TRENT UNIVERSITY Summer 2017

MATH 1350H Test Monday, 29 May

Time: 60 minutes

Name:	Solutions	
Student Number:	0123456	

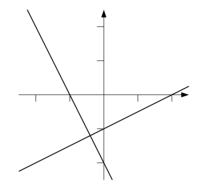
Question	Mark	
1		
2		
3		
4		
Total		/40

Instructions

- Show all your work. Legibly, please!
- If you have a question, ask it!
- Use the back sides of the test sheets for rough work or extra space.
- You may use a calculator and an aid sheet.

- **1.** Do **a** and any two (2) of **b**-**d**. $[10 = 2 + 2 \times 4 \text{ each}]$ Consider the lines given by the equations x - 2y = 2 and 2x + y = -2.
- **a.** Sketch a graph of the two lines including their x- and y-intercepts.
- **b.** Find the point where the lines intersect.
- c. Find vector-parametric equations for each of the lines.
- d. Find the angle between the lines.

SOLUTIONS. a. Here is a crude sketch of the two lines:



Observe that the intercepts of the line x - 2y = 2 are x = 2 on the x-axis and y = -1 on the y-axis, while the intercepts of the line 2x + y = -2 are x = -1 on the x-axis and y = -2 on the y-axis. \Box

b. Solving the equation of the first line for x gives x = 2y + 2. Substituting this into the equation of the second line gives 2(2y+2) + y = -2, so 5y + 4 = -2, hence 5y = -6, and thus $y = -\frac{6}{5}$. Substituting back gives $x = 2\left(-\frac{6}{5}\right) + 2 = \frac{-12+10}{5} = -\frac{2}{5}$. Thus the lines intersect at the point $\left(-\frac{2}{5}, -\frac{6}{5}\right)$. (As a quick sanity check, this is consistent with the crude sketch drawn for **a**.) \Box

c. We'll use the vectors from the origin to the *x*-intercepts of each line, namely $\begin{bmatrix} 2\\0 \end{bmatrix}$ and $\begin{bmatrix} -1\\0 \end{bmatrix}$ for the base vectors, and the vectors from the *x*-intercept to the *y*-intercepts, namely $\begin{bmatrix} 0-2\\-1-0 \end{bmatrix} = \begin{bmatrix} -2\\-1 \end{bmatrix}$ and $\begin{bmatrix} 0-(-1)\\-2-0 \end{bmatrix} = \begin{bmatrix} 1\\-2 \end{bmatrix}$, for the direction vectors. Thus $\begin{bmatrix} x\\y \end{bmatrix} = \begin{bmatrix} 2\\0 \end{bmatrix} + s \begin{bmatrix} -2\\-1 \end{bmatrix}$ and $\begin{bmatrix} x\\y \end{bmatrix} = \begin{bmatrix} -1\\0 \end{bmatrix} + t \begin{bmatrix} 1\\-2 \end{bmatrix}$

are vector-parametric equations for the two lines x - 2y = 2 and 2x + y = -2, respectively. (s and t are the respective parameters – it's probably not a good idea to use the same parameter for both lines in most applications.) \Box

d. The angle between the lines is the angle between the direction vectors. $\begin{bmatrix} -2\\1 \end{bmatrix} \cdot \begin{bmatrix} -1\\-2 \end{bmatrix} = (-2)(-1) + 1(-2) = 2 - 2 = 0$, so the two direction vectors are orthogonal to each other, so the angle between the lines is a right angle (*i.e.* 90° or $\frac{\pi}{2}$ rad).

- **2.** Do any two (2) of \mathbf{a} - \mathbf{c} . $[10 = 2 \times 5 \text{ each}]$ Let $\mathbf{u} = \begin{bmatrix} 0\\1\\1 \end{bmatrix}$, $\mathbf{v} = \begin{bmatrix} 1\\0\\1 \end{bmatrix}$, and $\mathbf{w} = \begin{bmatrix} 1\\1\\0 \end{bmatrix}$.
- **a.** Find the components of ${\bf w}$ that are, respectively, parallel to and perpendicular to ${\bf v}.$
- **b.** Solve $2\mathbf{u} + 4\mathbf{w} + 5\mathbf{x} = -3\mathbf{v}$ for \mathbf{x} .
- **c.** Find the angle between \mathbf{u} and \mathbf{v} .

SOLUTIONS. a. The component of \mathbf{w} parallel to \mathbf{v} is the projection of \mathbf{w} onto \mathbf{v} :

$$\operatorname{proj}_{\mathbf{v}}(\mathbf{w}) = \frac{\mathbf{w} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} = \frac{1 \cdot 1 + 1 \cdot 0 + 0 \cdot 1}{1 \cdot 1 + 0 \cdot 0 + 1 \cdot 1} \begin{bmatrix} 1\\0\\1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1\\0\\1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2}\\0\\\frac{1}{2} \end{bmatrix}$$

The component of \mathbf{w} perpendicular to \mathbf{v} is what is left when you take the component parallel to \mathbf{v} away from \mathbf{w} :

$$\mathbf{w} - \operatorname{proj}_{\mathbf{v}}(\mathbf{w}) = \begin{bmatrix} 1\\1\\0 \end{bmatrix} - \begin{bmatrix} \frac{1}{2}\\0\\\frac{1}{2} \end{bmatrix} = \begin{bmatrix} \frac{1}{2}\\1\\-\frac{1}{2} \end{bmatrix} \qquad \Box$$

b. Just a bit of rearranging and arithmetic:

$$2\mathbf{u} + 4\mathbf{w} + 5\mathbf{x} = -3\mathbf{v}$$

$$\implies 5\mathbf{x} = -2\mathbf{u} - 3\mathbf{v} - 4\mathbf{w}$$

$$\implies \mathbf{x} = -\frac{2}{5}\mathbf{u} - \frac{3}{5}\mathbf{v} - \frac{4}{5}\mathbf{w} = -\frac{2}{5}\begin{bmatrix}0\\1\\1\end{bmatrix} - \frac{3}{5}\begin{bmatrix}1\\0\\1\end{bmatrix} - \frac{4}{5}\begin{bmatrix}1\\1\\0\end{bmatrix} = \begin{bmatrix}-\frac{7}{5}\\-\frac{6}{5}\\-1\end{bmatrix} \qquad \Box$$

c. Recall that if θ is the (smallest) angle between **u** and **v**, then

$$\cos(\theta) = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\| \mathbf{v}\|} = \frac{0 \cdot 1 + 1 \cdot 0 + 1 \cdot 1}{\sqrt{0^2 + 1^2 + 1^2}\sqrt{1^2 + 0^2 + 1^2}} = \frac{1}{\sqrt{2}\sqrt{2}} = \frac{1}{2},$$

so $\theta = \arccos\left(\frac{1}{2}\right) = 60^\circ = \frac{\pi}{3}$ rad.

- **3.** Consider the following system of linear equations:
- **a.** Find all the solutions, if any, of this system. [8]
- **a.** Find all the solutions, if any, of this $c_j = 1$. **b.** Use your solution to **a** to help determine whether the vectors $\begin{bmatrix} 2\\1\\1 \end{bmatrix}$, $\begin{bmatrix} 1\\1\\2 \end{bmatrix}$, and $\begin{bmatrix} 1\\0\\-1 \end{bmatrix}$. are linearly independent. (2)

SOLUTIONS. a. We set up the augmented matrix corresponding to the given system and apply the Gauss-Jordan algorithm:

x

x

y2y 1

1

2

$$\begin{bmatrix} 2 & 1 & 1 & | & 1 \\ 1 & 1 & 0 & | & 1 \\ 1 & 2 & -1 & | & 2 \end{bmatrix} \stackrel{R_1 \leftrightarrow R_2}{\Longrightarrow} \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 2 & 1 & 1 & | & 1 \\ 1 & 2 & -1 & | & 2 \end{bmatrix} \stackrel{\Longrightarrow}{\Longrightarrow} \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 0 & -1 & 1 & | & -1 \\ R_3 - R_1 \begin{bmatrix} 0 & -1 & 1 & | & -1 \\ 0 & 1 & -1 & | & 1 \end{bmatrix}$$
$$\stackrel{\Longrightarrow}{\Longrightarrow} \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 0 & 1 & -1 & | & 1 \\ 0 & 1 & -1 & | & 1 \end{bmatrix} \stackrel{R_1 - R_2}{\Longrightarrow} \begin{bmatrix} 1 & 0 & 1 & | & 0 \\ 0 & 1 & -1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \stackrel{i.e.}{y-z=1} \stackrel{x+z=0}{y-z=1}$$

Having fully reduced the matrix, we see that there are infinitely many solutions; if we set z = t for a parameter t, then x = -z = -t and y = 1 + z = 1 + t, which forms a line in \mathbb{R}^3 . In vector-parametric form the solutions are $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}, t \in \mathbb{R}$. \Box

b. The three vectors are not linearly independent. If one were to replace the right-hand side column in the original augmented matrix above by all zeros and then apply the Gauss-1 0 1 [0]

Jordan algorithm just as above, the final augmented matrix would be $\begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$ $0 \mid$, -10 0 0 0

representing the system x + z = 0 and y - z = 0. (Recall that the allowed row operations do not change a column of zeros.) This also has infinitely many solutions, so there must

x, y, and z which are not all 0 and such that $x \begin{bmatrix} 2\\1\\1 \end{bmatrix} + y \begin{bmatrix} 1\\1\\2 \end{bmatrix} + z \begin{bmatrix} 1\\0\\-1 \end{bmatrix} = \begin{bmatrix} 0\\0\\0 \end{bmatrix}$. This means, by definition, that these vectors are not linearly independent.

3

4. Let
$$S = \left\{ \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\0\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\1\\0\\1 \end{bmatrix} \right\}$$
, and let $\mathbf{x} = \begin{bmatrix} 1\\0\\0\\1 \end{bmatrix}$.

a. Determine whether $\mathbf{x} \in \text{Span}(S)$. [8]

b. Determine whether S is a linearly independent set of vectors. [2]

SOLUTIONS. **a.** By definition, $\mathbf{x} \in \text{Span}(S)$ if there are scalars a, b, and c such that $a \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix} + b \begin{bmatrix} 1\\0\\1\\1 \end{bmatrix} + c \begin{bmatrix} 1\\1\\0\\1 \end{bmatrix} = \begin{bmatrix} 1\\0\\0\\1 \end{bmatrix}$, *i.e.* such that a + b + c = 1, a + c = 0, a + b = 0,

and a + b + c = 1. We set up the augmented matrix for this system of equations and Gauss-Jordan away:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} \xrightarrow{R_2 - R_1} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & -1 & 0 & | & -1 \\ 0 & 0 & -1 & | & -1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{(-1)R_2} \begin{bmatrix} 1 & 1 & 1 & | & 1 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$
$$R_1 - R_3 \begin{bmatrix} 1 & 0 & 0 & | & -1 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_1 - R_3} \begin{bmatrix} 1 & 0 & 0 & | & -1 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_2 - R_1} \xrightarrow{R_1 - R_3} \begin{bmatrix} 1 & 0 & 0 & | & -1 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_2 - R_1} \xrightarrow{R_1 - R_3} \begin{bmatrix} 1 & 0 & 0 & | & -1 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_2 - R_1} \xrightarrow{R_1 - R_3} \xrightarrow{R_1 - R_3} \begin{bmatrix} 1 & 0 & 0 & | & -1 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \xrightarrow{R_2 - R_1} \xrightarrow{R_1 - R_3} \xrightarrow{$$

Since there is a solution, $\mathbf{x} \in \text{Span}(S)$. \Box

b. Proceeding just as in the solution to **3b**, if one were to replace the right-hand side in the calculation above with zeros, one would eventually obtain $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ as the

fully reduced augmented matrix, corresponding to the unique solution a = b = c = 0. By definition, this means that S is a linearly independent set.

[Total = 40]