, y_n)|}{|x - y|} = \lim_{n \rightarrow \infty} \frac{n}{4} = \infty$ .



In the  $\widetilde{\mathcal{D}}_{\text{om}}$ -configuration shown above,  $C'(x^*, x_n) = (vhvh)^n \cong 2n$ , while  $C'(y^*, y_n) = (hvhv)^n \cong -2n$ , so  $C'(y_n, x_n) = -4n, \forall n \in \mathbb{N}$ .

But  $|x_n - y_n| = 4, \forall n \in \mathbb{N}$ , so  $\lim_{n \rightarrow \infty} \frac{|C'(x_n, y_n)|}{|x - y|} = \lim_{n \rightarrow \infty} \frac{-4n}{4} = -\infty$ .



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## Persistence of Gaps

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**Theorem:** If  $\Phi: \mathcal{A}^{\mathbb{Z}^D} \rightarrow \mathcal{A}^{\mathbb{Z}^D}$  is a CA,  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ , and endomorphism

$$\Phi_* : \mathcal{H}^1(\mathfrak{A}, \mathbb{Z}) \ni C \mapsto C \circ \Phi \in \mathcal{H}^1(\mathfrak{A}, \mathbb{Z})$$

is surjective, then any gap is  $\Phi$ -persistent.

**Example:** If  $\mathcal{I} := \{\text{ice patterns}\}$ , and  $\Phi : \mathcal{I}^{\mathbb{Z}^2} \rightarrow \mathcal{I}^{\mathbb{Z}^2}$  is CA with  $\Phi(\mathfrak{I}_{ce}) \subseteq \mathfrak{I}_{ce}$ , and  $\Phi_* : \mathcal{H}^1(\mathfrak{I}_{ce}, \mathbb{Z}) \rightarrow \mathcal{H}^1(\mathfrak{I}_{ce}, \mathbb{Z})$  is surjective, then  $\Phi$  cannot destroy the ice gap (or even change the ‘difference in slope’).

**Proof idea:** First show that  $C$ -gaps depend only on cohomology class of  $C$ , i.e.:

**Lemma:** If  $C \approx C'$ , then any  $C$ -gap is also a  $C'$ -gap. ◇

Now suppose  $\mathbf{a}$  has  $C$ -gap. Now  $\Phi_*$  is surjective, so find  $C' \in \mathcal{Z}^1$  such that  $\Phi_* C' \approx C$ . Then  $\mathbf{a}$  also has  $(\Phi_* C')$ -gap. But this implies that  $\Phi(\mathbf{a})$  has  $C'$  gap.  $\square$

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## Sharp Gaps are Essential

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A gap in  $\mathbb{G}_r(\mathbf{a})$  is **sharp** if, for all  $R \geq r \geq 0$ , there exists constant  $K = K(R, r) \in \mathbb{N}$  such that, for any  $\mathbf{y} \in \mathbb{G}_r(\mathbf{a})$ ,  $\exists \mathbf{x} \in \mathbb{G}_R(\mathbf{a})$  in same connected component  $\mathbb{X}$  of  $\mathbb{G}_r(\mathbf{a})$  as  $\mathbf{y}$ , with  $d_{\mathbb{X}}(\mathbf{x}, \mathbf{y}) \leq K$ .

**Idea:** The gap does not ramify into lots of ‘tributaries’.

**Example:** If  $\mathfrak{A}$  is a subshift of finite type, and defect set  $\mathbb{D}(\mathbf{a})$  is confined to a thickened hyperplane [as in previous three examples] then the gap is sharp.

**Theorem:** *Sharp gaps are essential defects.*

**Proof idea:** First show:

**Lemma:** *The existence of a gap does not depend on the choice of reference points  $\mathbf{x}^* \in \mathbb{X}$  and  $\mathbf{y}^* \in \mathbb{Y}$ .* ◇

Thus, we can always move our basepoint  $\mathbf{x}^*$  and ‘gap-detection’ sequence  $\{\mathbf{x}_1, \mathbf{x}_2, \dots\}$  far away from gap. Thus, a gap is ‘detectable’ from any distance; hence it cannot be removed by locally changing  $\mathbf{a}$ . □

## Defect Codimension

A domain boundary is a defect of **codimension 1**.

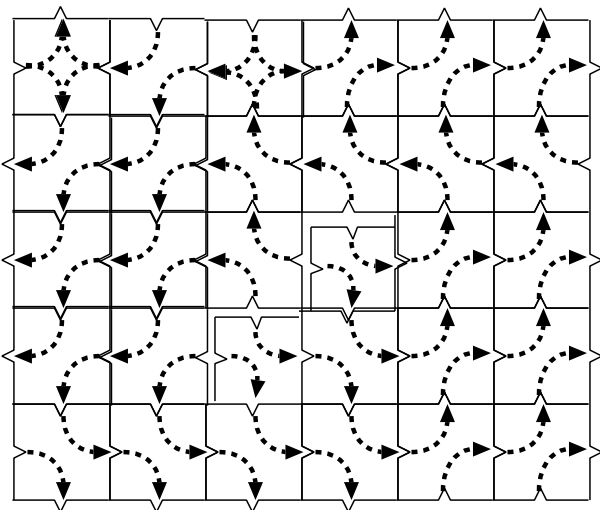
Fix  $r \in \mathbb{N}$ . Let  $\mathbb{G}_r(\mathbf{a}) := \{\mathbf{z} \in \mathbb{Z}^D ; \mathbf{a}_{\mathbb{B}(\mathbf{z}, r)} \in \mathfrak{A}_{(r)}\}$ . (Loosely, this is the complement of a radius- $r$  neighbourhood around the defects in  $\mathbf{a}$ .)

Let  $\mathbf{G}_r(\mathbf{a}) :=$  union of all unit cubes whose corners are all in  $\mathbb{G}_r(\mathbf{a})$ .

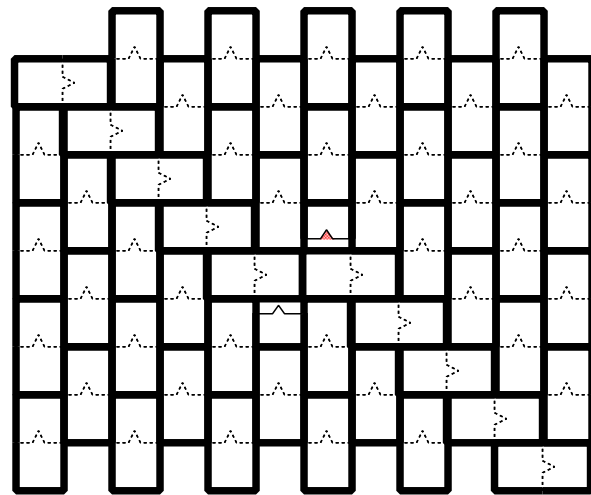
We say  $\mathbf{a}$  has a (range  $r$ ) **codimension**  $(k + 1)$  defect if the  $k$ th homotopy group  $\pi_k[\mathbf{G}_r(\mathbf{a})]$  is nontrivial<sup>(\*)</sup>.

### Examples of Codimension-Two Defects:

In  $\mathfrak{I}_{ce}$ :



In  $\mathfrak{D}_{om}$ :



[due to S. Lightwood, via M. Einsiedler, 2001]

The sequence of inclusions  $\mathbb{G}_1(\mathbf{a}) \supseteq \mathbb{G}_2(\mathbf{a}) \supseteq \mathbb{G}_3(\mathbf{a}) \supseteq \dots$  yields sequence of homomorphisms

$$\pi_k[\mathbf{G}_1(\mathbf{a})] \longleftarrow \pi_k[\mathbf{G}_2(\mathbf{a})] \longleftarrow \pi_k[\mathbf{G}_3(\mathbf{a})] \longleftarrow \dots$$

Define  $\pi_k[\mathbf{G}_\infty(\mathbf{a})] :=$  inverse limit of this sequence<sup>(†)</sup> (detects ‘extremely large scale’ homotopy properties).

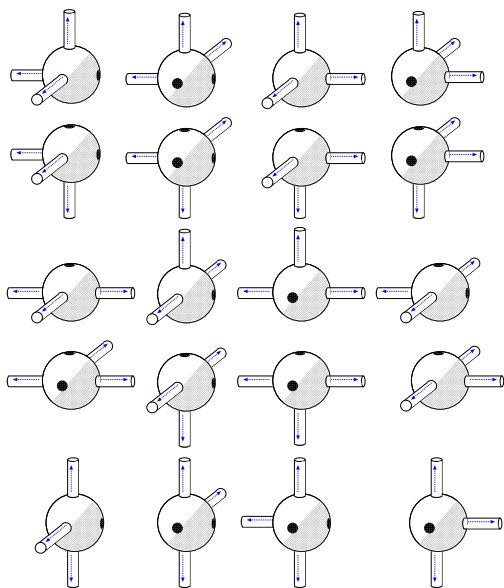
Say  $\mathbf{a}$  has a **projective** codimension  $(k + 1)$  defect if  $\pi_k[\mathbf{G}_\infty(\mathbf{a})] \neq \{0\}$ .

(\*) Strictly speaking, we must fix a basepoint and a connected component of  $\mathbf{G}_r$ .

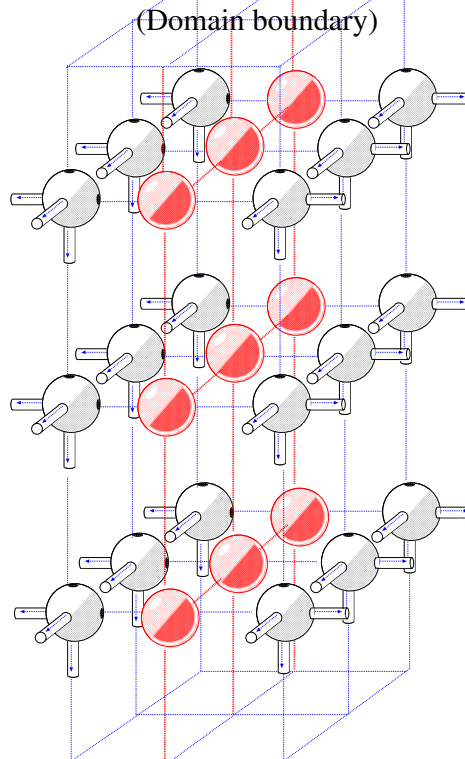
(†) We must fix a *proper base ray*, and assume  $\mathbf{G}_r$  has unique connected component for large  $r$ .

## Defect Codimension in 3D

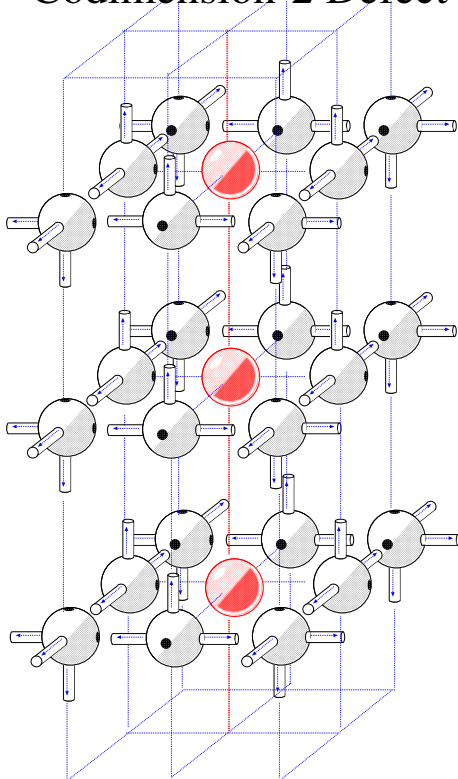
The 'Ice Cube' Shift:



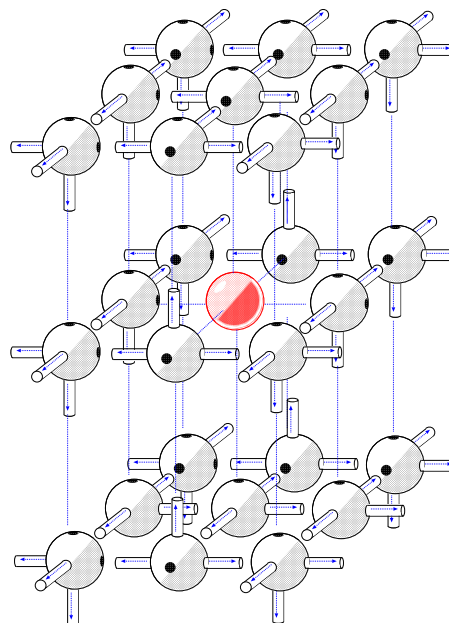
Codimension-1 Defect  
(Domain boundary)



Codimension-2 Defect



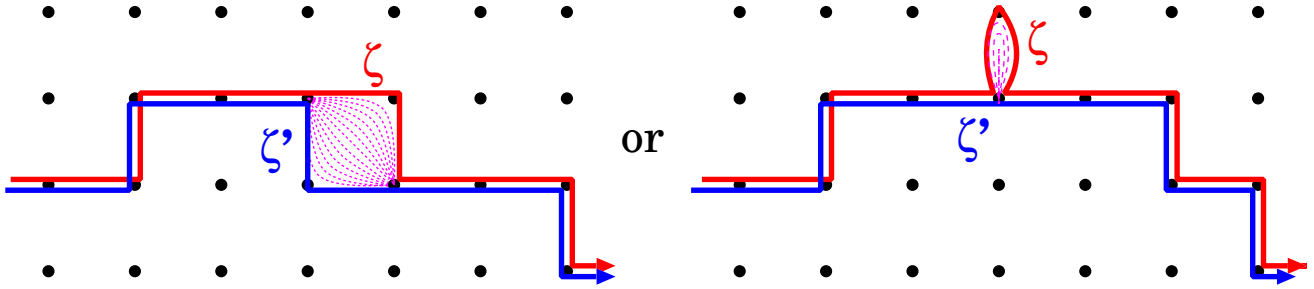
Codimension-3 Defect



## Trail Homotopy

Let  $\mathbb{Y} \subseteq \mathbb{Z}^D$  and let  $\zeta$  and  $\zeta'$  be trails in  $\mathbb{Y}$ .

$\zeta$  and  $\zeta'$  are **homotopic in  $\mathbb{Y}$**  (notation:  $\zeta \approx \zeta'$ ) if we can move from  $\zeta$  to  $\zeta'$  through a sequence of transformations like:



If  $\mathbb{Y}$  is connected, then every homotopy class of  $\pi_1(\mathbb{Y})$  can be represented as a (trail) homotopy class of trails in  $\mathbb{Y}$ .

Hence regard  $\pi_1(\mathbb{Y}) = \{\text{group of } \mathbb{Y}\text{-homotopy classes of } \mathbb{Y}\text{-trails}\}$ .

**Lemma:** Let  $C \in \mathcal{Z}_r^1(\mathfrak{A}, \mathcal{G})$ . Let  $\mathbf{a} \in \tilde{\mathfrak{A}}$ . Let  $\zeta$  be closed trail in  $\mathbb{G}_r(\mathbf{a})$ .

(a) If  $\zeta \approx \zeta'$  in  $\mathbb{G}_r(\mathbf{a})$ , then  $C(\zeta, \mathbf{a}) = C(\zeta', \mathbf{a})$ .

(e.g. If  $\zeta$  is nullhomotopic in  $\mathbb{G}_r(\mathbf{a})$ , then  $C(\zeta, \mathbf{a}) = e_{\mathcal{G}}$ .)

(b) Suppose  $(\mathcal{G}, \cdot)$  is abelian. If  $C \approx C'$  then  $C(\zeta, \mathbf{a}) = C'(\zeta, \mathbf{a})$ . □

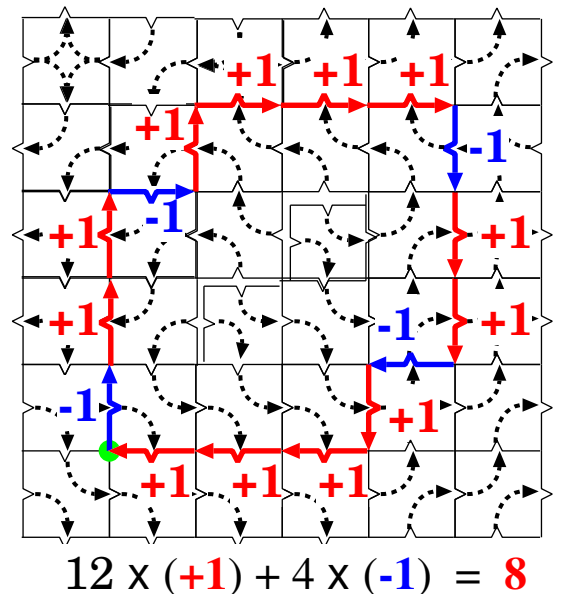
We say that  $\mathbf{a}$  has a **C-pole** if  $C(\zeta, \mathbf{a}) \neq e_{\mathcal{G}}$  for some closed trail  $\zeta \in \pi_1[\mathbb{G}_r(\mathbf{a})]$ .

**Example:** Recall  $C : \mathfrak{J}_{ce} \times \mathbb{Z}^2 \rightarrow \mathbb{Z}$

$$c_1\left(\begin{matrix} * & * \\ * & \frown \\ * & * \end{matrix}\right) := +1 =: c_2\left(\begin{matrix} * \\ \swarrow \\ * \\ * \end{matrix}\right)$$

$$c_1\left(\begin{matrix} * & * \\ * & \smile \\ * & * \end{matrix}\right) := -1 =: c_2\left(\begin{matrix} * \\ \searrow \\ * \\ * \end{matrix}\right)$$

If  $\zeta$  is the clockwise trail around the defect, then  $C(\zeta, \mathbf{a}) = 8$ . Thus,  $\mathbf{a}$  has a pole.



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## Poles and Residues

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**Proposition:** Let  $\mathbf{a} \in \tilde{\mathfrak{A}}$ . Let  $C \in \mathcal{Z}_r^1(\mathfrak{A}, \mathcal{G})$ .

- (a)  $\text{Res}_{\mathbf{a}}C : \pi_1[\mathbb{G}_r(\mathbf{a})] \ni \underline{\zeta} \mapsto C(\zeta, a) \in \mathcal{G}$  is a group homomorphism.
- (b) If  $(\mathcal{G}, \cdot)$  is abelian, and  $C \approx C'$  then  $\text{Res}_{\mathbf{a}}C = \text{Res}_{\mathbf{a}}C'$ . Thus, we get group homomorphism

$$\text{Res}_{\mathbf{a}} : \mathcal{H}_{\text{dy}}(\mathfrak{A}, \mathcal{G}) \times \pi_1[\mathbb{G}_{\infty}(\mathbf{a})] \ni (\underline{C}, \underline{\zeta}) \mapsto C(\zeta, a) \in \mathcal{G}. \quad \square$$

The configuration  $\mathbf{a}$  has a  **$\mathcal{G}$ -pole** if  $\text{Res}_{\mathbf{a}}$  is nontrivial homomorphism. The function  $\text{Res}_{\mathbf{a}}$  acts as an algebraic ‘signature’ of the defect in  $\mathbf{a}$ .

**Theorem:**  $\mathcal{G}$ -poles are essential defects. □

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## Persistence of Poles

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**Theorem:** If the function  $\Phi_* : \mathcal{H}^1(\mathfrak{A}, \mathcal{G}) \ni C \mapsto (C \circ \Phi) \in \mathcal{H}^1(\mathfrak{A}, \mathcal{G})$  is surjective, then all  $\mathcal{G}$ -poles are  $\Phi$ -persistent.

**Example:** If  $\Phi : \mathcal{I}^{\mathbb{Z}^2} \longrightarrow \mathcal{I}^{\mathbb{Z}^2}$  was a CA with  $\Phi(\mathfrak{I}_{\text{ce}}) \subseteq \Phi(\mathfrak{I}_{\text{ce}})$ , and  $\Phi_*$  was surjective, then the ice pole would persist under  $\Phi$ . ◇

**Proof idea:** Let  $R := \text{radius}(\Phi)$ . If  $\mathbf{a} \in \tilde{\mathfrak{A}}$  and  $\mathbf{a}' := \Phi(\mathbf{a})$ , then  $\mathbb{G}_{r+R}(\mathbf{a}) \subseteq \mathbb{G}_r(\mathbf{a}')$ .

This yields homomorphisms  $\Phi_{\dagger} : \pi_1[\mathbb{G}_{r+R}(\mathbf{a})] \longrightarrow \pi_1[\mathbb{G}_r(\mathbf{a}')]$ , for all  $r \in \mathbb{N}$ .

**Lemma:** For all  $\zeta \in \pi_1[\mathbb{G}_{r+R}(\mathbf{a})]$  and  $C' \in \mathcal{Z}_r^1(\mathfrak{A}, \mathcal{G})$ , if  $\zeta' := \Phi_{\dagger}(\zeta)$  and  $C \approx \Phi_*(C')$ , then  $C'(\mathbf{a}', \zeta') = C(\mathbf{a}, \zeta)$ . ◇

Now, if  $\mathbf{a}$  has a  $C$ -pole for some  $C \in \mathcal{Z}^1(\mathfrak{A}, \mathcal{G})$ , then there exists  $\zeta \in \pi_1[\mathbb{G}_{r+R}(\mathbf{a})]$  with  $C(\mathbf{a}, \zeta)$  nontrivial.

$\Phi_*$  is surjective, so  $\exists C' \in \mathcal{Z}^1(\mathfrak{A}, \mathcal{G})$  with  $\Phi_*C' \approx C$ . Let  $\zeta' := \Phi_{\dagger}(\zeta) \in \pi_1[\mathbb{G}_r(\mathbf{a}')]$ . Then  $C'(\mathbf{a}', \zeta') = C(\mathbf{a}, \zeta)$  is nontrivial. Thus  $\mathbf{a}'$  has a  $C'$ -pole. □

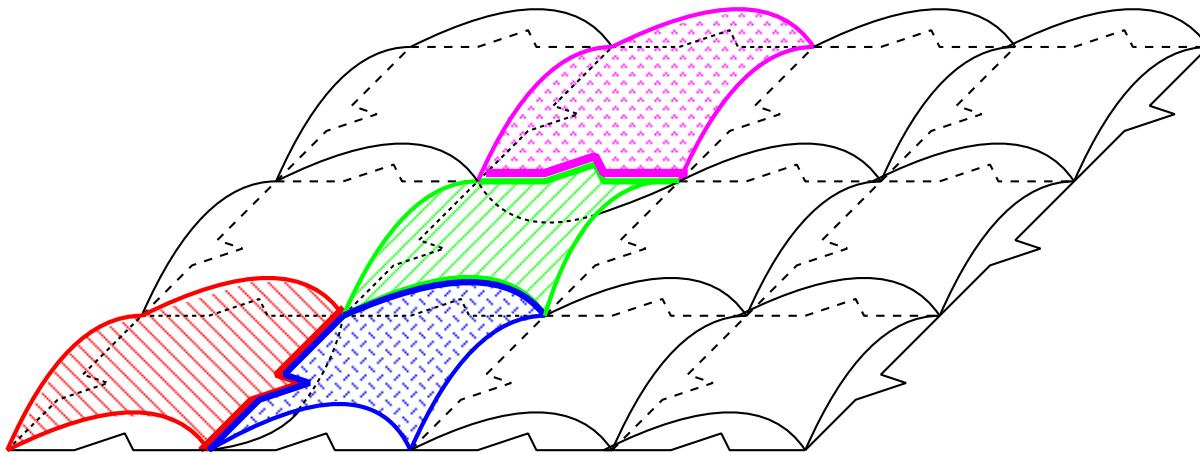
**Remark:** We can also characterize poles using the *fundamental cocycles* of [K.Schmidt, 1998].

## The Conway-Lagarias Tiling Group

Let  $\mathcal{W}$  be a (finite) set of notched square prototiles (to tile  $\mathbb{R}^2$ ). The **tile complex** of  $\mathcal{W}$  is a 2-dimensional cell complex  $\mathbf{X}$  defined as follows:

- For each  $\mathbf{z} \in \mathbb{Z}^D$  and each  $w \in \mathcal{W}$ , there is a  $w$ -shaped 2-cell in  $\mathbf{X}$ , positioned in space ‘over’  $\mathbf{z}$ . Each notched edge of  $w$  is a 1-cell in  $\mathbf{X}$ .
- If  $\mathbf{z}$  and  $\mathbf{z}'$  are adjacent in  $\mathbb{Z}^2$ , and tiles  $w$  and  $w'$  ‘match’ along the corresponding edge, then glue together tiles  $(w, \mathbf{z})$  and  $(w', \mathbf{z}')$  in  $\mathbf{X}$ .

**Example:** (Piece of tile-complex for  $\mathcal{D}_{\text{om}}$ ). Each square contains four 2-cells  $\left\{ \square, \square, \square, \square \right\}$ . Between each vertex-pair  $\exists$  two edges  $\{ |, \rangle \}$ .



$\exists$  natural projection  $\Pi : \mathbf{X} \rightarrow \mathbb{R}^2$  (sending the vertices of  $\mathbf{X}^0$  into  $\mathbb{Z}^2$ ).

$$\begin{aligned} \left( \text{Admissible } \mathcal{W}\text{-tiling } \mathbf{w} \text{ of } \mathbb{R}^2 \right) &\cong \left( \text{Continuous } \Pi\text{-section } \varsigma_{\mathbf{w}} : \mathbb{R}^2 \rightarrow \mathbf{X} \right) \\ \left( \text{'Partial' } \mathcal{W}\text{-tiling } \mathbf{w} \text{ of } \mathbf{U} \subset \mathbb{R}^2 \right) &\cong \left( \text{'Partial' } \Pi\text{-section } \varsigma_{\mathbf{w}} : \mathbf{U} \rightarrow \mathbf{X} \right) \end{aligned}$$

In the second case,  $\varsigma_{\mathbf{w}}$  defines homomorphism  $\varsigma_{\mathbf{w}}^* : \pi_1(\mathbf{U}) \rightarrow \pi_1(\mathbf{X})$ . Then:

$$\begin{aligned} \left( \mathbf{U}^{\text{c}}\text{-hole in } \mathbf{w} \text{ can be admissibly filled} \right) &\implies \\ \left( \varsigma_{\mathbf{w}}^*\text{-image of any loop in } \mathbf{U} \text{ is nullhomotopic} \right) &\iff \left( \varsigma_{\mathbf{w}}^* \text{ is trivial} \right). \end{aligned}$$

$\pi_1(\mathbf{X}) = \text{'tile homotopy group'}$  [J.H.Conway & J.C.Lagarias, 1990; W.Thurston, 1990]

— **Higher homotopy/homology groups for Wang tiles** —

Let  $\mathcal{W}$  be a (finite) set of  $D$ -dimensional notched hypercubic **Wang tiles** (to tile  $\mathbb{R}^D$ ). Build a  $D$ -dimensional cell complex  $\mathbf{X}$  analogous to before. Get projection  $\Pi : \mathbf{X} \rightarrow \mathbb{R}^D$  such that  $\Pi(\mathbf{X}^0) = \mathbb{Z}^D$ .

$$\left( \text{Admissible } \mathcal{W}\text{-tiling } \mathbf{w} \text{ of } \mathbb{R}^D \right) \cong \left( \text{Continuous } \Pi\text{-section } \varsigma_{\mathbf{w}} : \mathbb{R}^D \rightarrow \mathbf{X} \right).$$

$$\left( \text{'Partial' } \mathcal{W}\text{-tiling } \mathbf{w} \text{ of } \mathbf{U} \subset \mathbb{R}^D \right) \cong \left( \text{'Partial' } \Pi\text{-section } \varsigma_{\mathbf{w}} : \mathbf{U} \rightarrow \mathbf{X} \right).$$

In this case, for all  $k \in \mathbb{N}$ , the section  $\varsigma_{\mathbf{w}}$  defines homomorphisms:

$$\pi_{k\varsigma_{\mathbf{w}}} : \pi_k(\mathbf{U}, u) \longrightarrow \pi_k(\mathbf{X}, x); \quad (x, u = \text{suitable basepoints})$$

$$\mathcal{H}_{k\varsigma_{\mathbf{w}}} : \mathcal{H}_k(\mathbf{U}, \mathcal{G}) \longrightarrow \mathcal{H}_k(\mathbf{X}, \mathcal{G}); \quad ((\mathcal{G}, +) = \text{some coefficient group, e.g. } \mathcal{G} = \mathbb{Z})$$

$$\mathcal{H}^k_{\varsigma_{\mathbf{w}}} : \mathcal{H}^k(\mathbf{U}, \mathcal{G}) \longrightarrow \mathcal{H}^k(\mathbf{X}, \mathcal{G})$$

$$\left( \text{Hole in } \mathbf{w} \text{ is fillable} \right) \implies \left( \pi_{k\varsigma_{\mathbf{w}}}, \mathcal{H}_{k\varsigma_{\mathbf{w}}} \text{ and } \mathcal{H}^k_{\varsigma_{\mathbf{w}}} \text{ are trivial, } \forall k \in \mathbb{N} \right).$$

– **Homotopy/homology groups for subshifts of finite type** –

Let  $\mathcal{A}$  be a finite alphabet. Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}^D}$  be a subshift of finite type of radius  $r > 0$ . Fix  $R \geq r$ . Treat  $\mathcal{W} := \mathfrak{A}_{(R)}$  as Wang tiles with obvious edge-matching conditions. Get tile complex  $\mathbf{X}_R$ . Then:

$$\left( \mathbf{a} \in \mathfrak{A} \right) \cong \left( \mathcal{W}\text{-admissible tiling of } \mathbb{R}^D \right) \cong \left( \Pi\text{-section } \varsigma_{\mathbf{a}} : \mathbb{R}^D \rightarrow \mathbf{X}_R \right).$$

**Idea:** Use homotopy/(co)homology groups of  $\mathbf{X}_R$  as invariant for  $\mathfrak{A}$  (and get algebraic invariants for codimension- $(k+1)$  defects in  $\tilde{\mathfrak{A}}$ ).

**Problems:**

[i] There  $\exists$  many different Wang representations for  $\mathfrak{A}$ . None is ‘canonical’. Different Wang representations may yield non-isomorphic groups.

[ii] Wang representations (and hence, their homotopy/homology groups) do not behave well under subshift homomorphisms (i.e. CA).

## \_\_\_\_\_The Geller-Propp Projective Fundamental Group \_\_\_\_\_

**Solution:** There are natural surjections  $\mathbf{X}_r \leftarrow \mathbf{X}_{r+1} \leftarrow \mathbf{X}_{r+2} \leftarrow \cdots$

Get homomorphisms  $\pi_k(\mathbf{X}_r, x_r) \leftarrow \pi_k(\mathbf{X}_{r+1}, x_{r+1}) \leftarrow \pi_k(\mathbf{X}_{r+2}, x_{r+2}) \leftarrow \cdots$

(Here,  $\{x_k\}$  are basepoints determined by some fixed  $\mathbf{a} \in \mathfrak{A}$ .)

Define  $k$ th **projective homotopy group**  $\pi_k(\mathfrak{A}, \mathbf{a}) :=$  inverse limit of this sequence. (If  $k = 1$  this is the *projective fundamental group* of W.Geller & J.Propp, 1995).

Likewise, we define  $k$ th **projective (co)homology groups**

$$\mathcal{H}_k(\mathfrak{A}, \mathcal{G}) := \varprojlim (\mathcal{H}_k(\mathbf{X}_r, \mathcal{G}) \leftarrow \mathcal{H}_k(\mathbf{X}_{r+1}, \mathcal{G}) \leftarrow \mathcal{H}_k(\mathbf{X}_{r+2}, \mathcal{G}) \leftarrow \cdots)$$

$$\mathcal{H}^k(\mathfrak{A}, \mathcal{G}) := \varinjlim (\mathcal{H}^k(\mathbf{X}_r, \mathcal{G}) \rightarrow \mathcal{H}^k(\mathbf{X}_{r+1}, \mathcal{G}) \rightarrow \mathcal{H}^k(\mathbf{X}_{r+2}, \mathcal{G}) \rightarrow \cdots)$$

- Isomorphism invariants of  $\mathfrak{A}$ .
- Detects codimension  $(k+1)$  defects.

## \_\_\_\_\_Basepoint Freedom \_\_\_\_\_

The definition of  $\pi_k(\mathfrak{A})$  depends upon a chosen ‘basepoint’  $\mathbf{a} \in \mathfrak{A}$ .

We say  $\mathfrak{A}$  is **basepoint free** in dimension  $k$  if, for any  $\mathbf{a}, \mathbf{a}' \in \mathfrak{A}$ , there is a canonical isomorphism  $\pi_k(\mathfrak{A}, \mathbf{a}) \cong \pi_k(\mathfrak{A}, \mathbf{a}')$ .

### Proposition:

- (a) Suppose  $\Pi_r^0 : \mathbf{X}_r^0 \rightarrow \mathbb{Z}^D$  is injective for all large enough  $r \in \mathbb{N}$ .  
Then  $\mathfrak{A}$  is basepoint-free in all dimensions.

Suppose  $(\mathfrak{A}, \sigma)$  is topologically weakly mixing [i.e. the Cartesian product  $(\mathfrak{A} \times \mathfrak{A}, \sigma \times \sigma)$  is topologically transitive]. Then:

- (b) If  $\pi_1(\mathfrak{A}, \mathbf{a})$  is abelian, then  $\mathfrak{A}$  is basepoint free in dimension 1.  
(c) If  $\pi_1(\mathfrak{A}, \mathbf{a})$  is trivial, then  $\mathfrak{A}$  is basepoint free in all dimensions.  $\square$



\_\_\_\_\_Projective Groups and Cellular Automata\_\_\_\_\_

**Proposition:** Let  $\Phi: \mathcal{A}^{\mathbb{Z}^D} \longrightarrow \mathcal{A}^{\mathbb{Z}^D}$  be a CA with  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ . Then  $\Phi$  induces group endomorphisms:

$$\begin{aligned} \pi_{\mathfrak{d}}\Phi: \pi_{\mathfrak{d}}(\mathfrak{A}, \mathbf{a}) &\longrightarrow \pi_{\mathfrak{d}}(\mathfrak{A}, \mathbf{a}') \quad (\cong \pi_{\mathfrak{d}}(\mathfrak{A}, \mathbf{a}) \text{ if basepoint free}) \\ \mathcal{H}_{\mathfrak{d}}\Phi: \mathcal{H}_{\mathfrak{d}}(\mathfrak{A}, \mathcal{G}) &\longrightarrow \mathcal{H}_{\mathfrak{d}}(\mathfrak{A}, \mathcal{G}) \\ \mathcal{H}^{\mathfrak{d}}\Phi: \mathcal{H}^{\mathfrak{d}}(\mathfrak{A}, \mathcal{G}) &\longrightarrow \mathcal{H}^{\mathfrak{d}}(\mathfrak{A}, \mathcal{G}). \end{aligned}$$

*Proof:* (Idea) If  $\Phi$  has radius  $q$ , then  $\Phi$  induces a cellular map  $\Phi_*: \mathbf{X}_{R+q} \longrightarrow \mathbf{X}_R$  for all  $R \geq r$ , which yields corresponding homotopy/(co)homology homomorphisms. The resulting infinite commuting ladder of homomorphisms defines a homomorphism of the inverse/direct limit groups.  $\square$

Recall that  $\pi_{\mathbf{k}}[\mathbb{G}_{\infty}(\mathbf{a})] :=$  inverse limit of  $\pi_{\mathbf{k}}[\mathbb{G}_r(\mathbf{a})]$  as  $r \rightarrow \infty$ .

Likewise define  $\mathcal{H}^{\mathbf{k}}[\mathbb{G}_{\infty}(\mathbf{a})]$  (direct limit) and  $\mathcal{H}_{\mathbf{k}}[\mathbb{G}_{\infty}(\mathbf{a})]$  (inverse limit),  $\forall k \in \mathbb{N}$ .

If  $\mathbf{a} \in \tilde{\mathfrak{A}}$ , then  $\mathbf{a}$  defines ‘partial’  $\Pi$ -section  $\varsigma_{\mathbf{a}}: \mathbf{G}_R(\mathbf{a}) \longrightarrow \mathbf{X}_R$  for all  $R \geq r$ . This induces group homomorphisms:

$$\begin{aligned} \mathcal{H}_{\mathbf{k}}\mathbf{a}: \mathcal{H}_{\mathbf{k}}[\mathbb{G}_R(\mathbf{a}), \mathcal{G}] &\longrightarrow \mathcal{H}_{\mathbf{k}}(\mathbf{X}_R, \mathcal{G}); \\ \mathcal{H}^{\mathbf{k}}\mathbf{a}: \mathcal{H}^{\mathbf{k}}(\mathbf{X}_R, \mathcal{G}) &\longrightarrow \mathcal{H}^{\mathbf{k}}[\mathbb{G}_R(\mathbf{a}), \mathcal{G}]; \\ \pi_{\mathbf{k}}\mathbf{a}: \pi_{\mathbf{k}}[\mathbb{G}_R(\mathbf{a})] &\longrightarrow \pi_{\mathbf{k}}(\mathbf{X}_R). \end{aligned}$$

The resulting infinite commuting ladders of homomorphisms define homomorphisms of the inverse/direct limit groups. Thus, we have:

**Theorem:** (a) Any  $\mathbf{a} \in \tilde{\mathfrak{A}}$  induces group homomorphisms:

$$\mathcal{H}_{\mathbf{k}}\mathbf{a}: \mathcal{H}_{\mathbf{k}}[\mathbb{G}_{\infty}(\mathbf{a}), \mathcal{G}] \longrightarrow \mathcal{H}_{\mathbf{k}}(\mathfrak{A}, \mathcal{G}) \text{ and } \mathcal{H}^{\mathbf{k}}\mathbf{a}: \mathcal{H}^{\mathbf{k}}(\mathfrak{A}, \mathcal{G}) \longrightarrow \mathcal{H}^{\mathbf{k}}[\mathbb{G}_{\infty}(\mathbf{a}), \mathcal{G}].$$

(b) If  $\mathfrak{A}$  is basepoint-free in dimension  $k$ , then  $\mathbf{a}$  also induces a group homomorphism  $\pi_{\mathbf{k}}\mathbf{a}: \pi_{\mathbf{k}}[\mathbb{G}_{\infty}(\mathbf{a})] \longrightarrow \pi_{\mathbf{k}}(\mathfrak{A})$ .

We call  $\pi_{\mathbf{k}}\mathbf{a}$  (resp.  $\mathcal{H}_{\mathbf{k}}\mathbf{a}$  or  $\mathcal{H}^{\mathbf{k}}\mathbf{a}$ ) the  **$k$ th homotopy** (resp. **(co)homology signature**) of  $\mathbf{a}$ ; if it is nontrivial, we say  $\mathbf{a}$  has a **homotopy** (resp. **(co)homology defect**) of codimension  $(k + 1)$ .

\_\_\_\_\_Persistence of Homotopy/(co)homology Defects \_\_\_\_\_

**Theorem:** Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}^D}$  be SFT. Let  $\Phi: \mathcal{A}^{\mathbb{Z}^D} \rightarrow \mathcal{A}^{\mathbb{Z}^D}$  be CA with  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ .

- (a) Suppose  $\mathfrak{A}$  is basepoint-free in dimension  $k$ . If  $\pi_k \Phi: \pi_k(\mathfrak{A}) \rightarrow \pi_k(\mathfrak{A})$  is injective, then every homotopy defect of codimension  $(k+1)$  is  $\Phi$ -persistent.
- (b) If  $\mathcal{H}_k \Phi: \mathcal{H}_k(\mathfrak{A}, \mathcal{G}) \rightarrow \mathcal{H}_k(\mathfrak{A}, \mathcal{G})$  is injective, then every homology defect of codimension  $(k+1)$  is  $\Phi$ -persistent.
- (c) If  $\mathcal{H}^k \Phi: \mathcal{H}^k(\mathfrak{A}, \mathcal{G}) \rightarrow \mathcal{H}^k(\mathfrak{A}, \mathcal{G})$  is surjective, then every cohomology defect of codimension  $(k+1)$  is  $\Phi$ -persistent.  $\square$

This follows from:

**Theorem:** Let  $\Phi: \mathcal{A}^{\mathbb{Z}^D} \rightarrow \mathcal{A}^{\mathbb{Z}^D}$  be a CA with  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ . Let  $\mathbf{a} \in \tilde{\mathfrak{A}}$  and let  $\Phi(\mathbf{a}) = \mathbf{b}$ . Then we have commuting diagrams:

$$\begin{array}{ccccccc}
 \mathcal{H}_k[\mathbb{G}_\infty(\mathbf{a}), \mathcal{G}] & \xrightarrow{\mathcal{H}_k \iota} & \mathcal{H}_k[\mathbb{G}_\infty(\mathbf{b}), \mathcal{G}] & & \mathcal{H}^k[\mathbb{G}_\infty(\mathbf{a}), \mathcal{G}] & \xleftarrow{\mathcal{H}^k \iota} & \mathcal{H}^k[\mathbb{G}_\infty(\mathbf{b}), \mathcal{G}] \\
 \mathcal{H}_k \mathbf{a} \downarrow & & \downarrow \mathcal{H}_k \mathbf{b} & & \mathcal{H}^k \mathbf{a} \uparrow & & \uparrow \mathcal{H}^k \mathbf{b} \\
 \mathcal{H}_k(\mathfrak{A}, \mathcal{G}) & \xrightarrow{\mathcal{H}_k \Phi} & \mathcal{H}_k(\mathfrak{A}, \mathcal{G}) & & \mathcal{H}^k(\mathfrak{A}, \mathcal{G}) & \xleftarrow{\mathcal{H}^k \Phi} & \mathcal{H}^k(\mathfrak{A}, \mathcal{G})
 \end{array}$$

If  $\mathfrak{A}$  is basepoint-free, we also get a commuting diagram:

$$\begin{array}{ccc}
 \pi_k[\mathbb{G}_\infty(\mathbf{a}), \omega] & \xrightarrow{\pi_k \iota} & \pi_k[\mathbb{G}_\infty(\mathbf{b}), \omega] \\
 \pi_k \mathbf{a} \downarrow & & \downarrow \pi_k \mathbf{b} \\
 \pi_k(\mathfrak{A}) & \xrightarrow{\pi_k \Phi} & \pi_k(\mathfrak{A})
 \end{array}$$

*Proof:* (Idea) Stick together all the aforementioned infinite commuting ladders to get infinite commuting ‘girder’, which yields commuting square of inverse limit homomorphisms.  $\square$

$$\begin{array}{ccccccc}
\pi_d[\mathbb{G}_{q+R}(\mathbf{a})] & \xrightarrow{\alpha_{q+R}^*} & \pi_d[\mathbb{G}_{q+R+1}(\mathbf{a})] & \xrightarrow{\alpha_{q+R+1}^*} & \pi_d[\mathbb{G}_{q+R+2}(\mathbf{a})] & \xrightarrow{\alpha_{q+R+2}^*} & \dots & \xrightarrow{\alpha_{q+R+2}^*} & \pi_d[\mathbb{G}_\infty(\mathbf{a})] \\
\searrow \iota_{R+R}^* & & \searrow \iota_{R+R+1}^* & & \searrow \iota_{R+R+2}^* & & \searrow \iota_{R+R+2}^* & & \searrow \iota_{R+R+2}^* \\
\pi_d[\mathbb{G}_{q+R}(\mathbf{b})] & \xrightarrow{\beta_R^*} & \pi_d[\mathbb{G}_{q+R+1}(\mathbf{b})] & \xrightarrow{\beta_{R+1}^*} & \pi_d[\mathbb{G}_{q+R+2}(\mathbf{b})] & \xrightarrow{\beta_{R+2}^*} & \dots & \xrightarrow{\beta_{R+2}^*} & \pi_d[\mathbb{G}_\infty(\mathbf{b})] \\
\downarrow \pi_d^{q+R} \mathbf{a} & \downarrow \pi_d^{q+R+1} \mathbf{a} & \downarrow \pi_d^{q+R+1} \mathbf{a} & \downarrow \pi_d^{q+R+2} \mathbf{a} & \downarrow \pi_d^{q+R+2} \mathbf{a} & \downarrow \pi_d^{q+R+2} \mathbf{a} & \downarrow \pi_d^{q+R+2} \mathbf{a} & \downarrow \pi_d^{q+R+2} \mathbf{a} & \downarrow \pi_d^{q+R+2} \mathbf{a} \\
\pi_d^{q+R}(\mathfrak{A}) & \xrightarrow{\zeta_{q+R}^*} & \pi_d^{q+R+1}(\mathfrak{A}) & \xrightarrow{\zeta_{q+R+1}^*} & \pi_d^{q+R+1}(\mathfrak{A}) & \xrightarrow{\zeta_{q+R+1}^*} & \pi_d^{q+R+2}(\mathfrak{A}) & \xrightarrow{\zeta_{q+R+2}^*} & \pi_d^{q+R+2}(\mathfrak{A}) \\
\downarrow \pi_d^{R+R} \Phi & \downarrow \pi_d^{R+R+1} \Phi & \downarrow \pi_d^{R+R+1} \Phi & \downarrow \pi_d^{R+R+2} \Phi & \downarrow \pi_d^{R+R+2} \Phi & \downarrow \pi_d^{R+R+2} \Phi & \downarrow \pi_d^{R+R+2} \Phi & \downarrow \pi_d^{R+R+2} \Phi & \downarrow \pi_d^{R+R+2} \Phi \\
\pi_d^R(\mathfrak{A}) & \xrightarrow{\zeta_R^*} & \pi_d^{R+1}(\mathfrak{A}) & \xrightarrow{\zeta_{R+1}^*} & \pi_d^{R+2}(\mathfrak{A}) & \xrightarrow{\zeta_{R+2}^*} & \dots & \xrightarrow{\zeta_{R+2}^*} & \pi_d(\mathfrak{A})
\end{array}$$

## Equivariant (co)Homology

**Question:** *Is there a higher-codimension analog to the codimension-2 ‘poles’ from dynamical cohomology?*

Let  $k \in \mathbb{N}$ . A (cubic)  **$k$ -chain** is a formal ‘sum’ of  $k$ -dimensional cubes in  $\mathbb{R}^D$  with vertices in  $\mathbb{Z}^D$  (combinatorial analog of ‘ $k$ -dimensional submanifold’). Fix an abelian group  $(\mathcal{G}, +)$ . Define  $\mathcal{C}_k := \{\text{free abelian group of cubic } k\text{-chains}\}$ .

$$\mathcal{C}^k(\mathcal{G}) := \{(\text{cubic } k\text{-cochains})\} = \{\text{homomorphisms } c : \mathcal{C}_k \longrightarrow \mathcal{G}\}.$$

(combinatorial analog of ‘ $k$ -dimensional differential forms’).

$\mathbb{Z}^D$  acts on  $\mathbb{R}^D$  by shifts. This induces  $\mathbb{Z}^D$ -action on  $\mathcal{C}_k$ , and thus on  $\mathcal{C}^k$ .

Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}^D}$  be subshift. An **equivariant cochain** on  $\mathfrak{A}$  is a continuous function  $C : \mathfrak{A} \longrightarrow \mathcal{Z}^k(\mathcal{G})$  which commutes with all  $\mathbb{Z}^D$ -shifts.

**Idea:** For any  $\mathbf{a} \in \mathfrak{A}$ ,  $C(\mathbf{a})$  is a cochain. If  $\zeta \in \mathcal{C}_k$  is any chain, then

$$C(\sigma^z(\mathbf{a}))[\zeta] = C(\mathbf{a})[\sigma^z(\zeta)].$$

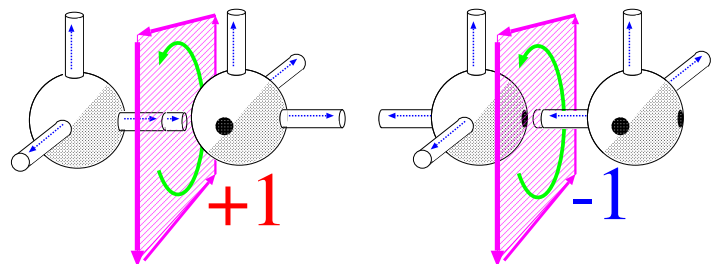
Let  $\mathcal{C}_{\text{eq}}^k(\mathfrak{A}, \mathcal{G}) := \{\text{equivariant } k\text{-chains}\}$ . There is a natural **coboundary** operator  $\delta^k : \mathcal{C}_{\text{eq}}^k \longrightarrow \mathcal{C}_{\text{eq}}^{k+1}$ . Let  $\mathcal{Z}_{\text{eq}}^k := \ker(\delta^k)$  be the group of **equivariant cocycles**.

**Examples:** (a) Recall that a ‘dynamical’ cocycle is a function  $c : \mathbb{Z}^D \times \mathfrak{A} \longrightarrow \mathcal{G}$  such that

$$c(\mathbf{y} + \mathbf{z}, \mathbf{a}) = c[\mathbf{y}, \sigma^z(\mathbf{a})] + c(\mathbf{z}, \mathbf{a}).$$

Any dynamical cocycle defines an equivariant cocycle  $C \in \mathcal{Z}_{\text{eq}}^1$  as follows: for any chain  $\zeta \in \mathcal{C}_k$ , treat  $\zeta$  as a ‘trail’ and define  $C(\zeta, \mathbf{a})$  as before.

(b) (*Equivariant cocycle  $C \in \mathcal{Z}_{\text{eq}}^2$  on ‘ice cube’ shift*) This picture shows how to evaluate  $C$  on a single 2-cell (i.e. oriented square). To evaluate  $C$  on 2-chain, sum values on all constituent 2-cells.



## —Equivariant Cohomology vs. Dynamical Cohomology—

Let  $\mathcal{B}_{\text{eq}}^k := \text{image}(\delta^{k-1})$  (equivariant coboundaries).

Define **equivariant cohomology group**  $\mathcal{H}_{\text{eq}}^k(\mathfrak{A}, \mathcal{G}) := \mathcal{Z}_{\text{eq}}^k / \mathcal{B}_{\text{eq}}^k$ .

$\mathcal{Z}_{\text{eq}}^k$  and  $\mathcal{B}_{\text{eq}}^k$  are  $\sigma$ -invariant. Thus,  $\sigma$  induces  $\mathbb{Z}^D$ -action on  $\mathcal{H}_{\text{eq}}^k$ . Let

$$\begin{aligned} \mathcal{Z}_{\text{dy}}^1(\mathfrak{A}, \mathcal{G}) &:= \{\text{dynamical cocycles}\}; \\ \mathcal{H}_{\text{dy}}^1(\mathfrak{A}, \mathcal{G}) &:= \text{'dynamical' cohomology group.} \end{aligned}$$

**Theorem:** *Let  $(\mathcal{G}, +)$  be abelian. There are canonical isomorphisms:*

$$\mathcal{Z}_{\text{eq}}^1(\mathfrak{A}, \mathcal{G}) \cong \mathcal{Z}_{\text{dy}}^1(\mathfrak{A}, \mathcal{G}) \quad \text{and} \quad \mathcal{H}_{\text{eq}}^1(\mathfrak{A}, \mathcal{G}) \cong \mathcal{H}_{\text{dy}}^1(\mathfrak{A}, \mathcal{G}).$$

**Proof idea:** Given  $C \in \mathcal{Z}_{\text{dy}}^1$ , define  $C' \in \mathcal{Z}_{\text{eq}}^1$  as follows: for any chain  $\zeta \in \mathcal{C}_k$ , represent  $\zeta$  with (sum of) trails  $\zeta'$ , and then define  $C'(\zeta, \mathbf{a}) := C(\zeta', \mathbf{a})$ . This sends cocycles to cocycles because  $(\delta^1 C' \equiv 0) \iff (C'(\partial_2 \xi, \mathbf{a}) = 0 \text{ for all } \xi \in \mathcal{C}_2) \iff (C(\zeta', \mathbf{a}) = 0 \text{ for any closed trail } \zeta' \text{ in } \mathbb{Z}^D)$ .  $\square$

## Codimension- $k$ poles

Let  $\partial_k : \mathcal{C}_k \longrightarrow \mathcal{C}_{k-1}$  be combinatorial ‘boundary’ operator

Let  $\mathcal{Z}_k := \ker(\partial_k) = \{k\text{-dimensional cycles}\}$  (‘submanifolds without boundary’).

**Example:**  $\mathcal{Z}_1 := \{(\text{sums of}) \text{ closed trails}\}$ .

If  $C \in \mathcal{Z}_{\text{eq}}^k(\mathfrak{A}, \mathcal{G})$ , and  $\mathbf{a} \in \mathfrak{A}$ , and  $\zeta \in \mathcal{Z}_k$ , then  $C(\mathbf{a}, \zeta) = 0$ .

If  $\mathcal{G}$  is discrete, then  $C$  is ‘locally determined’ by rule of radius  $R > 0$ .

If  $\mathbf{a} \in \tilde{\mathfrak{A}}$ , and  $\zeta$  stays inside  $\mathbb{G}_r(\mathbf{a})$  (for some  $r \geq R$ ), then  $C(\mathbf{a}, \zeta)$  is still well-defined.

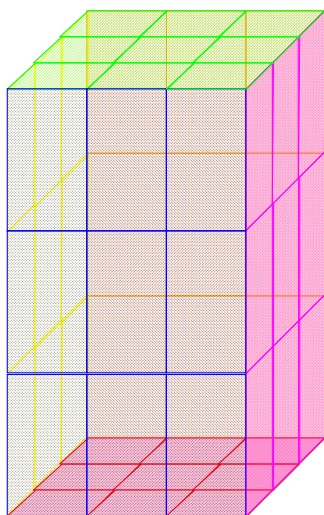
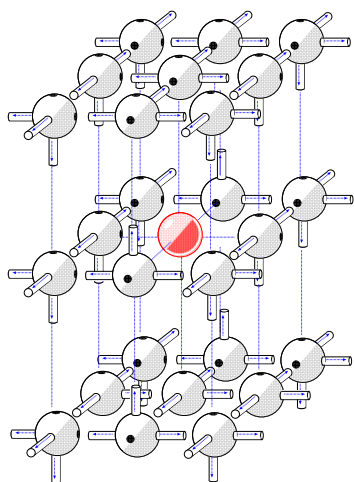
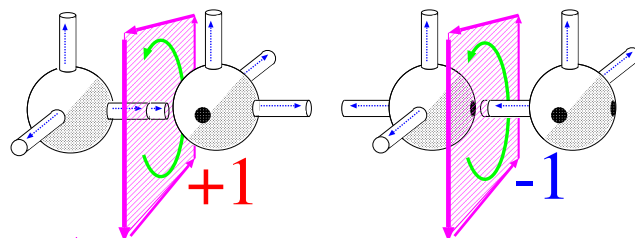
$\mathbf{a}$  has a **C-pole** (of radius  $r$ ) if there is some cycle  $\zeta$  such that  $C(\mathbf{a}, \zeta) \neq 0$ .

$\mathbf{a}$  has a **projective C-pole** if  $\mathbf{a}$  has a radius- $r$  pole for all large  $r \in \mathbb{N}$ .

### Example: Codimension-3 pole in Ice Cube shift

Let  $\Omega$  be the ‘ice cube’ shift.

Recall the equivariant 2-cocycle  $C \in \mathcal{Z}_{\text{eq}}^2(\Omega)$  defined:



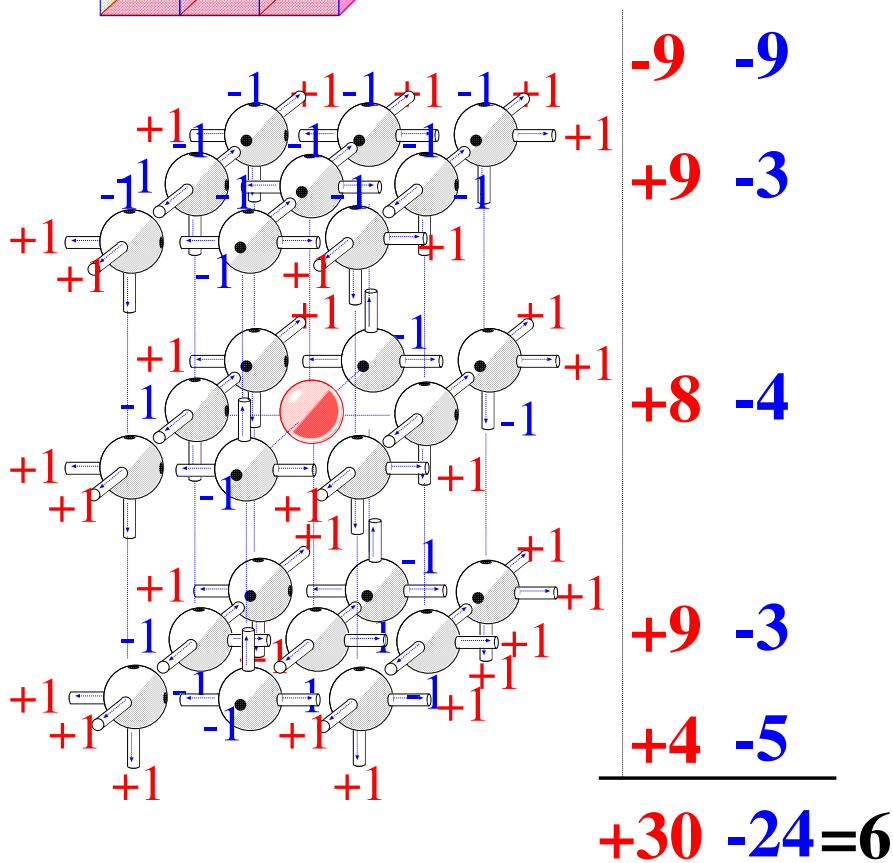
Let  $\mathbf{a}$  be the defective configuration at left.

Let  $\zeta \in \mathcal{Z}_2$  be the 2-cycle on right (the oriented boundary of a  $3 \times 3 \times 3$  cube).

Then

$$\begin{aligned} C(\mathbf{a}, \zeta) &= 30 - 24 \\ &= 6. \end{aligned}$$

Thus, the defect in  $\mathbf{a}$  is a  $C$ -pole with residue 6.



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## Persistence of Poles

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**Theorem:** *Projective poles are essential defects.*

**Proof idea:** Similar to ‘dynamical’ cohomology proof for codimension-2 poles.  $\square$

**Theorem:** *Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}^D}$  be an SFT. Let  $\Phi: \mathcal{A}^{\mathbb{Z}^D} \rightarrow \mathcal{A}^{\mathbb{Z}^D}$  be a CA with  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$ . Fix  $d \in [1 \dots D]$ .*

(a) *Define  $\Phi_*: \mathcal{C}_{\text{eq}}^d(\mathfrak{A}, \mathcal{G}) \rightarrow \mathcal{C}_{\text{eq}}^d(\mathfrak{A}, \mathcal{G})$  by  $\Phi_*C(\mathbf{a}, \zeta) := C[\Phi(\mathbf{a}), \zeta]$ .*

*This induces endomorphism  $\mathcal{H}_{\text{eq}}^d \Phi: \mathcal{H}_{\text{eq}}^d(\mathfrak{A}, \mathcal{G}) \rightarrow \mathcal{H}_{\text{eq}}^d(\mathfrak{A}, \mathcal{G})$ .*

(b) *Suppose  $\mathcal{H}_{\text{eq}}^d \Phi$  is an epimorphism.*

[i] *If  $\mathcal{G}$  is the additive group of a field (e.g.  $\mathcal{G} = \mathbb{Z}/p$  for  $p$  prime), then all projective  $\mathcal{G}$ -poles are  $\Phi$ -persistent.*

[ii] *If  $d = 1$  or  $D$ , then any projective  $d$ -pole is  $\Phi$ -persistent.  $\square$*

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## Invariant Cohomology

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**Questions:** (a) *What is relationship between the (dynamical) cocycles of  $\mathfrak{A}$  and the (co)homology groups of Wang tile cell complex of  $\mathfrak{A}$ ?*

(b) *What is relationship between poles and (co)homology defects?*

$\forall r \geq R := \text{radius}(\mathfrak{A})$ , let  $\mathbf{X}_r :=$  radius- $r$  Wang tile cell complex for  $\mathfrak{A}$ .

The  $\sigma$ -action on  $\mathfrak{A}$  induces natural  $\mathbb{Z}^D$ -action on  $\mathbf{X}_r$ ; hence on  $\mathcal{H}^k(\mathbf{X}_r, \mathcal{G})$ .

Let  $\mathcal{H}_{\text{inv}}^k(\mathbf{X}_r, \mathcal{G}) :=$  group of  $\mathbb{Z}^D$ -fixed elements of  $\mathcal{H}^k(\mathbf{X}_r, \mathcal{G})$ . We define the  $k$ th **invariant cohomology group** of  $\mathfrak{A}$ :

$$\mathcal{H}_{\text{inv}}^k(\mathfrak{A}, \mathcal{G}) := \varinjlim \left( \mathcal{H}_{\text{inv}}^k(\mathbf{X}_{R+1}, \mathcal{G}) \rightarrow \mathcal{H}_{\text{inv}}^k(\mathbf{X}_{R+2}, \mathcal{G}) \rightarrow \mathcal{H}_{\text{inv}}^k(\mathbf{X}_{R+3}, \mathcal{G}) \rightarrow \dots \right)$$

**Theorem:** *Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}^D}$  be SFT. Let  $(\mathcal{G}, +)$  be discrete abelian group.*

*There is a natural isomorphism  $\mathcal{H}_{\text{inv}}^d(\mathfrak{A}, \mathcal{G}) \cong \mathcal{H}_{\text{eq}}^d(\mathfrak{A}, \mathcal{G})$ .*

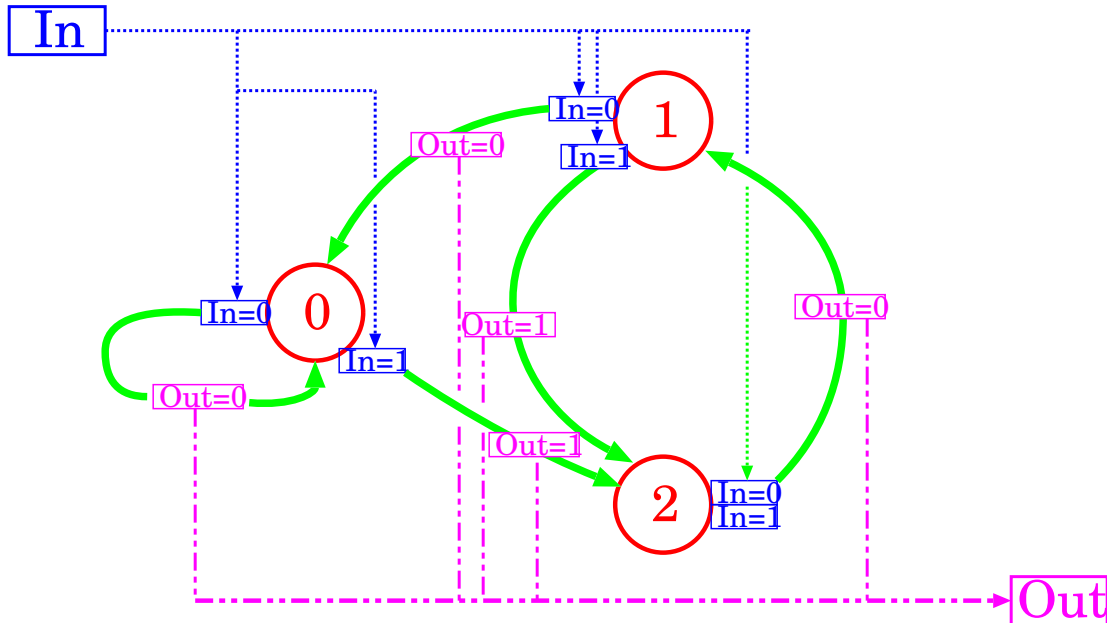
*In particular,  $\mathcal{H}_{\text{inv}}^1(\mathfrak{A}, \mathcal{G}) \cong \mathcal{H}_{\text{dy}}^1(\mathfrak{A}, \mathcal{G})$ .  $\square$*

Thus, poles are  $\mathcal{H}_{\text{inv}}^d(\mathfrak{A}, \mathcal{G})$ -cohomology defects.

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## Finite State Machines

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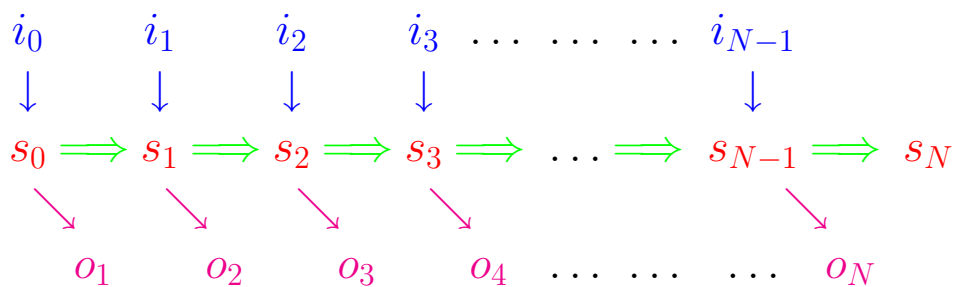
A **finite state machine** (FSM) has a finite set of internal *states*  $\mathcal{S}$ , finite *input alphabet*  $\mathcal{I}$  and *output alphabet*  $\mathcal{O}$ , and *update rule*

$$\Upsilon : \mathcal{I} \times \mathcal{S} \longrightarrow \mathcal{S} \times \mathcal{O}$$

If FSM begins in state  $s_0$ , and receives input stream  $i_0, i_1, i_2, \dots, i_{N-1}$ , then it proceeds through states  $s_1, s_2, \dots, s_N$  and produces output  $o_1, o_1, \dots, o_N$ , where, for every  $n \in [0 \dots N)$ ,

$$\Upsilon(i_n, s_n) = (s_{n+1}, o_{n+1})$$

Diagrammatically:





## Defect Particle Kinematics

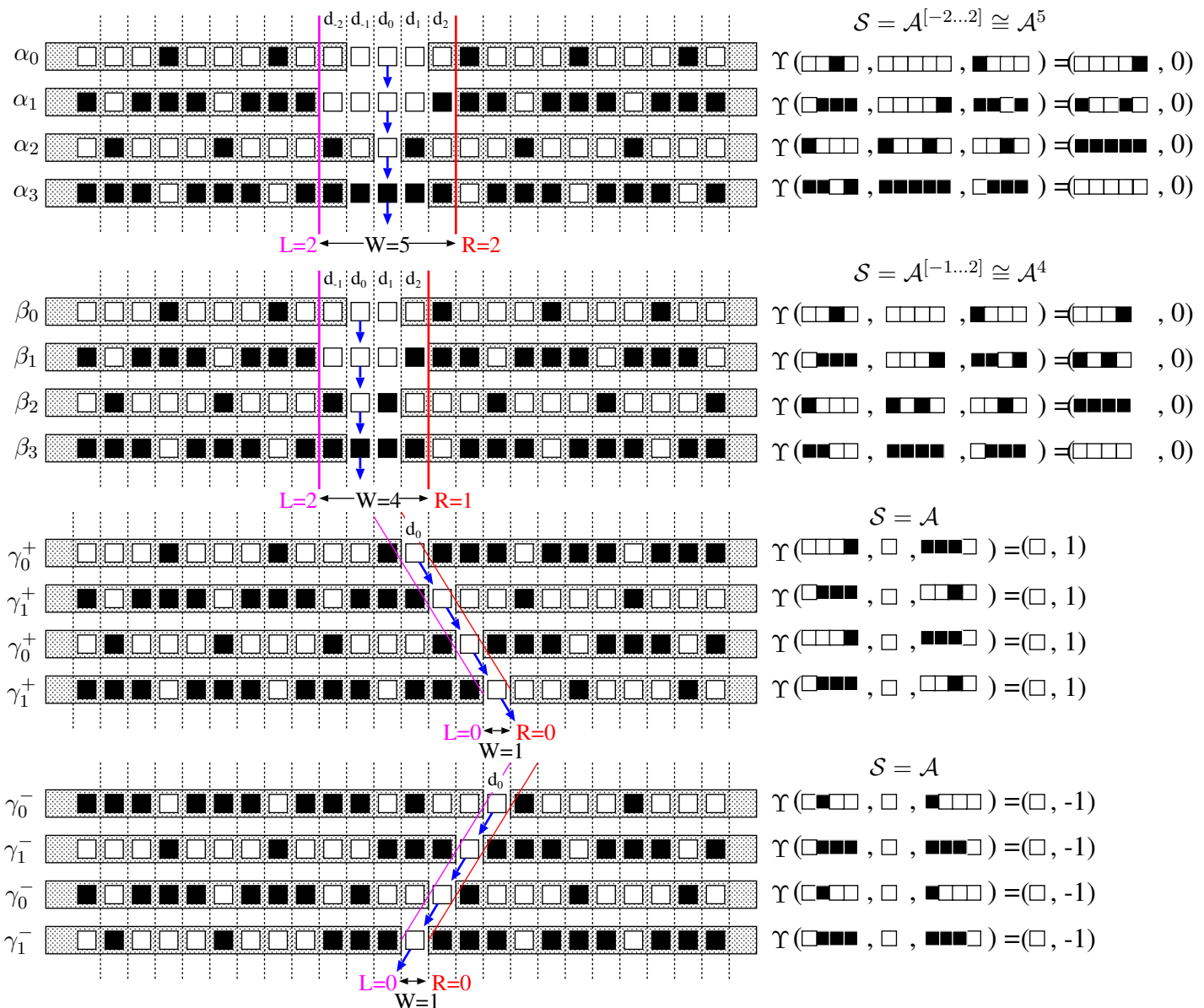
A **defect particle** in  $\mathbf{a}$  is a defect which is finite in size and whose size in  $\Phi^t(\mathbf{a})$  remains bounded for all  $t > 0$ . Defect particles act like FSM:

**Internal state** =  $\mathfrak{A}$ -inadmissible symbol-sequence inside defect.

**Input** =  $\mathfrak{A}$ -admissible symbols on boundary of defect.

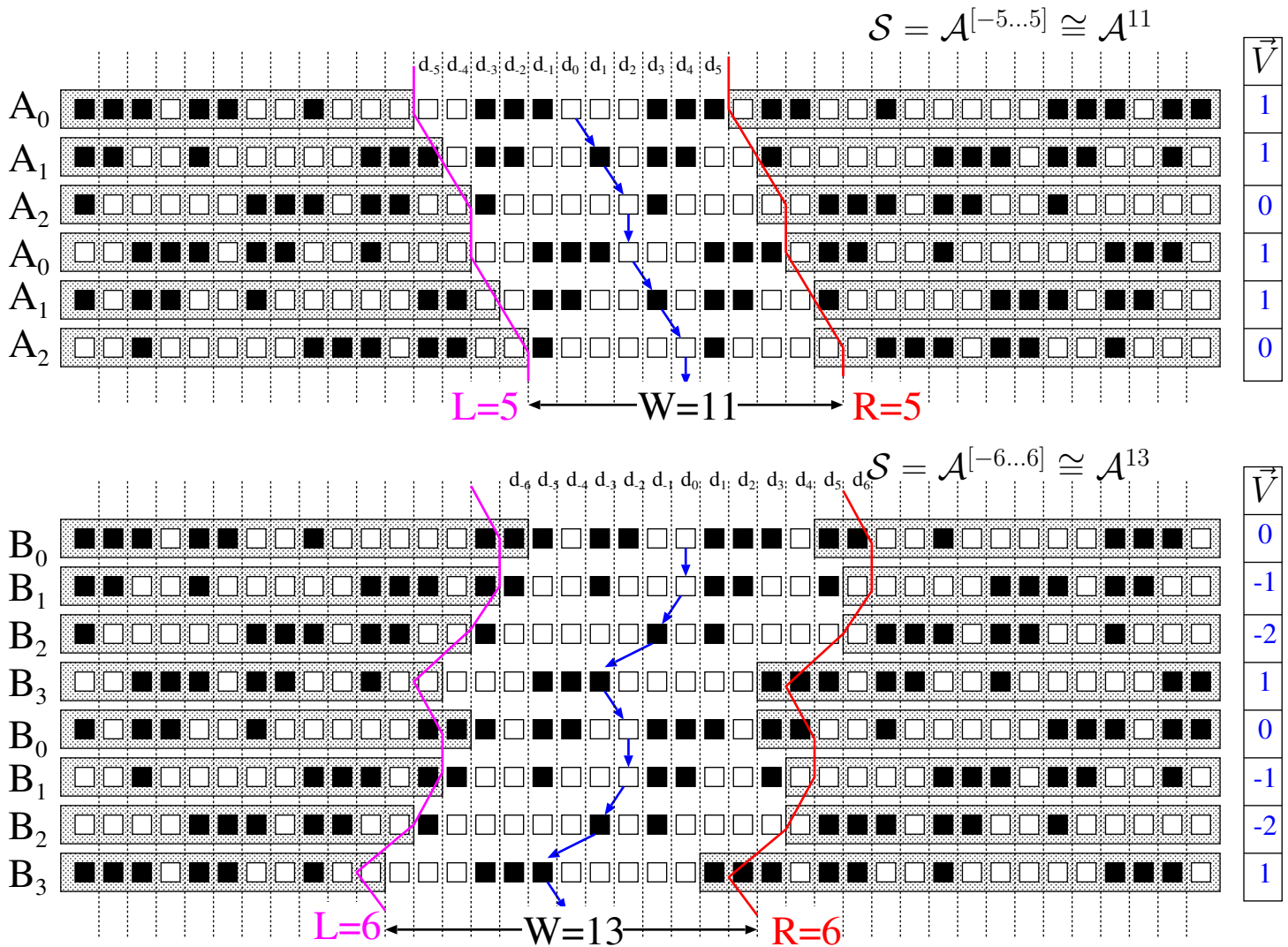
**Output** = Instantaneous velocity.

**Example:** Defect particles in ECA#54:



## Defect Particle Kinematics

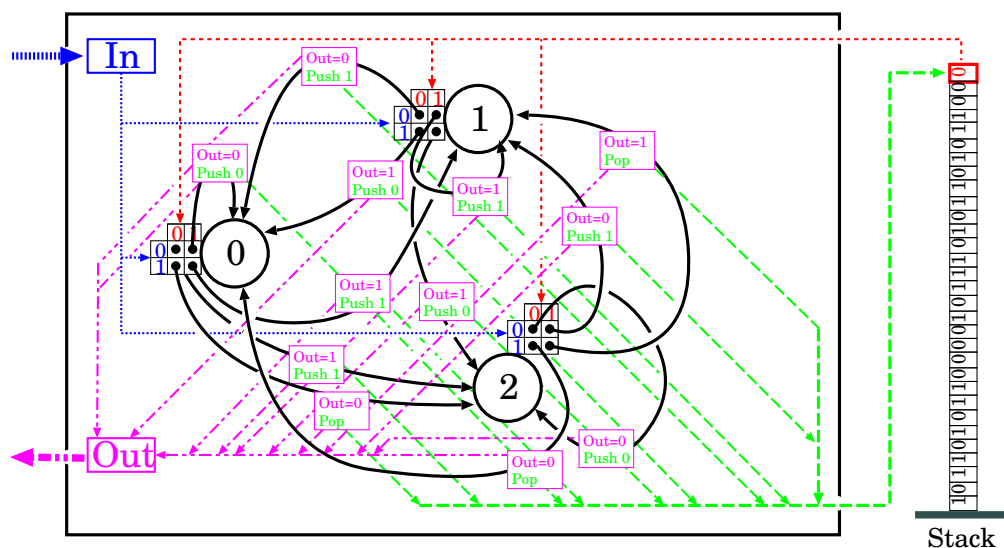
**Example:** The **A** and **B** defect particles of ECA#110:



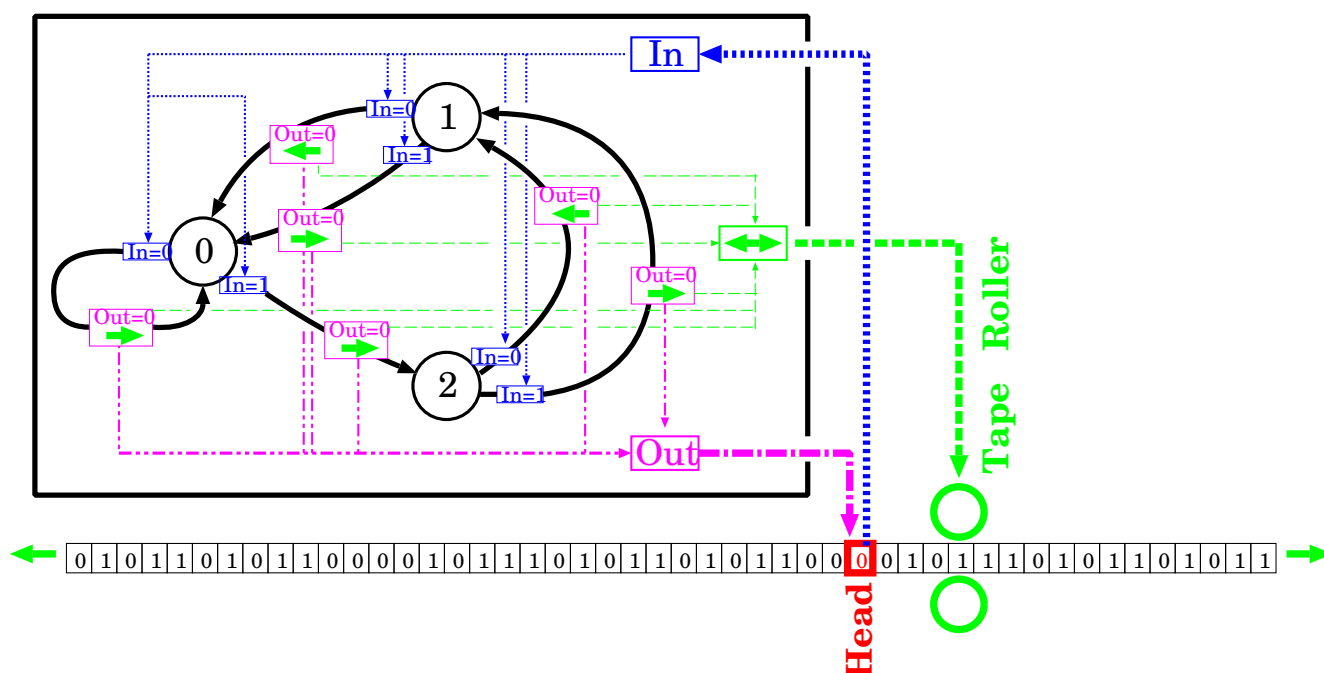
**Remarks:** • The width of inadmissible region fluctuates over time. We define the **width** of the defect to be the maximum width it ever obtains. This defines the effective ‘state space’ of the FSM representation.

- If  $\mathfrak{A}$  is  $(\Phi, \sigma)$ -periodic (as in these examples), then the FSM is driven by periodic input, so its long-term behaviour is periodic.
- The defect velocity fluctuates over time, but there is a long-term ‘average’ velocity obtained by averaging over the period.

## Pushdown Automata and Turing Machines



A **pushdown automaton** (PDA) is an FSM augmented with ‘last in, first out’ memory model called a **stack**. The machine can ‘push’ symbols onto the stack, and later ‘pop’ them off the stack in reverse order.



A **Turing machine** is an FSM augmented with a biinfinite random access memory model called a ‘tape’. The FSM acts has a ‘head’ which can read/write symbols as it moves along the tape.

## One-dimensional CA: Kinematic Regimes

In one-dimensional CA, the particle kinematics depends upon the kind of subshifts found to the right and left of the particle.

Defect Kinematic Regimes		Right Side ( $\sigma, \Phi$ )-Dynamics					
		$\sigma$ -dynamics	$\Phi$ -dynamics	Zero Entropy, $\sigma$ -periodic	Right-regular	Nonzero $\sigma$ -Entropy, Not $\sigma$ -periodic	
		$\sigma$ -dynamics	$\Phi$ -dynamics	$\Phi$ -Periodic or $\Phi$ -Fixed	Right-resolving	$\Phi$ -Periodic or $\Phi$ -Fixed	Anything else
Left Side ( $\sigma, \Phi$ )-Dynamics	Zero Entropy, $\sigma$ -periodic	$\Rightarrow$ $\Phi$ -Periodic or $\Phi$ -Fixed	<b>Ballistic</b>	<b>Diffusive</b>	<b>Autonomous PDA</b>	Complicated	
	Left-regular	Left-resolving	<b>Diffusive</b>	<b>Diffusive</b>	<b>Markov PDA</b>		
	Nonzero $\sigma$ -Entropy,	$\Phi$ -Periodic or $\Phi$ -Fixed	<b>Autonomous PDA</b>	<b>Markov PDA</b>	<b>Turing Machine</b>	Complicated	
	Not $\sigma$ -periodic	Anything else	Complicated		Complicated		

**Ballistic:** Defect has  $(\Phi, \sigma)$ -periodic subshifts on both sides. Acts like FSM driven by periodic input. Moves with constant average velocity through periodic background. **Examples:** ECAs 54, 62, 110, and 184

**Diffusive:** Regular,  $\Phi$ -resolving subshifts on one or both sides. Acts like FSM driven by Markov process. Performs generalized random walk. **Example:** ECA #18.

**Turing Machine:** Defect moves through  $\Phi$ -fixed, positive  $\sigma$ -entropy background, and modifies background as it goes. Acts like Turing machine: particle is the ‘head’, and inert background is the ‘tape’.

**Autonomous Pushdown Automaton:**  $\Phi$ -fixed, positive  $\sigma$ -entropy domain on one side (which acts as a ‘stack’ memory), and zero-entropy domain on the other side. Acts like a PDA without external input.

**Markov PDA:**  $\Phi$ -fixed, positive  $\sigma$ -entropy domain on one side (acts as a ‘stack’), and regular  $\Phi$ -resolving subshift on the other. Acts like a PDA driven by a Markov process.

## Regular Markov Subshifts & Resolving CA

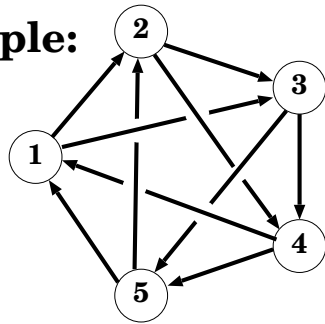
$\forall a \in \mathcal{A}$ , let  $\mathcal{F}(a) \subseteq \mathcal{A}$  be a set of ‘admissible followers’. Write  $a \rightsquigarrow b$  if  $b \in \mathcal{F}(a)$ .

The corresponding **Markov subshift**  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}}$  is the set of all infinite sequences  $[\dots \rightsquigarrow a \rightsquigarrow b \rightsquigarrow c \rightsquigarrow d \rightsquigarrow \dots]$  (Every SFT can be recoded thus.)

Let  $\mathcal{P}(a) := \{b \in \mathcal{A} ; b \rightsquigarrow a\}$  be the set of admissible ‘predecessors’.

$\mathfrak{A}$  is **regular** if  $\exists F \in \mathbb{N}$  such that  $\#\mathcal{F}(a) = F$  for all  $a \in \mathcal{A}$ , and  $\exists P \in \mathbb{N}$  such that  $\#\mathcal{P}(a) = P$  for all  $a \in \mathcal{A}$ .

**Example:**

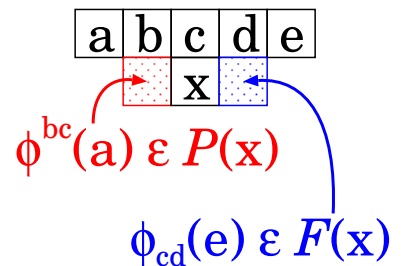


$$\begin{array}{ll} \mathcal{F}(1) = \{2, 3\}; & \mathcal{P}(1) = \{4, 5\} \\ \mathcal{F}(2) = \{3, 4\}; & \mathcal{P}(2) = \{5, 1\} \\ \mathcal{F}(3) = \{4, 5\}; & \mathcal{P}(3) = \{1, 2\} \\ \mathcal{F}(4) = \{5, 1\}; & \mathcal{P}(4) = \{2, 3\} \\ \mathcal{F}(5) = \{1, 2\}; & \mathcal{P}(5) = \{3, 4\} \end{array}$$

Let  $\Phi : \mathcal{A}^{\mathbb{Z}} \rightarrow \mathcal{A}^{\mathbb{Z}}$  be a CA with local rule  $\phi : \mathcal{A}^3 \rightarrow \mathcal{A}$ . Suppose  $\Phi(\mathfrak{A}) \subset \mathfrak{A}$ . Let  $(b \rightsquigarrow c \rightsquigarrow d)$  and let  $x := \phi(b, c, d)$ .

If  $d \rightsquigarrow e$ , then  $x \rightsquigarrow \phi(c, d, e)$ . Thus, we get function  $\phi_{c,d} : \mathcal{F}(d) \rightarrow \mathcal{F}(x)$ . We say  $\Phi$  is **right-resolving** if  $\phi_{c,d}$  is bijective for all such  $(c, d)$ .

If  $a \rightsquigarrow b$ , then  $\phi(a, b, c) \rightsquigarrow x$ . Thus, we get function  $\phi^{b,c} : \mathcal{P}(b) \rightarrow \mathcal{P}(x)$ . We say  $\Phi$  is **left-resolving** if  $\phi^{b,c}$  is bijective for all such  $(b, c)$ .



$\Phi$  is **resolving** if it is both left- and right- resolving.

**Examples:** (a) *Permutative* CA acting on full shift  $\mathfrak{A} = \mathcal{A}^{\mathbb{Z}}$ .

(b) *Linear* CA acting on Markov subgroup. (Here  $\mathcal{A}$  is a group, so  $\mathcal{A}^{\mathbb{Z}}$  is a group.  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}}$  is a subgroup, and  $\Phi : \mathcal{A}^{\mathbb{Z}} \rightarrow \mathcal{A}^{\mathbb{Z}}$  is endomorphism.)

## Diffusive Defect Particle Kinematics

The **Parry measure**  $\mu$  is the measure of maximal entropy on  $\mathfrak{A}$ . It is Markov measure given equal transition probability to all  $b \in \mathcal{F}(a)$ .

**Theorem:** Let  $\mathfrak{A} \subset \mathcal{A}^{\mathbb{Z}}$  be regular Markov subshift. Let  $\Phi : \mathcal{A}^{\mathbb{Z}} \rightarrow \mathcal{A}^{\mathbb{Z}}$  be CA with  $\Phi(\mathfrak{A}) \subseteq \mathfrak{A}$  and  $\Phi$  resolving on  $\mathfrak{A}$ . Let  $\mu =$  Parry measure on  $\mathfrak{A}$ . (Then  $\Phi\mu = \mu$ .)

Let  $\mathbf{l} \in \mathcal{A}^{(-\infty \dots 0)}$  be  $\mu$ -random, left-infinite  $\mathfrak{A}$ -admissible sequence.

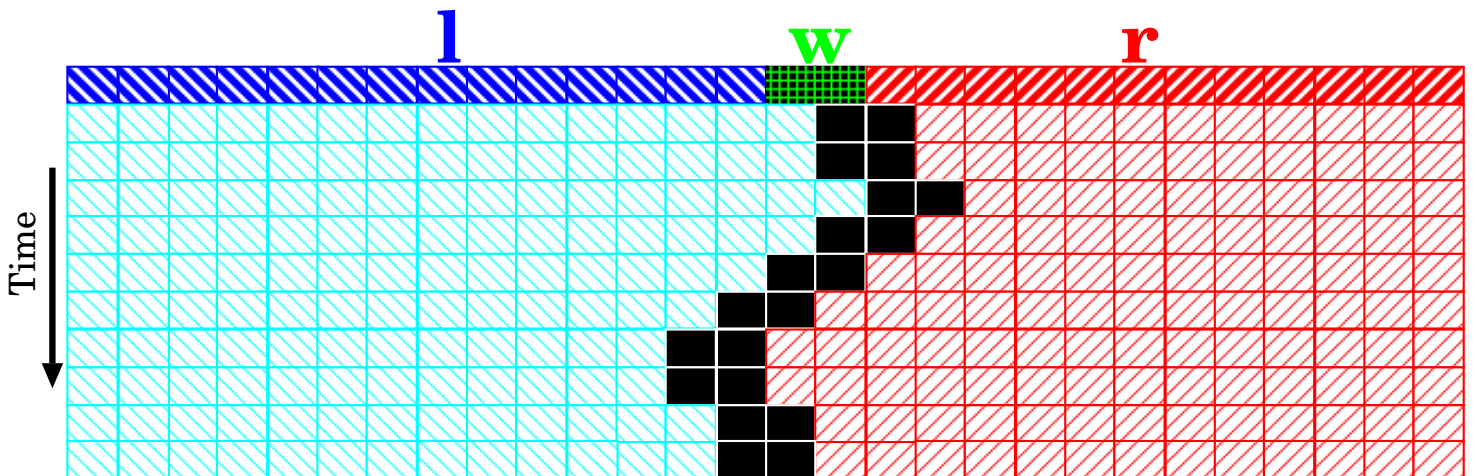
Let  $\mathbf{r} \in \mathcal{A}^{[W \dots \infty)}$  be  $\mu$ -random, right-infinite  $\mathfrak{A}$ -admissible sequence.

Let  $\mathbf{w} \in \mathcal{A}^{[0 \dots W)}$  be ‘defect’ word. Set initial condition:  $\mathbf{a} := \mathbf{l.w.r}$ .

Define  $\zeta : \mathbb{N} \rightarrow \mathbb{Z}$  by  $\zeta(t) :=$  position of defect in  $\Phi^t(\mathbf{a})$ . Then  $\zeta$  is a generalized random walk. [i.e. increments of  $\zeta$  are a hidden Markov process].

(Generalizes Eloranta [1993-1995]; similar result for 0-width defects in ‘partially permutive’ CA.)

**Proof idea:** The defect motion is driven by ‘ $\mu$ -random information’ coming in from the left and right, as follows:

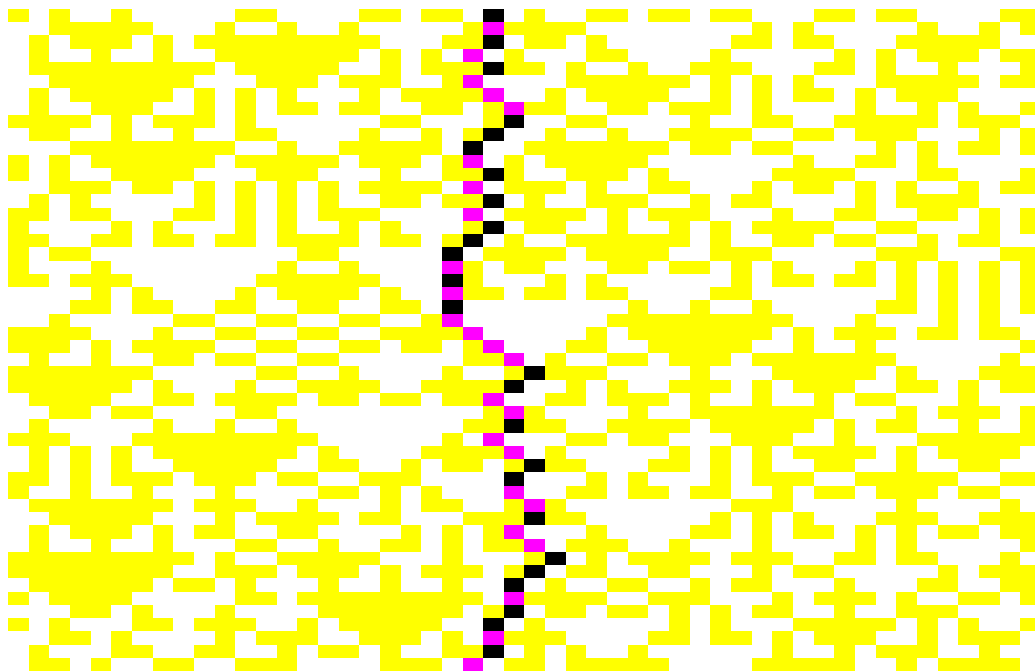


**Legend:**    Initial conditions  Defect particle path  
   $\mu$ -random cells determined by  $\mu$ -random initial conditions

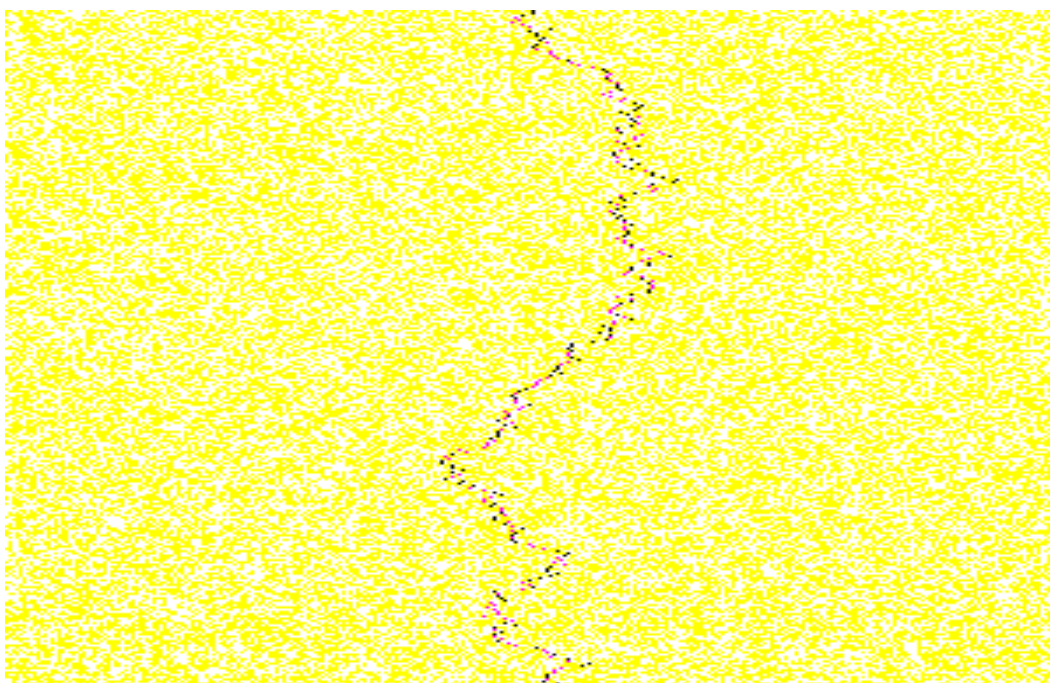
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## Diffusive Defect Particle Kinematics

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Scale:  $50 \times 50$  (space  $\times$  time)



Scale:  $300 \times 6000$  (space  $\times$  time)