Mathematics 1350H – Linear algebra I: matrix algebra TRENT UNIVERSITY, Fall 2008

Solutions to the quizzes

Quiz #1. Friday, 19 September, 2008. [5 minutes]

1. Sketch the vector $\begin{bmatrix} 2\\4\\4 \end{bmatrix}$ (in standard position) and find its length. [5]

Solution. Here's a sketch of the vector:



It remains to compute the length of the vector:

$$\left\| \begin{bmatrix} 2\\4\\4 \end{bmatrix} \right\| = \sqrt{2^2 + 4^2 + 4^2} = \sqrt{4 + 16 + 16} = \sqrt{36} = 6$$

Quiz #2. Friday, 26 September, 2008. [5 minutes]

1. Let
$$\mathbf{a} = \begin{bmatrix} 3 \\ -1 \\ 0 \\ -3 \end{bmatrix}$$
 and $\mathbf{b} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix}$. Compute $\operatorname{proj}_{\mathbf{b}}(\mathbf{a})$. [5]

Solution. We plug into the formula and chug away!

$$proj_{\mathbf{b}}(\mathbf{a}) = \frac{\mathbf{a} \cdot \mathbf{b}}{\mathbf{b} \cdot \mathbf{b}} \mathbf{b} = \frac{\begin{bmatrix} 3 \\ -1 \\ 0 \\ -3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix}}{\begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix}} \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix}$$
$$= \frac{3 \cdot 1 + (-1) \cdot 0 + 0 \cdot 1 + (-3) \cdot (-1)}{1 \cdot 1 + 0 \cdot 0 + 1 \cdot 1 + (-1) \cdot (-1)} \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix}$$
$$= \frac{6}{3} \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 2 \\ -2 \end{bmatrix}$$

Whew! \blacksquare

Quiz #3. Friday, 3 October, 2008. [5 minutes]

1. Find the (least) distance from the point (0,0,0) to the plane x + y + z = 12. [5]

Solution. First, observe that $\mathbf{n} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ is a vector perpendicular to the plane x + y + z = 12: just read off the coefficients of the variables in the given equation.

Second, it is easy to see that (12, 0, 0) is a point on the plane, and hence that $\mathbf{a} = \begin{bmatrix} 12 \\ 0 \\ 0 \end{bmatrix}$

is the vector that runs from the given point, (0, 0, 0), to the point (12, 0, 0) on the plane.

Third, to obtain the vector that runs between (0, 0, 0) and the nearest point to it on the plane (in one direction or the other), we project the vector **a** onto the normal vector **b**:

$$\operatorname{proj}_{\mathbf{n}}(\mathbf{a}) = \frac{\mathbf{a} \cdot \mathbf{n}}{\mathbf{n} \cdot \mathbf{n}} \mathbf{n} = \frac{\begin{bmatrix} 12\\0\\0 \end{bmatrix} \cdot \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}}{\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}} \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}} \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix} = \frac{12}{3} \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix} = \begin{bmatrix} 4\\4\\4 \end{bmatrix}$$

Finally, the distance between (0, 0, 0) and the plane x + y + z = 12 is the length of this projection vector:

$$\left\| \begin{bmatrix} 4\\4\\4 \end{bmatrix} \right\| = \sqrt{4^2 + 4^2 + 4^2} = 4\sqrt{3} \qquad \blacksquare$$

Quiz #4. Friday, 10 October, 2008. [5 minutes]

1. Solve the following system of linear equations using Gauss-Jordan reduction. [5]

Solution. We set up the corresponding augmented matrix and throw elementary row operations at it ...

Hence the (only!) solution to the given system of linear equations is $x = y = w = \frac{1}{2}$ and $z = -\frac{1}{2}$.

Quiz #5. Friday, 17 October, 2008. [10 minutes]

1. Determine whether
$$\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$$
 is in Span $\left\{ \begin{bmatrix} 0\\1\\2\\0 \end{bmatrix}, \begin{bmatrix} 1\\2\\0\\4 \end{bmatrix} \right\}$ or not. [5]
Solution. $\begin{bmatrix} 1\\1\\1\\1\\1 \end{bmatrix}$ is in Span $\left\{ \begin{bmatrix} 0\\1\\2\\0\\1\\2 \end{bmatrix}, \begin{bmatrix} 1\\2\\0\\0\\4 \end{bmatrix}, \begin{bmatrix} -1\\0\\4\\4 \end{bmatrix} \right\}$ exactly when there are scalars $a, b, a = \begin{bmatrix} 0\\1\\2\\0\\1 \end{bmatrix} + b \begin{bmatrix} 1\\2\\0\\1\\2 \end{bmatrix} + b \begin{bmatrix} 1\\2\\0\\1\\2 \end{bmatrix} + c \begin{bmatrix} -1\\0\\4\\1 \end{bmatrix} = \begin{bmatrix} 1\\1\\1\\1\\1 \end{bmatrix}.$

We set up the corresponding system of equations in augmented matrix form and attempt to solve it:

$$\begin{bmatrix} 0 & 1 & -1 & | & 1 \\ 1 & 2 & 0 & | & 1 \\ 2 & 0 & 4 & | & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 2 & 0 & | & 1 \\ 0 & 1 & -1 & | & 1 \\ 2 & 0 & 4 & | & 1 \end{bmatrix}$$
$$\Longrightarrow \begin{bmatrix} 1 & 2 & 0 & | & 1 \\ 0 & 1 & -1 & | & 1 \\ 0 & -4 & 4 & | & -1 \end{bmatrix} \xrightarrow{R_1 - 2R_2} \begin{bmatrix} 1 & 0 & 2 & | & -1 \\ 0 & 1 & -1 & | & 1 \\ 0 & 0 & 0 & | & 3 \end{bmatrix}$$

At this point the Gauss-Jordan algorithm can take us no further. Observe that the last row corresponds to the equation 0a + 0b + 0c = 3, which is impossible to satisfy, so there are no solutions. It follows that $\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$ is not in Span $\left\{ \begin{bmatrix} 0\\1\\2\\0 \end{bmatrix}, \begin{bmatrix} 1\\2\\0\\4 \end{bmatrix}, \begin{bmatrix} -1\\0\\4\\4 \end{bmatrix} \right\}$.

Quiz #6. Friday, 31 October, 2008. [10 minutes]

1. Use the Gauss-Jordan method to find the inverse of $\begin{bmatrix} 3 & 1 & 2 \\ 2 & 3 & -1 \\ 1 & -1 & 2 \end{bmatrix}$. [5]

Solution. We set up the super-augmented matrix and go:

$$\begin{bmatrix} 3 & 1 & 2 & | 1 & 0 & 0 \\ 2 & 3 & -1 & | 0 & 1 & 0 \\ 1 & -1 & 2 & | 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{bmatrix} 1 & -1 & 2 & | 0 & 0 & 1 \\ 2 & 3 & -1 & | 0 & 1 & 0 \\ 3 & 1 & 2 & | 1 & 0 & 0 \end{bmatrix}$$
$$\Longrightarrow \begin{bmatrix} 1 & -1 & 2 & | 0 & 0 & 1 \\ 0 & 5 & -5 & | 0 & 1 & -2 \\ 0 & 4 & -4 & | 1 & 0 & -3 \end{bmatrix} \xrightarrow{\frac{1}{5}} \begin{bmatrix} 1 & -1 & 2 & | 0 & 0 & 1 \\ 0 & 1 & -1 & | 0 & \frac{1}{5} & -\frac{2}{5} \\ 0 & 4 & -4 & | 1 & 0 & -3 \end{bmatrix}$$
$$\Longrightarrow \begin{bmatrix} 1 & -1 & 2 & | 0 & 0 & 1 \\ 0 & 1 & -1 & | 0 & \frac{1}{5} & -\frac{2}{5} \\ 0 & 4 & -4 & | 1 & 0 & -3 \end{bmatrix}$$
$$\Longrightarrow \begin{bmatrix} 1 & -1 & 2 & | 0 & 0 & 1 \\ 0 & 1 & -1 & | 0 & \frac{1}{5} & -\frac{2}{5} \\ 0 & 0 & 0 & | 1 & -\frac{4}{5} & -\frac{7}{5} \end{bmatrix}$$

At this point it should be apparent that we cannot turn the left-hand matrix into the identity matrix. It follows that $\begin{bmatrix} 3 & 1 & 2 \\ 2 & 3 & -1 \\ 1 & -1 & 2 \end{bmatrix}$ has no inverse.

Quiz #7. Friday, 7 November, 2008. [10 minutes]

1. Suppose **A** is an $n \times n$ matrix which has an inverse, and suppose $\mathbf{a}_1, \mathbf{a}_2, \ldots, \mathbf{a}_n$ are the columns of **A**. What can you deduce about this collection of vectors? [5]

Solution. Recall from class (and the text) that there is a longish list of properties which are equivalent to a matrix having an inverse. A couple of these are relevant here:

A has an inverse \iff $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n$ are linearly independent \iff Span $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n\} = \mathbb{R}^n$

One can rephrase these a little, using the definitions of independence and span:

 \iff No column of **A** is a linear combination of the other columns of **A**.

 \iff Every vector $\mathbf{b} \in \mathbb{R}^n$ is a linear combination of the columns of \mathbf{A} .

One could also note another equivalent that is closely related:

 \iff The dimension of Span $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n\}$ is n.

Using the fact that the (transposes of the) columns of \mathbf{A} are the rows of \mathbf{A}^T , we can also make a similar statements about the rows of \mathbf{A}^T .

Quiz #8. Friday, 8 November, 2008. [5 minutes]

1. Determine whether $U = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid |x| = |y| \right\}$ is a subspace of \mathbb{R}^2 or not. [5]

Solution. U is not a subspace of \mathbb{R}^2 . While it is closed under multiplication by scalars, it is not closed under vector addition. For example, it is easy to see that $\begin{bmatrix} 1\\1 \end{bmatrix}$ and $\begin{bmatrix} -1\\1 \end{bmatrix}$ are in U, since |1| = 1 = |1| and |-1| = 1 = |1|. However,

$$\begin{bmatrix} 1\\1 \end{bmatrix} + \begin{bmatrix} -1\\1 \end{bmatrix} = \begin{bmatrix} 0\\2 \end{bmatrix},$$

which is not in U because $|0| = 0 \neq 2 = |2|$.

Quiz #9. Friday, 21 November, 2008. [10 minutes]

1. Find a spanning set for the subspace

$$S = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \middle| \begin{array}{rrrrr} x & + & 2y & = & 0 \\ & & 2y & + & z & = & 0 \\ - & x & + & 2y & + & 2z & = & 0 \end{array} \right\}$$

of \mathbb{R}^3 . [5]

Solution. We find the (parametric representation of the) set of solutions of the system of linear equations used to define S:

$$\begin{bmatrix} 1 & 2 & 0 & | & 0 \\ 0 & 2 & 1 & 0 \\ -1 & 2 & 2 & | & 0 \end{bmatrix} \implies \begin{bmatrix} 1 & 2 & 0 & | & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 4 & 2 & | & 0 \end{bmatrix}$$
$$\begin{bmatrix} R_1 - R_2 \\ \Rightarrow \\ R_3 - 2R_2 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 & | & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \implies \begin{bmatrix} 1 & 0 & -1 & | & 0 \\ 0 & 1 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

The last augmented matrix corresponds to equations x - z = 0 and $y + \frac{1}{2}z = 0$, which we can use to solve for x and y in terms of z: x = z and $y = -\frac{1}{2}z$. hence the vector-parametric representation of the set of solutions to the original system of equations is

$$\begin{bmatrix} x\\ y\\ z \end{bmatrix} = t \begin{bmatrix} 1\\ -\frac{1}{2}\\ 1 \end{bmatrix} ,$$

where $t \in \mathbb{R}$ is the parameter. It follows that $S = \text{Span} \left\{ \begin{bmatrix} 1 \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right\}$.

Quiz #10. Friday, 28 November, 2008. [12 minutes]

1. Determine the dimension of the subspace

$$S = \operatorname{Span}\left\{ \begin{bmatrix} 1\\0\\1\\0 \end{bmatrix}, \begin{bmatrix} 1\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} 1\\0\\0\\-1 \end{bmatrix}, \begin{bmatrix} 1\\0\\1\\0\\1 \end{bmatrix}, \begin{bmatrix} 0\\0\\1\\1 \end{bmatrix}, \begin{bmatrix} 0\\0\\1\\1 \end{bmatrix} \right\}$$

of \mathbb{R}^4 . [5]

Solution. There are several ways to do this. In this solution we will find a basis for S that is a subset of the given spanning set for S and then count how many vectors there are in this basis. To this end we assemble the given spanning set into the columns of a matrix and then row reduce this matrix as far as possible:

	Γ1	1	1	0	ך 0		Γ1	1	1	0	ך 0
	0	1	0	1	0	\implies	0	1	0	1	0
	1	0	0	0	1	$R_3 - R_1$	0	-1	-1	0	1
	Lo	0	-1	1	1		LO	0	-1	1	1
$R_1 - R_2$	Γ1	0	1	_1	ך 0		Γ1	0	1	-1	ך 0
\implies	0	1	0	1	0	\implies	0	1	0	1	0
$R_3 + R_2$	0	0	-1	1	1	$(-1)R_3$	0	0	1	-1	-1
	Lo	0	-1	1	1		Lo	0	-1	1	1
$R_1 - R_3$	Γ1	0	0	0	ך 1						
\implies	0	1	0	1	0						
	0	0	1 -	-1	-1						
$R_4 + R_3$	Lo	0	0	0	0]						

Note that there are three non-zero rows remaining in this matrix. These have leading non-zero entries in the first three columns; thus the first three vectors of the given spanning set,

(Γ1-		r 1 7		r 1 T		
J	0		1		0		
Ì	1	,	0	,	0	ĺ	,
l					-1	J	

will serve as a basis for S. It follows that the dimension of S is three. \blacksquare

Quiz #11. Friday, 5 December, 2008. [10 minutes]

1. Find the the eigenvalue(s) and all the eigenvectors of $\begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix}$. [5]

Solution. First, we find the eigenvalues.

$$\begin{vmatrix} 2 & -1 \\ 1 & 0 \end{vmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = \begin{vmatrix} 2-\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = (2-\lambda)(-\lambda) - (-1) \cdot 1 = \lambda^2 - 2\lambda + 1$$

It's pretty easy to see that $\lambda^2 - 2\lambda + 1 = (\lambda - 1)^2 = 0$ only when $\lambda = 1$, and so $\lambda = 1$ is the only eigenvalue of the given matrix.

Second, we find all the eigenvectors of the given matrix for the eigenvalue $\lambda = 1$; that is, we find all the solutions $\begin{bmatrix} x \\ y \end{bmatrix}$ of the equation

$$\left(\begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix} - 1 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad i.e. \quad \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

It's obvious that we are looking for all the solutions to the linear equation x - y = 0, *i.e.* x = y. If we let y equal the parameter t, it follows that x = t as well, and so the vector-parametric presentation of the set of solutions is $\begin{bmatrix} x \\ y \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, where $t \in \mathbb{R}$.